ENGINEERING STATICS An Online Approach

Jeffrey E. Jones, PE

| Prefix | Symbol | | | Multiplication Factor |
|--------|--------|-------------------|----|-----------------------|
| tera | Т | 10 ¹² | =1 | 000 000 000 000 |
| giga | G | 10 ⁹ | = | 1 000 000 000 |
| mega | М | 10 ⁶ | = | 1 000 000 |
| kilo | k | 10 ³ | = | 1 000 |
| hecto | h | 10 ² | = | 100 |
| deka | da | 10 ¹ | = | 10 |
| deci | d | 10 ⁻¹ | = | .1 |
| centi | С | 10 ⁻² | = | .01 |
| milli | m | 10 ⁻³ | Ξ | .001 |
| micro | μ | 10 ⁻⁶ | = | .000 001 |
| nano | n | 10 ⁻⁹ | = | .000 000 001 |
| pico | р | 10 ⁻¹² | = | .000 000 001 |

| Greek Alp | habet | | | | |
|-----------|-------|---------|-----|---|---------|
| А | α | Alpha | Ν | ν | Nu |
| В | β | Beta | [1] | w | Xi |
| Г | γ | Gamma | 0 | 0 | Omicron |
| Δ | δ | Delta | П | π | Pi |
| Е | 3 | Epsilon | Р | ρ | Rho |
| Z | ζ | Zeta | Σ | σ | Sigma |
| Н | η | Eta | Т | τ | Tau |
| Θ | θ | Theta | Y | υ | Upsilon |
| Ι | l | lota | Φ | φ | Phi |
| K | к | Kappa | Х | χ | Chi |
| Λ | λ | Lambda | Ψ | ψ | Psi |
| М | μ | Mu | Ω | ω | Omega |



STATICS- AN ONLINE APPROACH

Published by YourOtherTeacher.com, Inc., Copyright © 2005-2024 by YourOtherTeacher.com, Inc. All rights reserved. No part of this publication may be reproduced, displayed or distributed in any form or by any means, electronic or otherwise, without the prior written permission of YourOtherTeacher.com.

STUDENTS...

This is your YourOtherTeacher.com Statics Companion. Inside you'll find over 300 Statics example problems for use in class or for extra practice outside of class with YourOtherTeacher.com's corresponding online Canvas Statics course. You'll find problems solved by your online instructor, in a detailed, step-by-step, whiteboard video format. Watch only the lessons you want, when you want, and use this companion to follow along. It's easy, and it will help you pass your class.

INSTRUCTORS...

This is your static's companion, too. Use it in class as a source of example problems and save your students the time and energy of copying problem statements and figures off the board. Encourage your students to watch any of these problems solved...anytime they want. Think of YourOtherTeacher.com as your online TA, with unlimited office hours. Contact your YOT representative for free access at admin@yourotherteacher.com.

YOUR SCHEDULE + YOUL CHOICE X YOUR OTHER TEACHER. COM YOUR SUCCEPS!

Copyright 2005-2024 by YourOtherTeacher.com, Inc. ALL RIGHTS RESERVED

No part of this publication may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, recording or otherwise without the prior written permission of the publisher and the author.

Cover Photograph:

The Golden Gate Bridge in San Francisco, California.

How to use this book: This video companion contains the screen shots of the problems that are solved on a students Learning Management System such as Canvas or <u>www.YourOtherTeacher.com</u>. The solutions are not included here since it is the authors' belief that more can be learned from the words and gestures in a video than can ever be written. It is suggested that the students write the solutions down as presented in the videos since memory is greatly increased by the writing process.

Avoid looking for problems that are similar to your homework. This would be very short sighted. It is better to understand the concepts than to get the solution for one problem. If you understand the concepts then you can solve any problem that may appear on a test or a problem you may encounter in industry. The saying "Give a man a fish, he eats for a day, teach him how to fish, he eats for a lifetime" is the motto for YourOtherTeacher.com.



Jeff Jones holds a bachelor's and master's degree in civil engineering from San Jose State University in San Jose, CA. His concentration was in structural engineering and applied mechanics. He is also the author of Strength of Materials- An Online Approach, Engineering Drawing- An Online Approach, as well as many others. He has personally recorded over 300 hours of video on the website www.YourOtherTeacher.com which helps 1000's of students every year towards their goal of becoming an engineer. After graduation, Jones was a senior structural engineer at Bechtel Corporation for 10 years where he became a registered professional engineer in California. Since then, he has served in various roles as a Professor, Department Chair, lead instructor, author, chairman and executive with 40+ years of proven experience. Jeff Jones is the recipient of the

prestigious "Community College Teacher of the Year" award, Awarded by the American Society of Engineering Educators (ASEE-PSW). He was also awarded Cuesta College's highest honor "Teaching Excellence Award".

Contents

1-INTRODUCTION

What is Mechanics?1-1Fundamental Concepts and Principles1-2Numerical Accuracy1-3

2- STATICS OF PARTICLES

Introduction 2-1

Forces in a Plane

| Vectors | 2-2 | | |
|----------------------|------------------------|----------------|------|
| Addition of Vectors | 2-2 | | |
| Resultant of Severa | I Concurrent Forces | 2-6 | |
| Resolution of a Ford | ce into Components | 2-7 | |
| Rectangular Compo | onents of a Force: Uni | t Vectors 2-11 | |
| Addition of Forces b | by Summing X and Y | Components | 2-13 |
| Equilibrium of a Par | ticle 2-17 | | |

Forces in Space

Rectangular Components of a Force in Space2-27Force Defined by Its Magnitude and Two Points on Its Line of Action2-31Equilibrium of Particle in Space2-37

Summary 2-45

3- RIGID BODIES: EQUIVALENT SYSTEMS OF FORCES

| Introduction 3-1 | | | |
|---|-----------------|--------|------|
| Moment of a Force about a Point in 2D | 3-2 | | |
| Rectangular Components of the Momer | nt of a Force | 3-10 | |
| Vector Product of Two Vectors | 3-17 | | |
| Moment of a Force about a Point | 3-20 | | |
| Scalar Product of Two Vectors | 3-26 | | |
| Mixed Triple Product of Three Vectors | 3-33 | | |
| Moment of a Couple 3-43 | | | |
| Resolution of a Given Force into a Forc | e at O and a Co | ouple | 3-48 |
| Reduction of a System of Forces to One | e Force and a C | Couple | 3-52 |
| Equivalent System of Forces | 3-56 | | |
| Further Reduction of a System of Force | S | 3-57 | |
| Reduction of a System of Forces to a W | /rench | 3-63 | |

4- EQUILIBRIUM OF RIGID BODIES

Introduction 4-1

Equilibrium in Two Dimension

| Reactions at support and Connections | for a Two-Dimensional Structure | 4-2 |
|--------------------------------------|---------------------------------|-----|
| Sample Free-Body Diagrams | 4-3 | |
| Constraints and Statical Determinacy | 4-6 | |
| Equilibrium of a Two-Force Body | 4-21 | |
| Equilibrium of a Three-Force Body | 4-22 | |
| | | |

Equilibrium in Three Dimensions

| Equilibrium of a | a Rigid Body in Three Dimensions 4-28 | |
|------------------|--|------|
| General Approa | ach for Solving Three Dimensional Problems | 4-29 |
| Symmetry | 4-31 | |
| | | |
| Summary | 4-41 | |

5- DISTRIBUTED FORCES: CENTROIDS AND CENTERS OF GRAVITY

Introduction 5-1

Areas and Lines

| Center of Gravity of a Two-Dimensional Composite Plates and Wires First Moment of Areas and Lines | Body 5-4 5-5 | 5-3 |
|---|--------------------|------|
| Centroids of Areas 5-6 | | |
| Centroids of Lines 5-13 | | |
| Determination of Centroids by Integration | n | 5-18 |
| Theorems of Pappus-Guldinus | 5-32 | |
| Distributed Loads on Beams | 5-39 | |
| Forces on Submerged Surfaces | 5-44 | |
| Volumes | | |
| Center of Gravity of a Three-Dimensional Centroid of a Volume 5-52 | al Body | 5-52 |
| Centroids of Volumes- Composite Bodie | es | 5-53 |
| | | |

Summary 5-57

6- ANALYSIS OF STRUCTURES

Introduction 6-1

Trusses

Plane Trusses6-2Method of Joints6-4Joints Under Special Loading Conditions- Tricks6-4Method of Sections6-20

Frames and Machines

Analysis of a Frame 6-29 Machines 6-29

Summary 6-41

7- FORCES IN BEAMS

| Introduction | 7-1 | |
|--------------------|---------|-----|
| Internal Forces in | Members | 7-1 |

Beams

| Shear and Bending Moment-Diagrams 7-3 | |
|---|-----|
| Relations among Load, Shear, and Bending Moment | 7-8 |

Summary 7-21

8- FRICTION

| Introduction | 8-1 | | |
|--------------------|--------|------|------|
| States of Friction | | 8-2 | |
| Angles of Friction | | 8-16 | |
| Wedges | 8-17 | | |
| Square-Threaded | Screws | | 8-25 |
| Belt Friction | 8-40 | | |

Summary

9- DISTRIBUTED FORCES: MOMENTS OF INERTIA

Introduction9-1Second Moment, or Moment of Inertia, of an Area9-1Determination of the Moment of Inertia of an Area by Integration9-1Polar Moment of Inertia9-9Parallel-Axis Theorem9-11Moments of Inertia of Composite Areas9-12

Chapter 1 Introduction

What is Mechanics?

That science which describes and predicts the conditions of rest or motion of bodies under the action of forces:

-Mechanics of Rigid Bodies

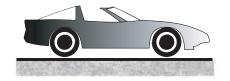
-Mechanics of Deformable Bodies

-Mechanics of Fluids

Fundamental Concepts and Principles

-The Parallelogram Law for the addition of forces:

-The principle of Transmissibility:



-Newton's First Law:

-Newton's Second Law:

-Newton's Third Law:

-Newton's Law of Gravitation:

Numerical Accuracy

Numerical accuracy depends on: -accuracy of the given data

-the accuracy of the computations

Example:

I want to measure the area of my house and I'm so cheap I can't afford a tape measure. But my foot is approximately 1 foot (no pun intended) long. So I measure the length and width of the house accordingly (47.5 by 26.5 foot lengths). Find the area.

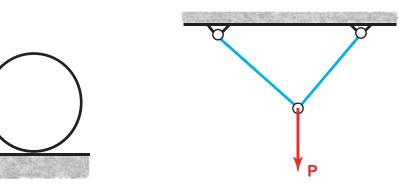
Trial and Error Solutions

Find x given: $0=73.6 - 100\sin(x) - 45\cos(x)$

Chapter 2 Statics of Particles

Introduction

Particles- when all of the forces converge at a common point:



Bodies- when all of the forces do not converge on a common point:



Goals

-Replace two or more forces acting on a given particle by a single force having the same effect as the original (2D and 3D).

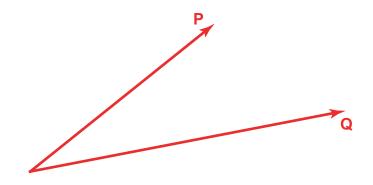
-Equilibrium (Newton's First Law) for 2D and 3D.

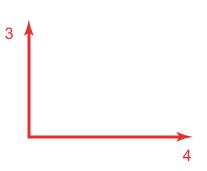
Vectors

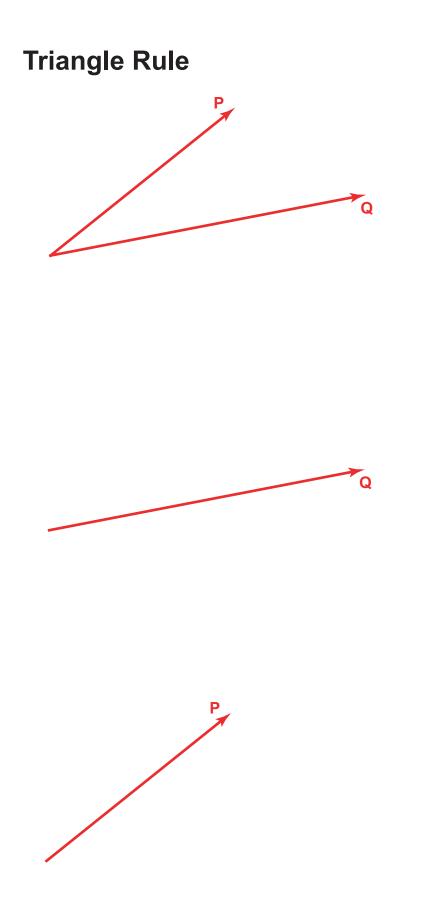


Addition of Vectors

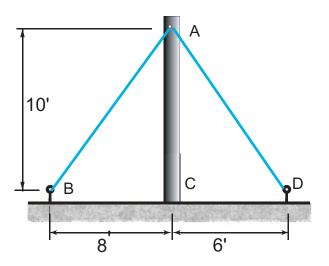
Parallelogram Law



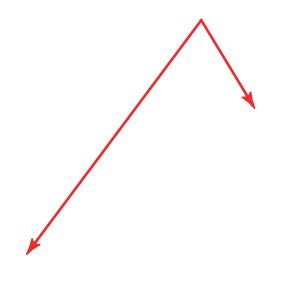




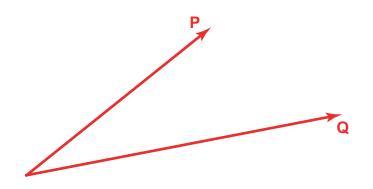
The cable stays AB and AD help support pole AC. Knowing that the tension is 120 lb in AB and 40 lb in AD, determine graphically the magnitude and direction of the resultant of the forces exerted by the stays at A using (a) the parallelogram law, (b) the triangle rule. Units: Lb.



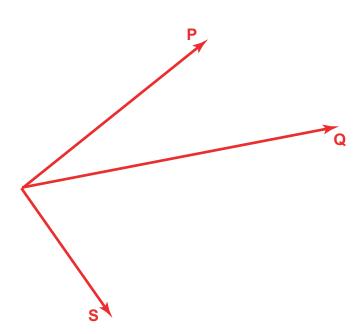
SCALE 1"= 40 lb



Subtraction



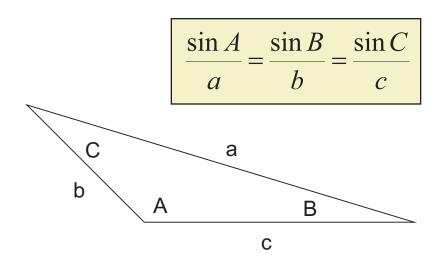
Sum of three or more vectors (Polygon Rule)



Resultant of Several Concurrent Forces

Law of Sines

In any triangle, the sides are proportional to the sines of the opposite angles, i.e.,

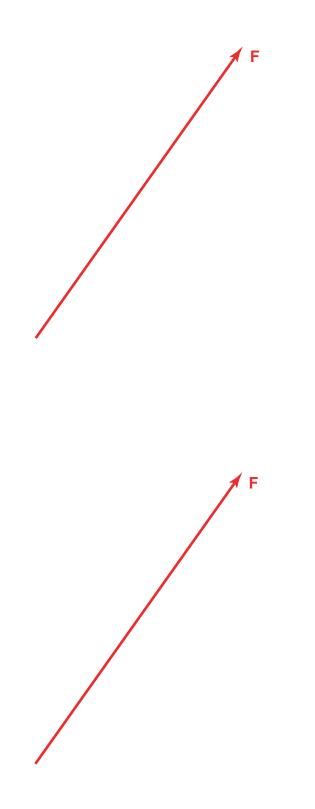


Law of Cosines

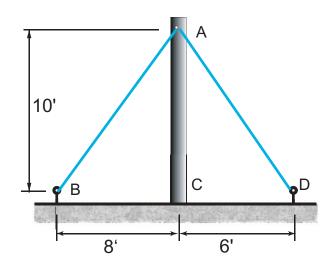
In any triangle ABC, the square of any side is equal to the sum of the squares of the other two sides diminished by twice the product of these sides and the cosine of their included angle, i.e.,

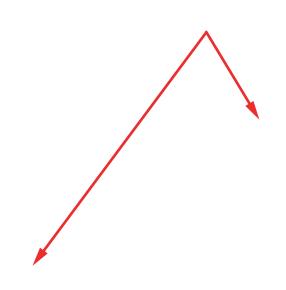
$$a2 = b2 + c2 - 2bc \cos A$$
$$b2 = a2 + c2 - 2ac \cos B$$
$$c2 = a2 + b2 - 2ab \cos C$$

Resolution of a Force into Components

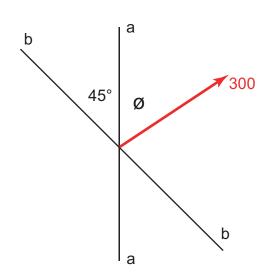


The cable stays AB and AD help support pole AC. Knowing that the tension is 120 lb in AB and 40 lb in AD, determine using trigonometry the magnitude and direction of the resultant of the forces exerted by the stays at A. Units: Lb, ft.

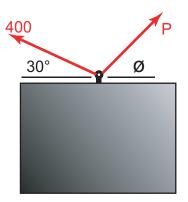




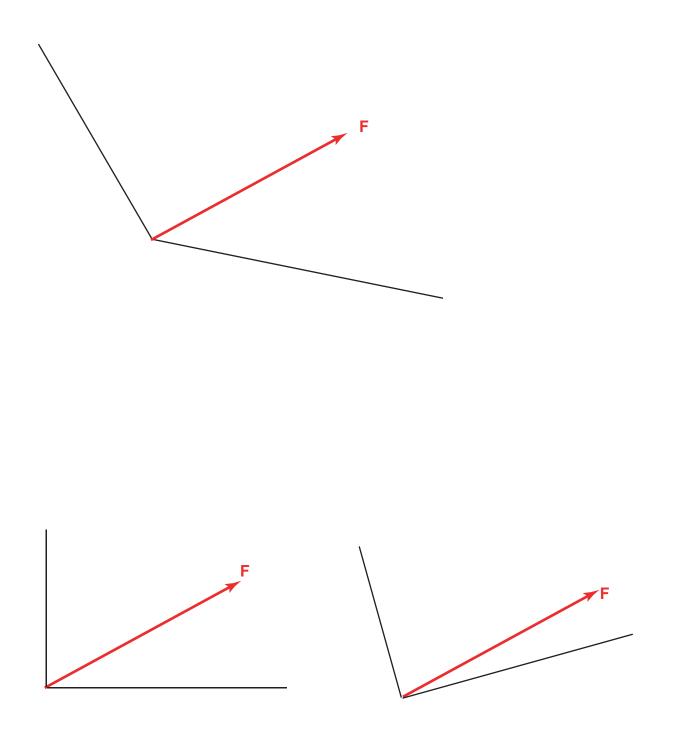
The 300 N force is to be resolved into two components along a-a and b-b. (a) Determine by trigonometry the angle ø, knowing that the component along line a-a is to be 150-N. (b) What is the corresponding value of the component along b-b? Units: N.



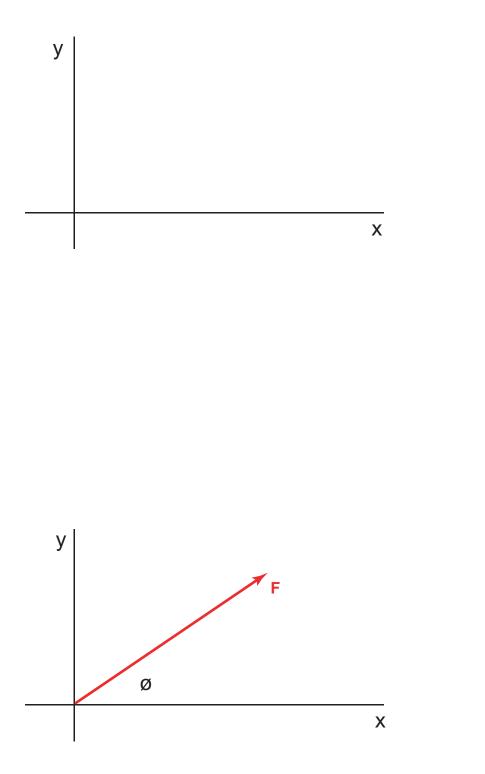
A steel plate is to be lifted straight up. Determine by trigonometry (a) the magnitude and direction of the smallest force P for which the resultant R of the two forces applied at the eye hook is vertical, (b) the corresponding magnitude of R. Units: Lb.



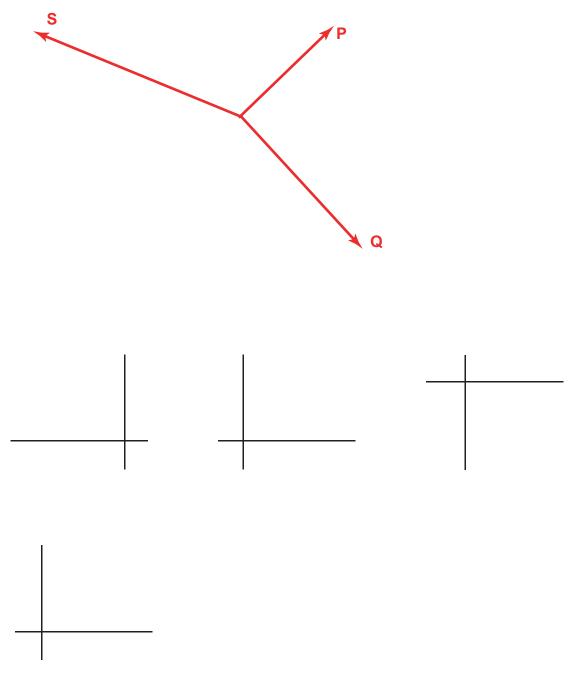
Rectangular Components of a Force. Unit Vectors



Unit Vectors



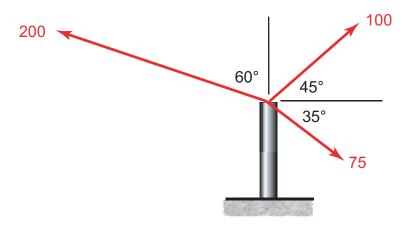
Addition of Forces by Summing X and Y Components



In Summary

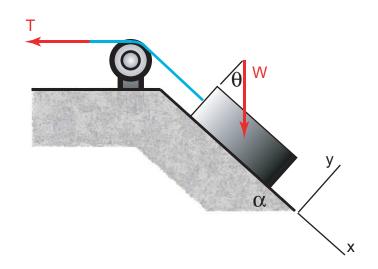
The scalar components of Rx and Ry of the resultant R of several forces acting on a particle are obtained by adding algebraically the corresponding scalar components of the given forces.

(a)Determine the x and y components of each of the forces shown on the stake. (b) Find the magnitude and direction of the resultant. Units: Lb.

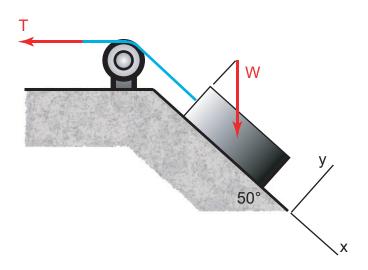


| Magnitude | x component | y component |
|-----------|-------------|-------------|
| 100 lb | | |
| 75 lb | | |
| 200 lb | | |

Example Prove that $\alpha = \theta$.



Example Find the x and y components of T and W. Units: N.

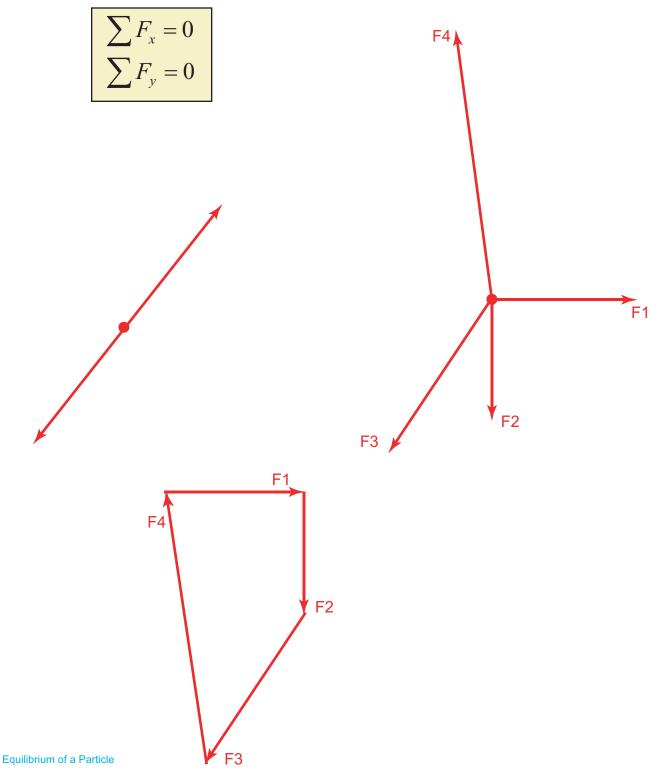


| Magnitude | x component | y component |
|-----------|-------------|-------------|
| | | |
| | | |
| | | |

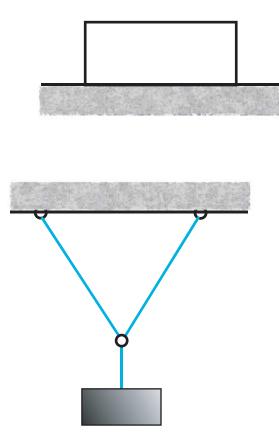
Equilibrium of a Particle

Newton's First Law

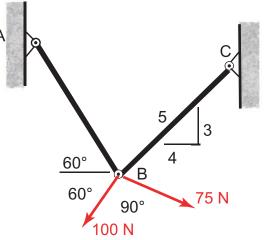
If the resultant force acting on a particle is zero, the particle will remain at rest (if originally at rest) or will move with constant speed in a straight line (if originally in motion).



Free-Body Diagram (FBD)

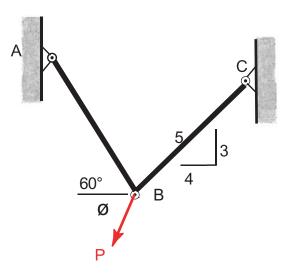


The loads are supported by two rods AB and BC as shown. Find the tension in each rod. Units: N.

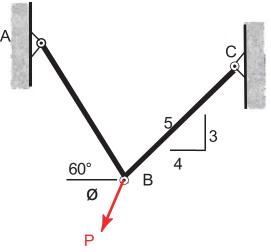


| | | 1 |
|-----------|-------------|-------------|
| Magnitude | x component | y component |
| 100 N | | |
| 75 N | | |
| | | |
| | | |
| | | |

It is known that the maximum allowable tension is 1200 N in rod AB and 600 N in BC. Determine (a) the maximum force P that may be applied at B, (b) the corresponding value of ø. Use the closed polygon method to solve. Units: N.

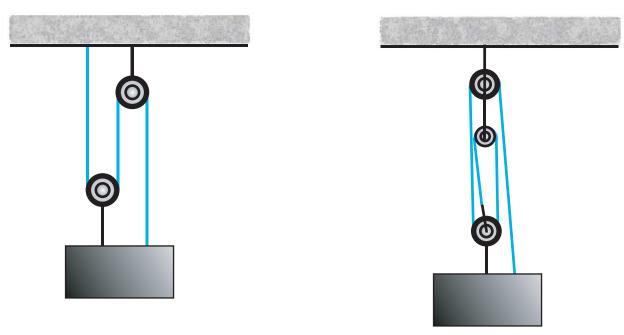


It is known that the maximum allowable tension is 1200 N in rod AB and 600 N in BC. Determine (a) the maximum force P that may be applied at B, (b) the corresponding value of ø. Use the component method to solve. Units: N.

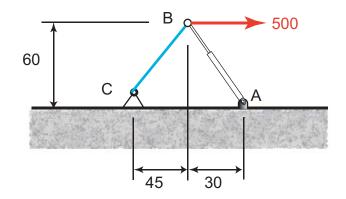


| Magnitude | x component | y component | |
|-----------|-------------|-------------|--|
| | | | |
| | | | |
| | | | |

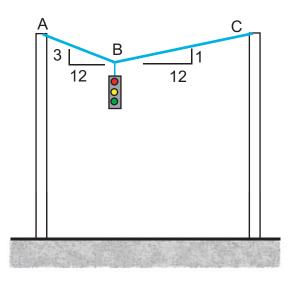
Find the tension in the rope. Assume that all cables are vertical. Note: The tension is the same through-out a continuous cable. This will be proven in another chapter.



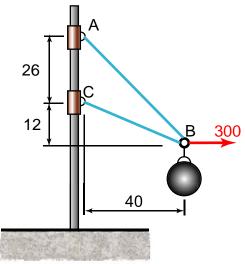
Determine the forces in AB and BC. Units: Lb, in.



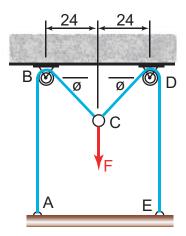
Determine the forces in cables AB and BC due to the 25 lb traffic light. Units: Lb.



Determine the forces in wires AB and BC. The sphere weighs 100 lbs. Units: Lb, in.

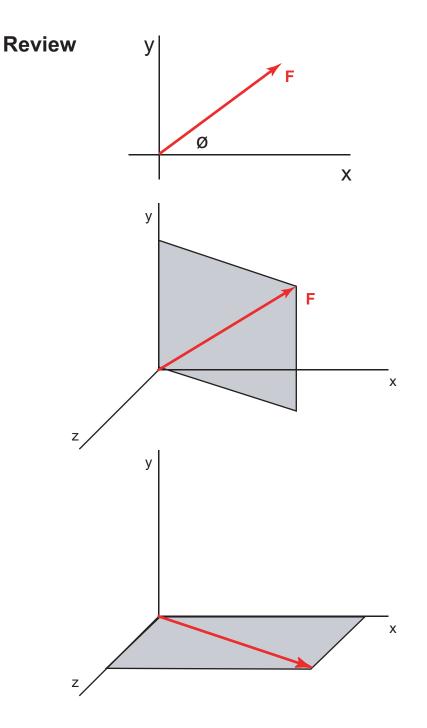


Determine the force F required to lift the 200 lb log when $\emptyset = 30^{\circ}$. Units: Lb, in.

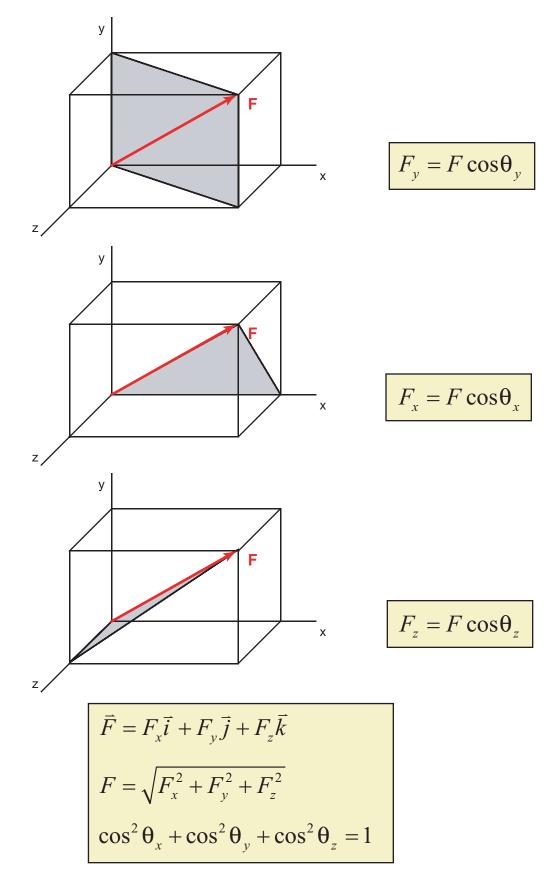


FORCES IN SPACE

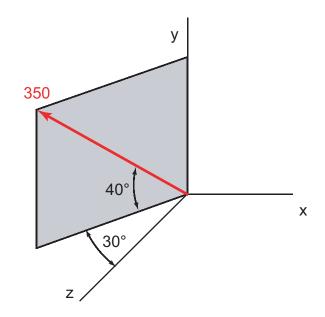
Rectangular Components of a Force in Space



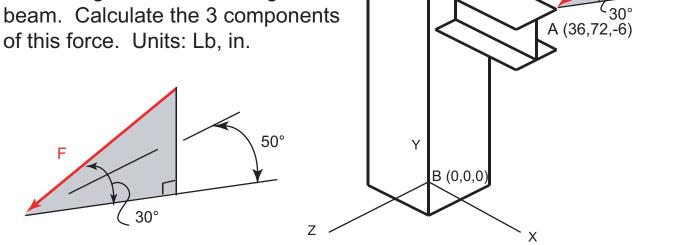
3D Vector Format



Determine (a) the x, y, and z components of the 350-N force, (b) the angles theta x, y, and z that the force forms with the coordinate axes.

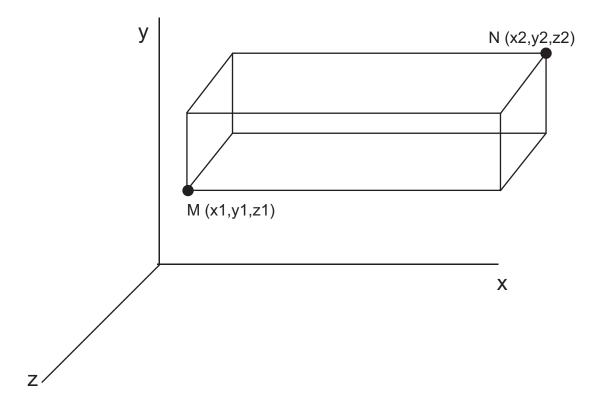


A 300 lb force is applied to point A on the edge of the wide flange beam. Calculate the 3 components



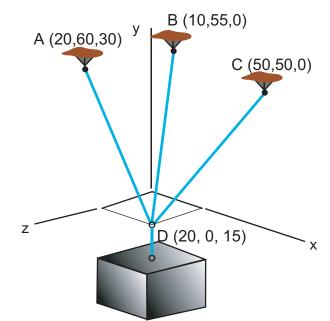
50°،

Force Defined by its Magnitude and Two Points on its Line of Action

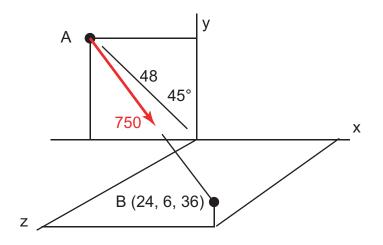


$$\vec{F} = \frac{F}{d} \left(d_x \vec{i} + d_y \vec{j} + d_z \vec{k} \right)$$
$$F_x = F \frac{d_x}{d} \qquad F_y = F \frac{d_y}{d} \qquad F_z = F \frac{d_z}{d}$$

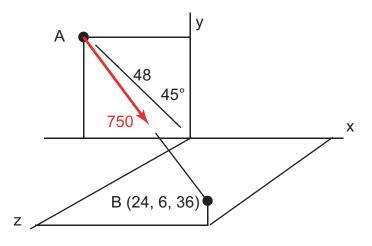
The crate is supported by 3 cables tied to the ring at D. Find the components of each on the ring in terms of their magnitude. Units: in.

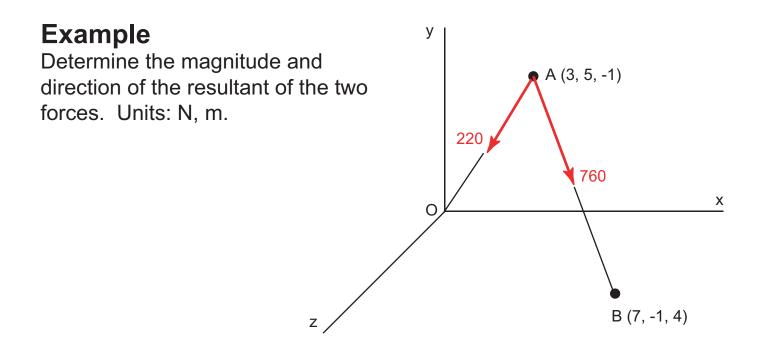


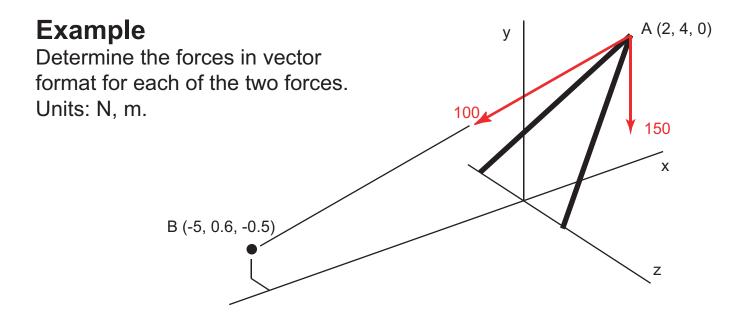
Find the 750 lb force in vector format, then determine the directional angles. Point A is in the xy-plane. Units: Lb, in.



Part 2: Find the 750 lb force in vector format, then determine the direction angles. Point A is in the xy-plane. Units: Lb, in.







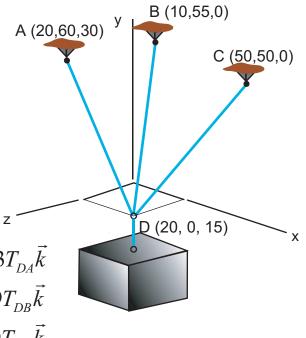
Equilibrium of a Particle in Space

$$\sum F_{x} = 0$$
$$\sum F_{y} = 0$$
$$\sum F_{z} = 0$$

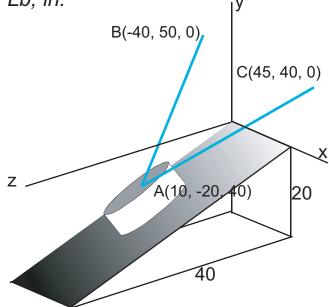
The crate is supported by 3 cables tied to the ring at D. Find the tension in each cable and the weight of the crate knowing that the tension in cable DC is 200 lb. Units: Lb, in.

From a previous solution,

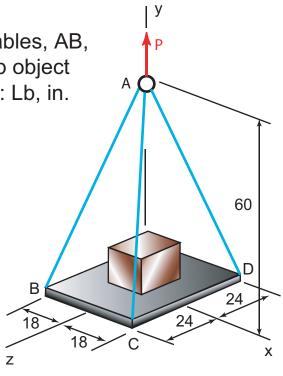
| $\vec{T}_{DA} =$ | $0\vec{i}$ | $+0.971T_{DA}\vec{j}$ | $+0.243T_{DA}\vec{k}$ |
|------------------------|-----------------------|-----------------------|-----------------------|
| $\vec{T}_{DB} = \cdot$ | $-0.173T_{DB}\vec{i}$ | $+0.950T_{DB}\vec{j}$ | $-0.259T_{DB}\vec{k}$ |
| $\vec{T}_{DC} =$ | $0.498T_{DC}\vec{i}$ | $+0.830T_{DC}\vec{j}$ | $-0.249T_{DC}\vec{k}$ |
| $\vec{W} =$ | $0\vec{i}$ | $-W \vec{j}$ | $+0\vec{k}$ |



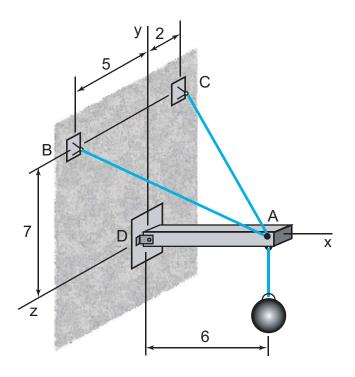
Using two ropes and a roller chute, two workers are unloading a 200 lb cylinder from a truck. Assuming that no friction exists between the cylinder and the chute, determine the tension in each rope. (*Hint: Since there is no friction the force exerted by the chute on the cylinder must be perpendicular to the chute). Units: Lb, in.*



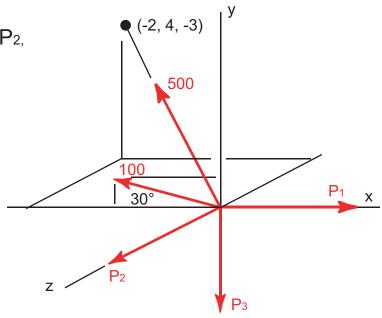
Determine the force in each of the three cables, AB, AC, and AD needed to support the 2200 lb object located in the center of the platform. Units: Lb, in.



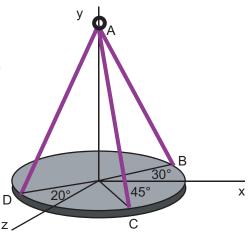
If the resultant force of AB, AC, and the weight is directed along AD, determine the forces in AB and AC due to the 150 lb sphere. Units: Lb, ft.



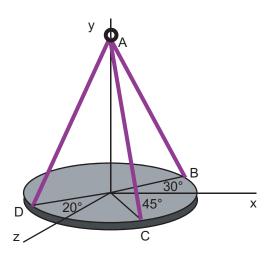
Determine the magnitude of P_1 , P_2 , and P_3 to maintain equilibrium. Units: Lb, ft.



The plate is supported by three wires. Each wire forms a 25° angle with the vertical. If the force in AD is 600 lb, determine the 3 components acting at point D. Also find the directional cosines. Units: Lb.



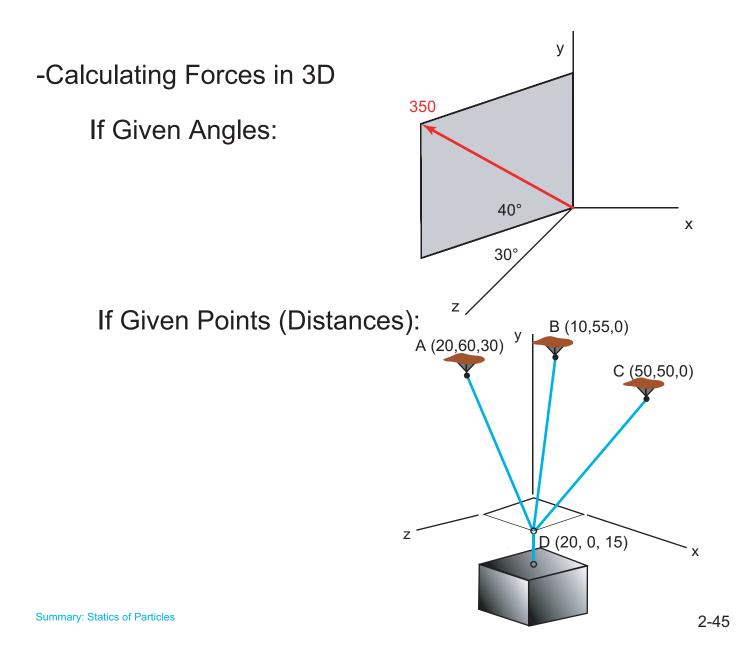
The plate is supported by three wires. Each wire forms a 25° angle with the vertical. If the x component of AB is 150 lbs, determine the force in AB. Also find the directional cosines. Units: Lb.



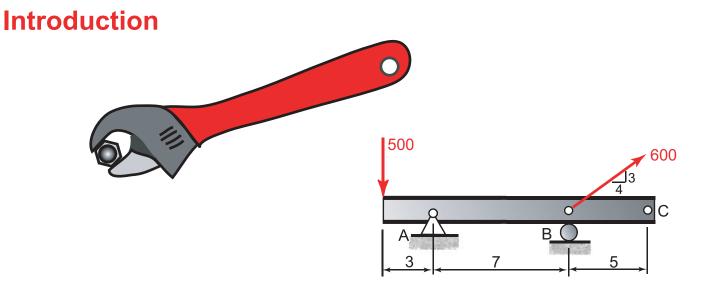


-Drawing FBDs

-Equilibrium



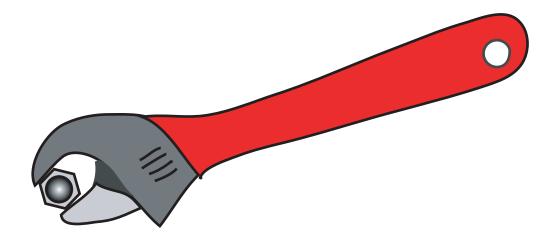
Chapter 3 Rigid Bodies: Equivalent Systems of Forces



Goals:

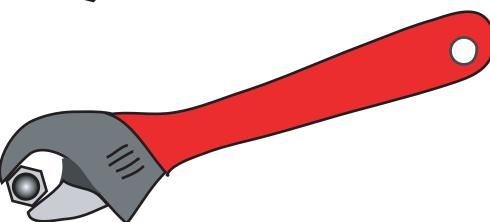
- -moments and couples
- -priniciple of transmissibility
- -replace a given system of forces by an equivalent system
- -vector products and scalar products

Moment of a Force about a Point in 2D



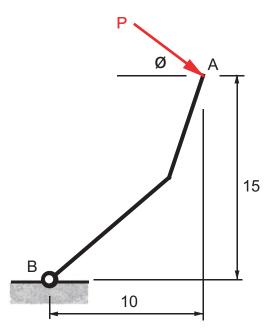
Sign Convention





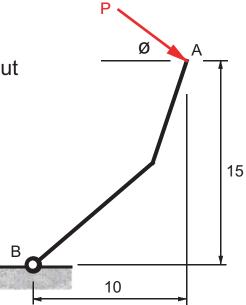
Determine the smallest force P that will create a 200 lb-in clockwise moment about B. Units: Lb, in.

Solution #1:

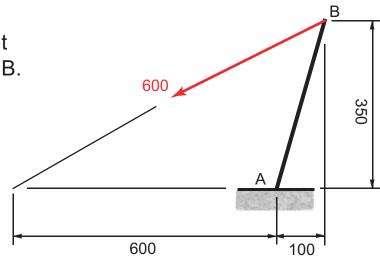


Determine the smallest force P that will create a 200 lb-in clockwise moment about B. Units: Lb, in.

Solution #2:



Calculate the moment about point A due to the 600 N force at point B. Units: N, mm.

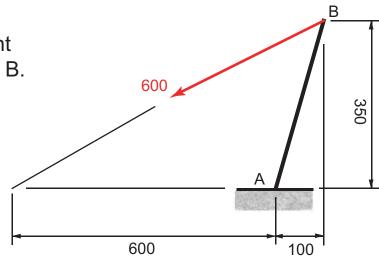


Solution #1:

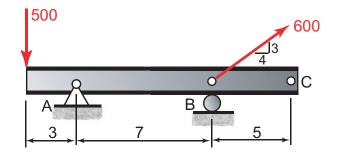
Solution #2:

Calculate the moment about point A due to the 600 N force at point B. Units: N, mm.

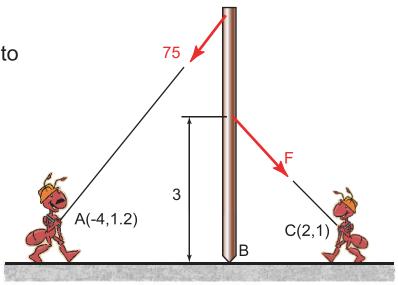
Solution #3:



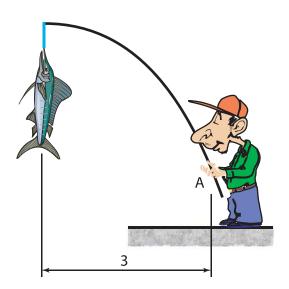
Find the moment of the two forces about point C on the beam. Units: N, m.



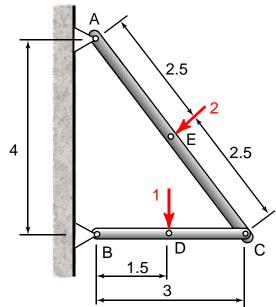
Determine the force F required to prevent the 5 meter pole from tipping. Units: N, m.

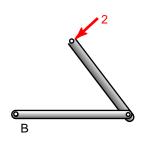


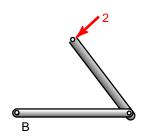
Determine the moment about point A created by the 100 kg fish. Units: N, m.



Determine the moment of the load at E about a) A, b) B. Units: Kips, ft.

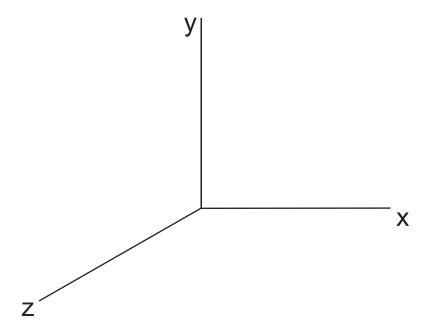






Rectangular Components of the Moment of a Force

Sign Convention for Moments in 3D

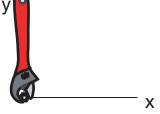




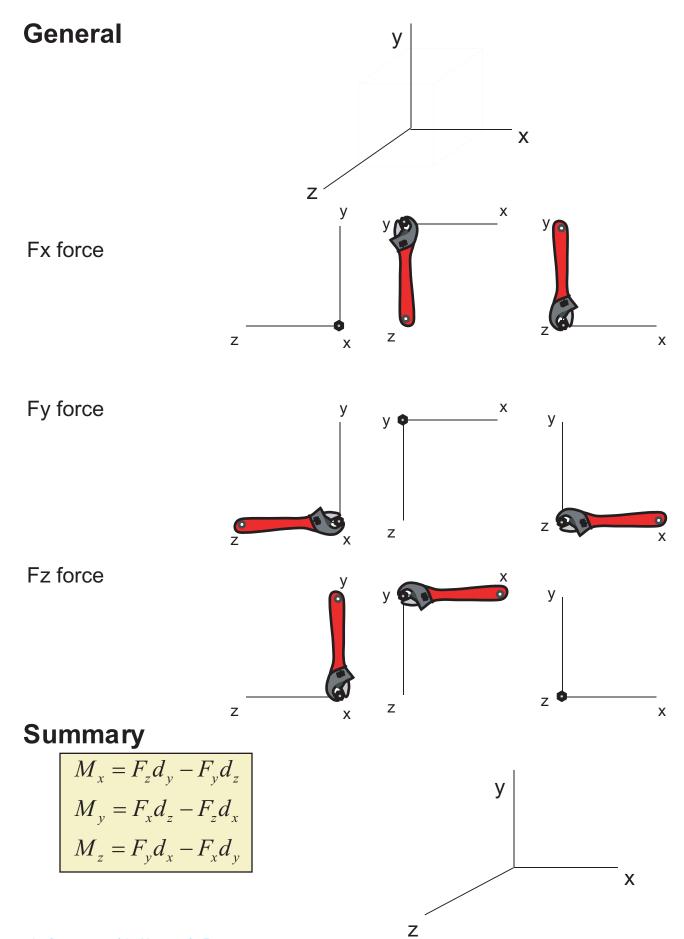
Review

Fy force

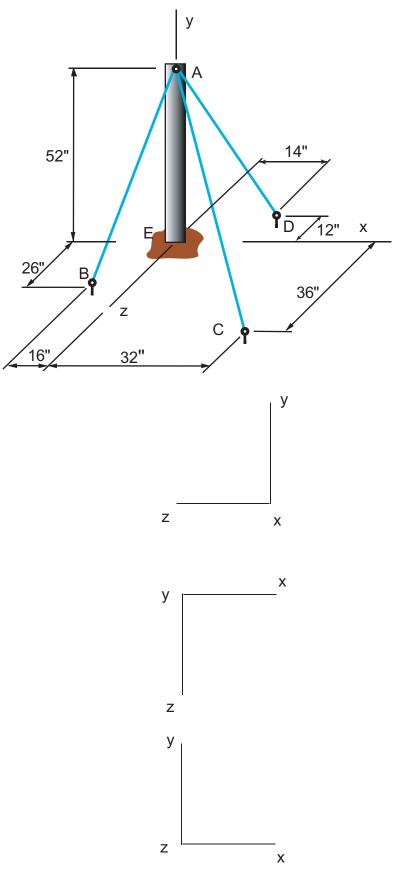
y y



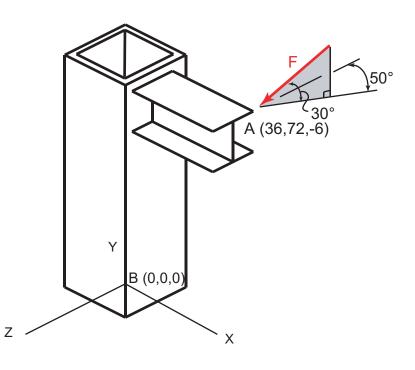
Fx force

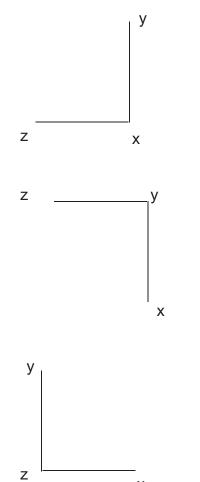


The tension force in wire AB is 600 lb. Calculate the moment at E due to this force. Units: Lb, in.



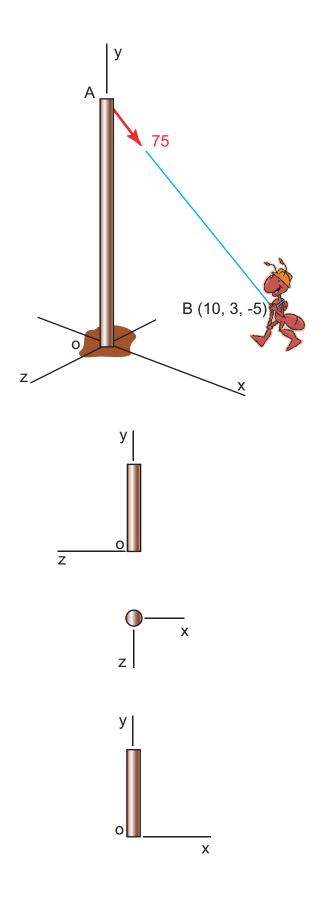
A 300 lb force is applied to point A on the edge of the wide flange beam. Calculate the moment at B due to this force. Units: Lb, in.



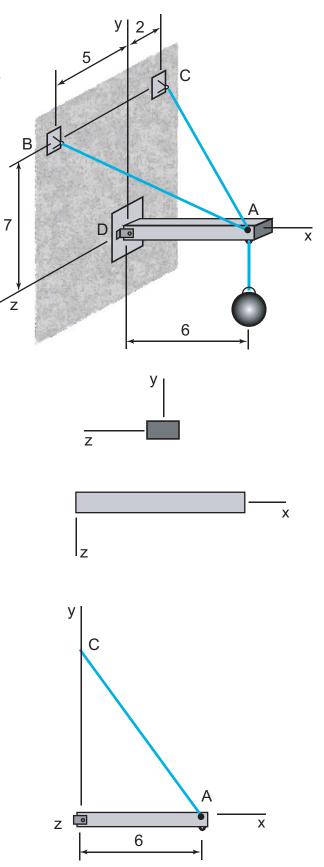


Х

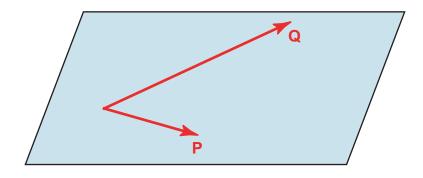
Find the moment about point O due to the 75 lb force applied at the top of the 25 ft pole. Units: Lb, ft.



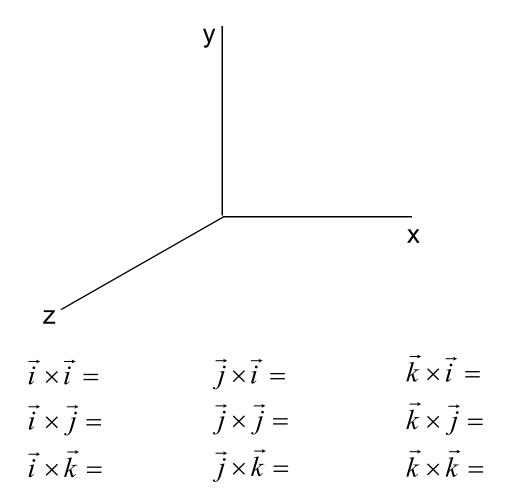
Determine the moment about D due to the force in wire AB if the force in AB is 64.2 lb. Units: Lb, ft.



Vector Product of Two Vectors



Vector Product of Two Vectors- continued



$$\vec{V} = \vec{P} \times \vec{Q} = (P_x \vec{i} + P_y \vec{j} + P_z \vec{k}) \times (Q_x \vec{i} + Q_y \vec{j} + Q_z \vec{k})$$

= $(P_x \vec{i}) \times (Q_x \vec{i}) + (P_x \vec{i}) \times (Q_y \vec{j}) + (P_x \vec{i}) \times (Q_z \vec{k})$
+ $(P_y \vec{j}) \times (Q_x \vec{i}) + (P_y \vec{j}) \times (Q_y \vec{j}) + (P_y \vec{j}) \times (Q_z \vec{k})$
+ $(P_z \vec{k}) \times (Q_x \vec{i}) + (P_z \vec{k}) \times (Q_y \vec{j}) + (P_z \vec{k}) \times (Q_z \vec{k})$

$$\vec{V} = (P_y Q_z - P_z Q_y)\vec{i} + (P_z Q_x - P_x Q_z)\vec{j} + (P_x Q_y - P_y Q_x)\vec{k}$$

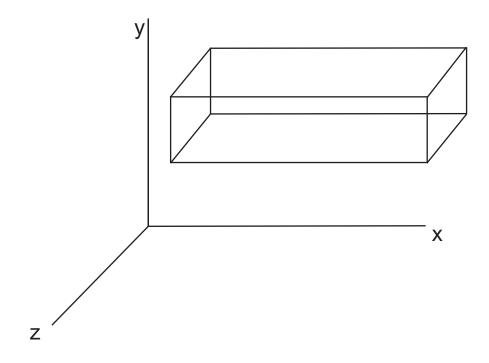
Vectors- continued

$$\vec{V} = \vec{P} \times \vec{Q} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix}$$

$$\vec{V} = (P_y Q_z - P_z Q_y)\vec{i} + (P_z Q_x - P_x Q_z)\vec{j} + (P_x Q_y - P_y Q_x)\vec{k}$$

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix} \qquad \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix} \qquad \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix} \qquad \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix}$$

Moment of a Force about a Point

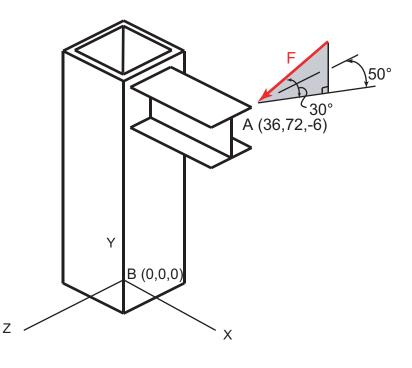


Definition of a Position Vector:

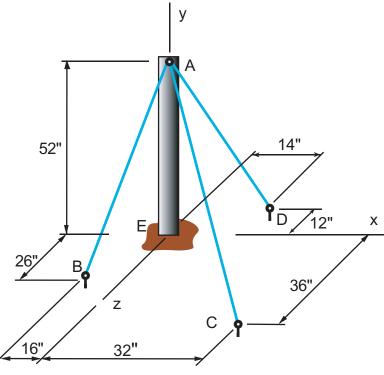
The position vector always starts at the point you want to find the moment about and ends anywhere along the axis of the force.

$$\vec{M} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

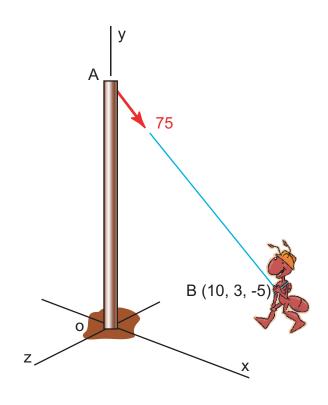
A 300 lb force is applied to point A on the edge of the wide flange beam. Calculate the moment at B due to this force. Use vector products to solve. Units: Lb, in.



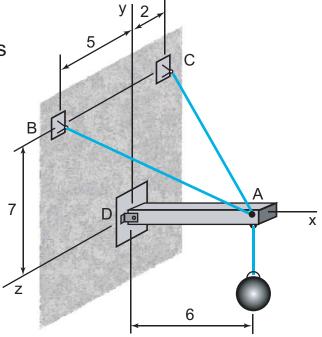
The tension force in wire AB is 600 lb. Calculate the moment at E due to this force. Units: Lb, in.



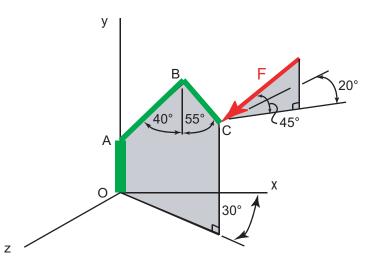
Find the moment about point O due to the 75 lb force applied at the top of the 25 ft pole. Units: Lb, ft.



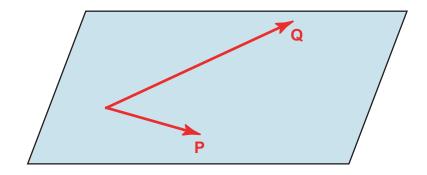
Determine the moment about D due to the force in wire AB if the force in AB is 64.2 lb. Units: Lb, ft.



Determine the moment about point O if AO= 150, AB= 400, BC= 300, and F= 5.5 N. Points OABC are in one plane. Units: N, mm.



Scalar Product of Two Vectors

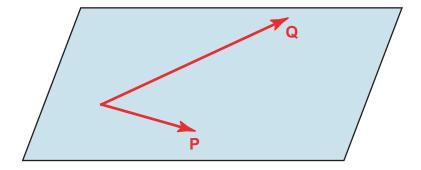


$$\vec{i} \cdot \vec{i} = \qquad \vec{j} \cdot \vec{i} = \qquad \vec{k} \cdot \vec{i} =$$
$$\vec{i} \cdot \vec{j} = \qquad \vec{j} \cdot \vec{j} = \qquad \vec{k} \cdot \vec{j} =$$
$$\vec{i} \cdot \vec{k} = \qquad \vec{j} \cdot \vec{k} = \qquad \vec{k} \cdot \vec{k} =$$

$$\vec{P} \cdot \vec{Q} = P_x Q_x + P_y Q_y + P_z Q_z$$

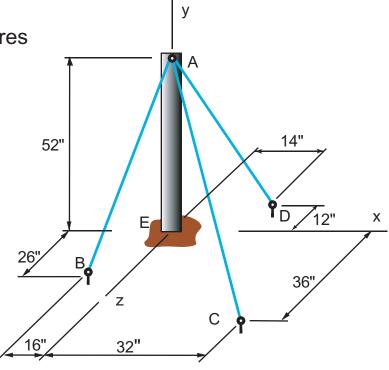
Angle Formed by Two Given Vectors

 $\vec{P} = P_x \vec{i} + P_y \vec{j} + P_z \vec{k}$ $\vec{Q} = Q_x \vec{i} + Q_y \vec{j} + Q_z \vec{k}$

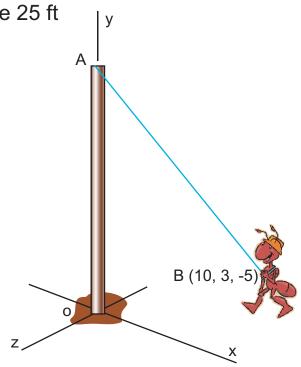


$$\cos\theta = \frac{P_x Q_x + P_y Q_y + P_z Q_z}{PQ}$$

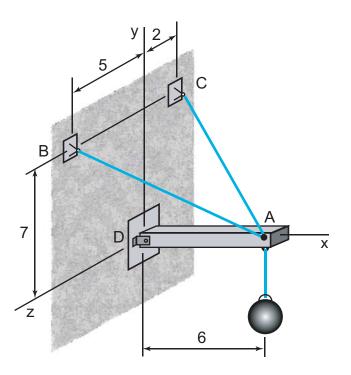
Determine the angle between wires AB and AC. Units: In.



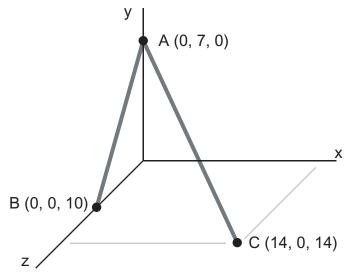
Determine the angle between AB and the 25 ft pole. Units: ft.



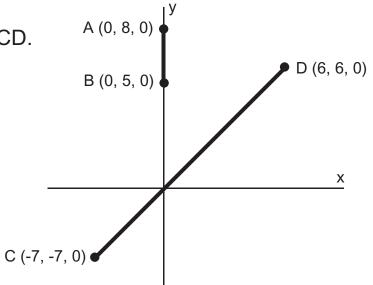
Determine the angle between AB and AC. Units: Lb, ft.



Find the angle between AB and AC. Units: Ft.

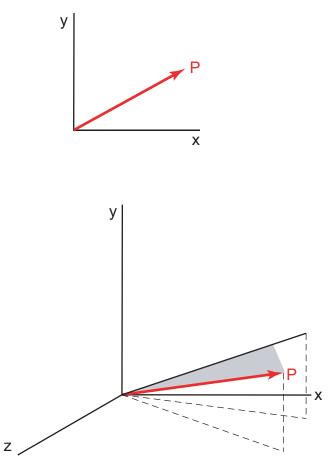


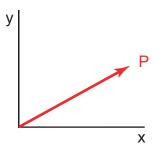
Find the angle between AB and CD. Units: Ft.



Mixed Triple Product of Three Vectors Projection of a Vector on a Given Axis

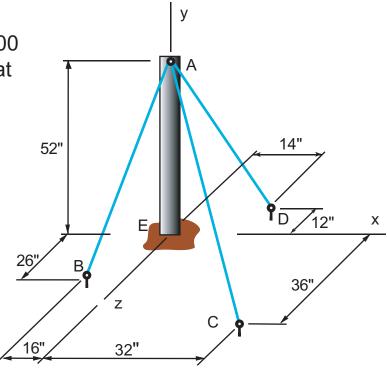
Review



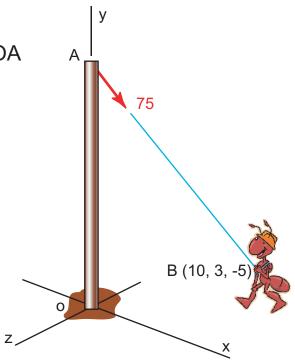


| $P_{OL} = \vec{P} \cdot \vec{\lambda}_{OL}$ |
|---|
|---|

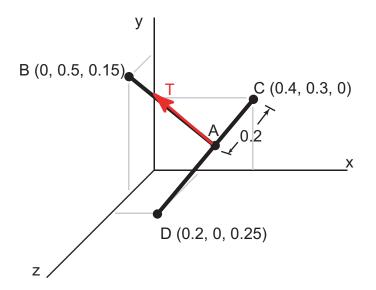
The tension force in wire AB is 600 lb. Calculate the projection of that force on AC. Units: Lb, in.



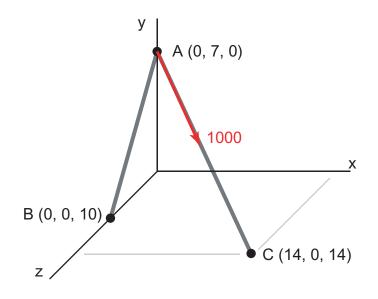
Determine the component of F onto the OA axis of the 25 m pole. Units: N, m.



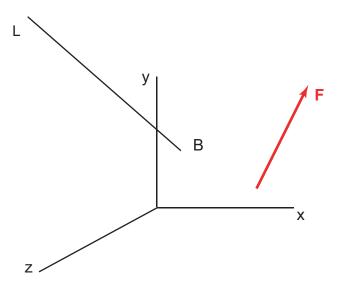
Find the component (projection) of the 50 N force along AB onto CD. Units: N, m.



Find the component (projection) of the 1000 lb force onto AB. Units: Lb, in.



Moment of a Force about a Given Axis



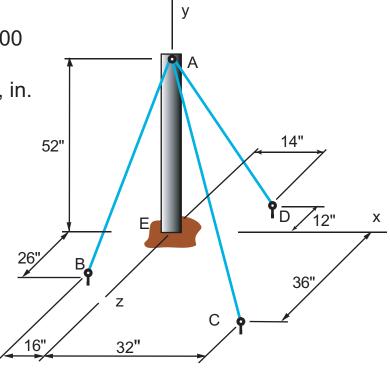
Recall,

$$\vec{M} = \vec{r} \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

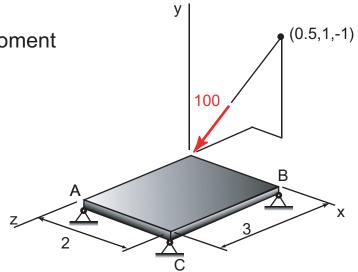
$$M_{BL} = \begin{vmatrix} \lambda_x & \lambda_y & \lambda_z \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

Note: This is the easiest way to solve moments about a line. It is normally far more difficult to look into the axis as we did earlier in the chapter.

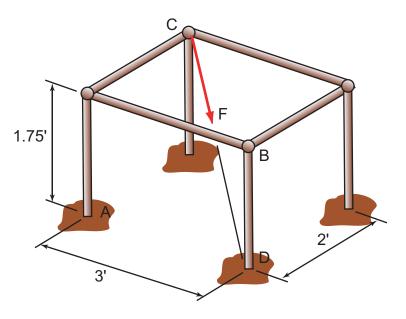
The tension force in wire AB is 600 lb. Compute the moment of the tension about line EC. Units: Lb, in.



Determine the magnitude of the moment about AB due to the 100 lb force. Units: Lb, ft.



Determine the magnitude of the moment about AB. The force F= 100 lb. Units: Lb, ft.



Observation

-When finding moments about a *point:*

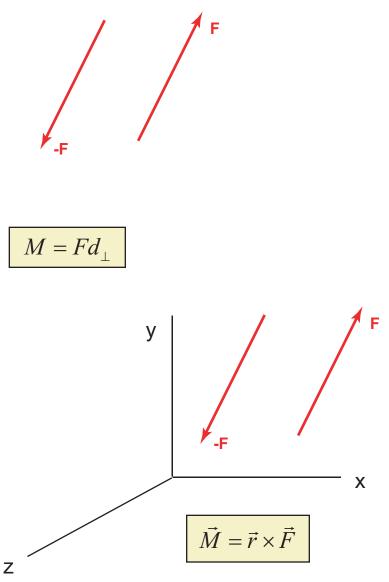
The position vector must always start at the point and ends anywhere along the force.

-When finding moments about an axis:

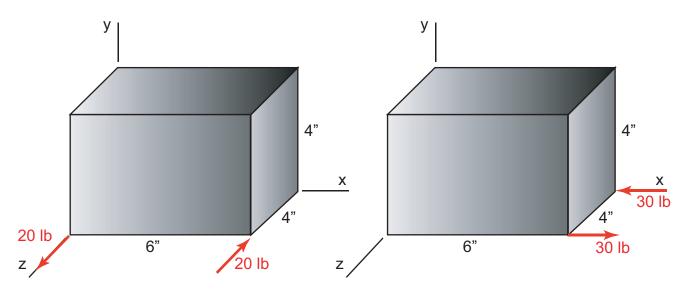
The position vector can start anywhere along the axis and ends anywhere along the force.

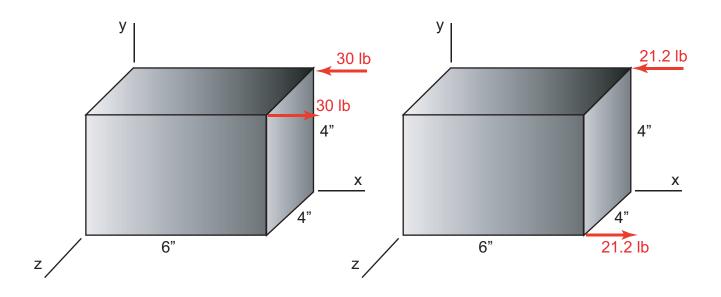
Moment of a Couple

Two forces **F** and -**F** having the same magnitude, parallel lines of action, and opposite sense are said to form a couple.

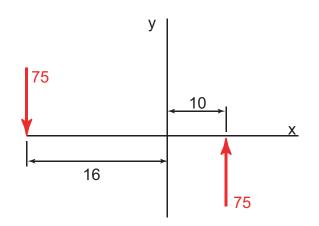


Equivalent Couples

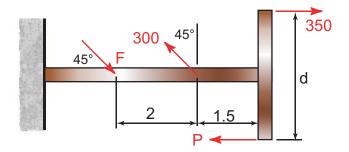


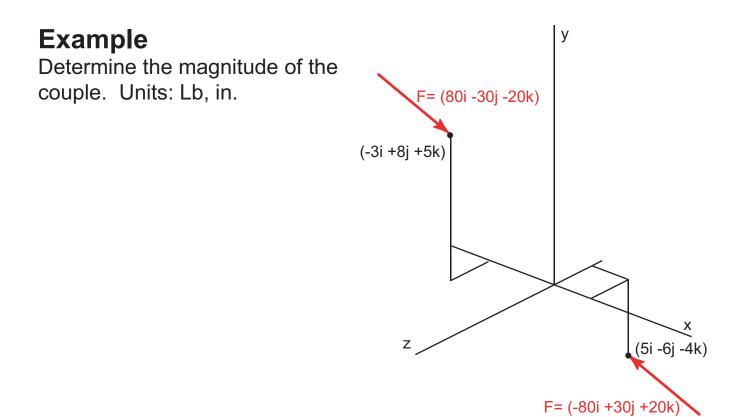


Determine the magnitude and direction of the couple. Units: Lb, in.

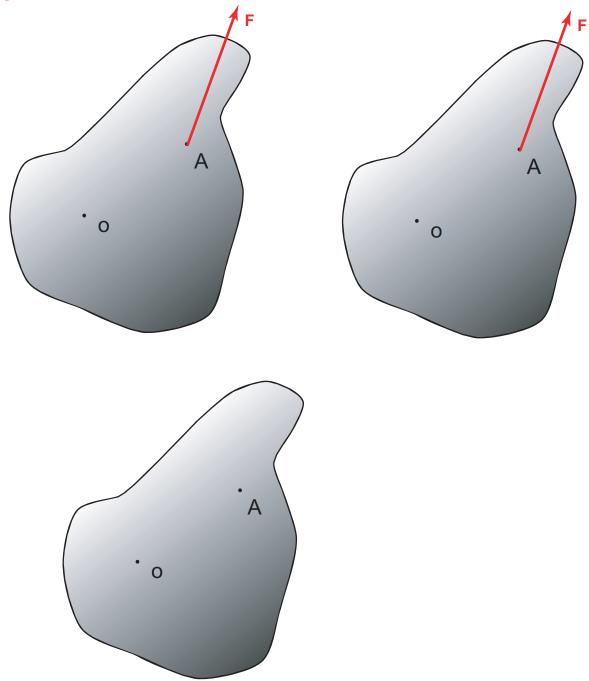


If the resultant of two couples is to be zero, determine the magnitudes of P and F, and the distance d. Units: N, m.





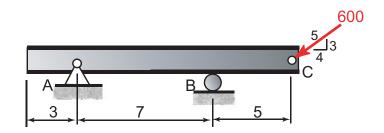
Resolution of a Given Force into a Force at O and a Couple

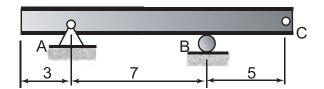


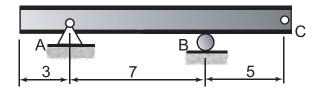
Conclusion:

You can move a force to a new location provided you add in the appropriate moment.

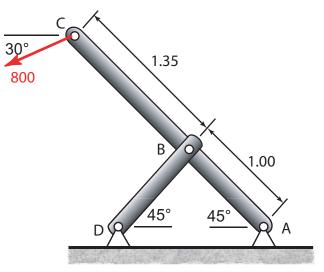
Find the equivalent force-couple system at point A and B on the beam. Units: Lb, ft.

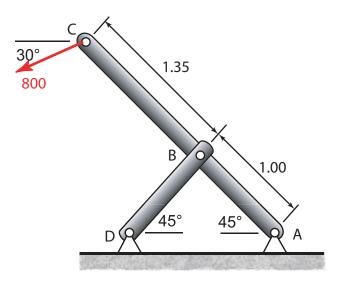






Find the equivalent force-couple system at point A and B on the beam. Units: N, m.

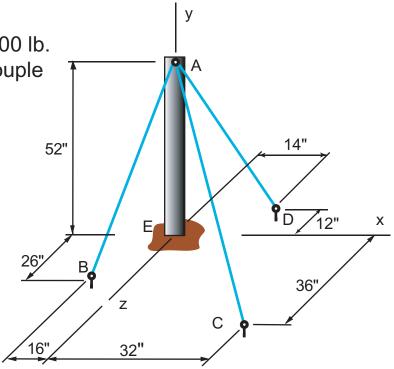




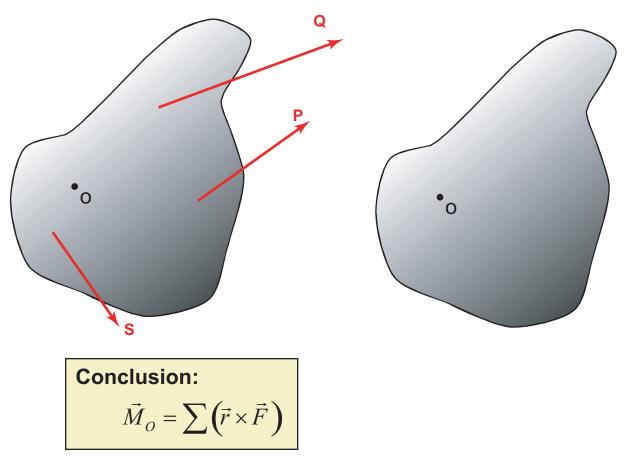
The tension force in wire AB is 600 lb. Calculate the equivalent force-couple system of this force at point E. Units: Lb, in.

From a previous solution,

$$\bar{T}_{_{AB}} = -159\bar{i} - 517\bar{j} + 259\bar{k}$$

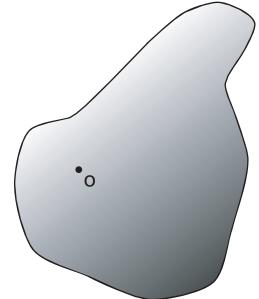


Reduction of a System of Forces to One Force and a Couple

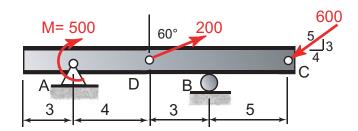


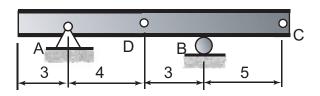
Moving a Moment to a New Location

Conclusion: To move a moment to a new location... just do it!

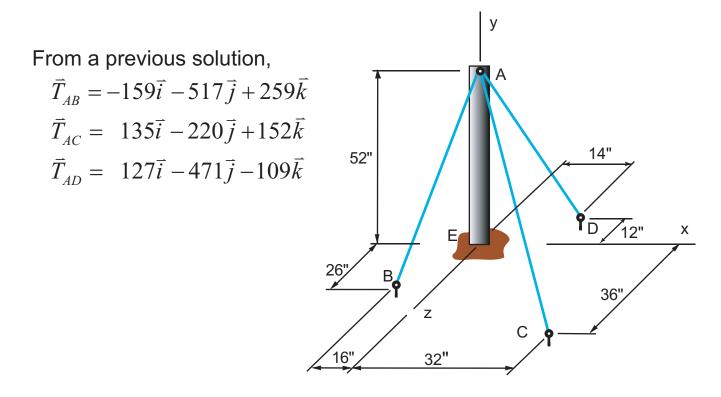


Replace the forces and moment by an equivalent force-couple system at point D on the beam. Units: Lb, ft.

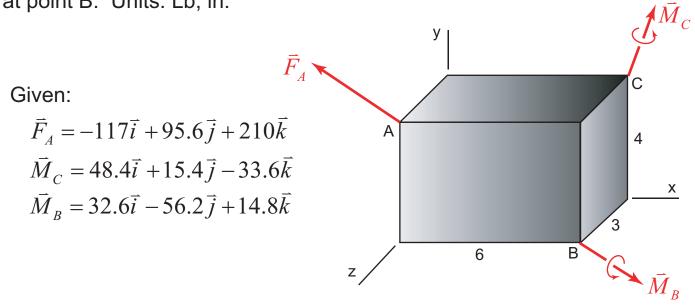




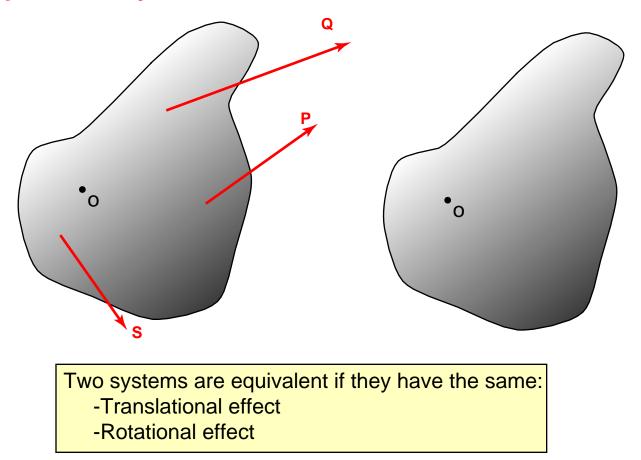
Replace the forces in the three wires at A by an equivalent force-couple system at point E. Units: Lb, ft.



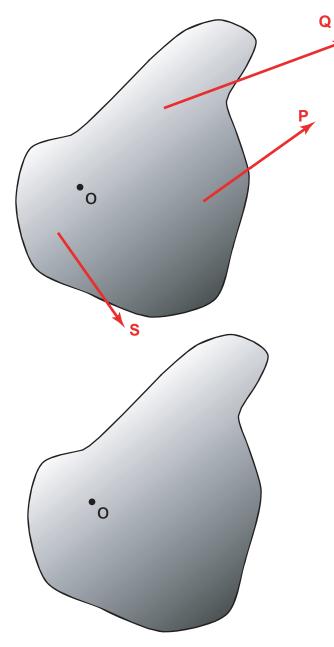
Replace the force and moments by an equivalent force-couple system at point B. Units: Lb, in.

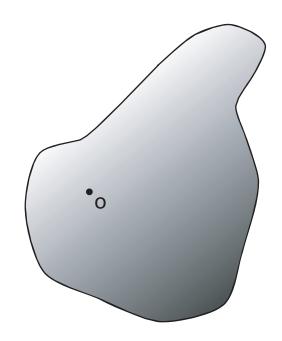


Equivalent System of Forces



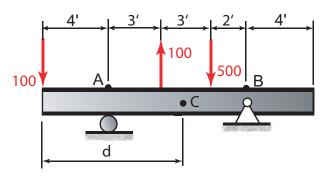
Further Reduction of a System of Forces

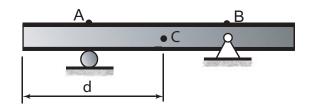




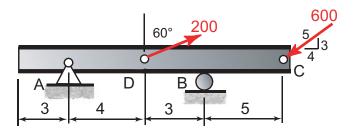
A system of forces can be replaced by a single force placed at a certain location.

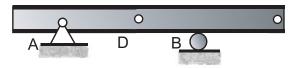
Replace this system with a single force at C and determine the distance d. Units: Lb, ft.



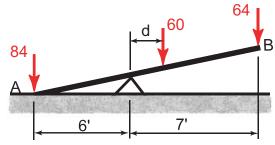


Replace the two forces with an equivalent force. Specify the location along the beam's centerline that this force must pass through. Units: N, m.



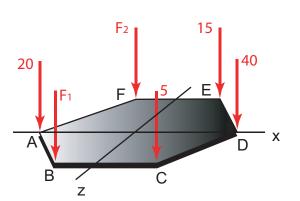


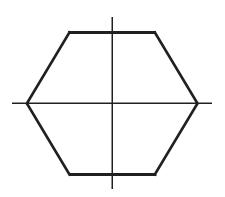
Two children are sitting at the ends of a seesaw. Where should a third child sit so that the seesaw is perfectly balanced if the third child weighs 60 lb? Units: Lb, ft.



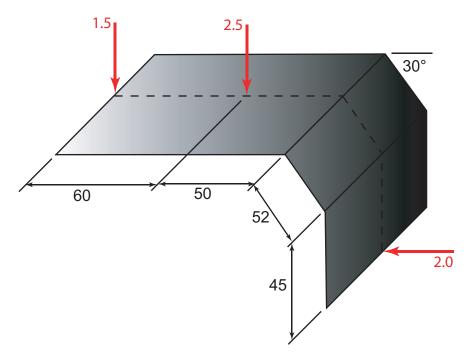
A concrete foundation mat in the shape of a regular hexagon of side 14 ft support four column loads as shown. Determine the magnitudes of the additional loads which must be applied at B and F if the resultant of all six loads is to pass through the center of the mat.

Units: Ft, kip (1 kip= 1000 pounds)

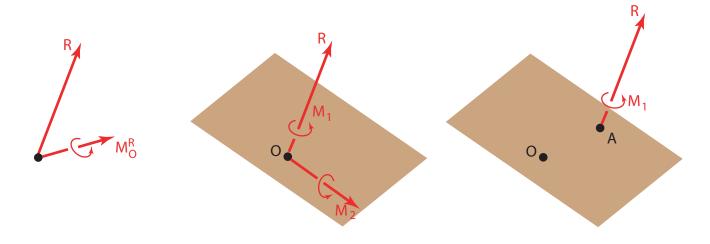




Find the resultant of the three loads and its location. Units: kN, mm.

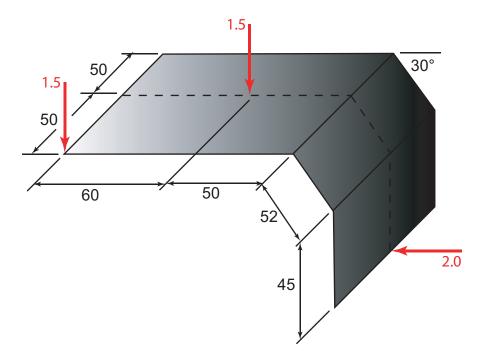


Reduction of a System of Forces to a Wrench



$$\rho = \frac{\vec{R} \cdot \vec{M}_O^R}{R^2}$$

Replace the three loads with an equivalent wrench and determine (a) the magnitude and direction of R, (b) the pitch of the wrench, (c) the point where the wrench intersects the yz plane. Units: kN, mm.



Summary

-Moments about a point in 2D

-Moments about a point in 3D

-Moments about a line

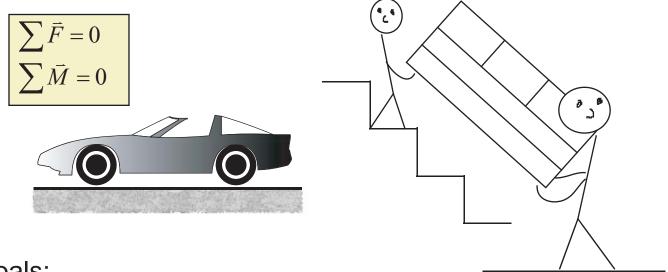
-Equivalent force couple systems

-Equivalent systems

Chapter 4 Equilibrium of Rigid Bodies

Introduction

A particle remains at rest or continues to move in a straight line with uniform velocity if the resultant forces acting on it are zero, in other words:



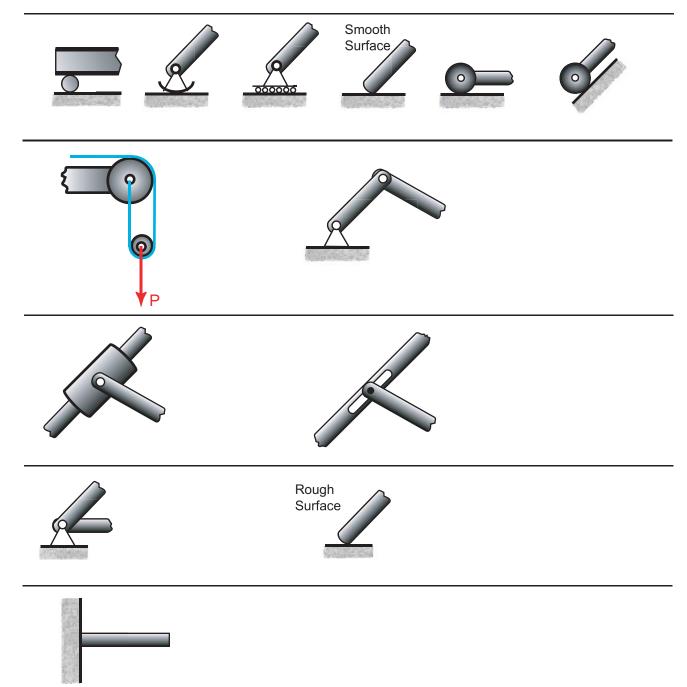
Goals:

- -Master drawing FBDs
- -Map (planning what you are going to do)
- -Equilibrium in 2D
- -Mastering moments about a point
- -Two force bodies
- -Three force bodies
- -Equilibrium in 3D
- -Mastering moments about an axis or a line

Reactions at Supports and Connections for a Two-Dimensional Structure

General Rule:

- -If it can move then there
- -If it can't move then there
- -If it can rotate then there
- -If it can't rotate then there

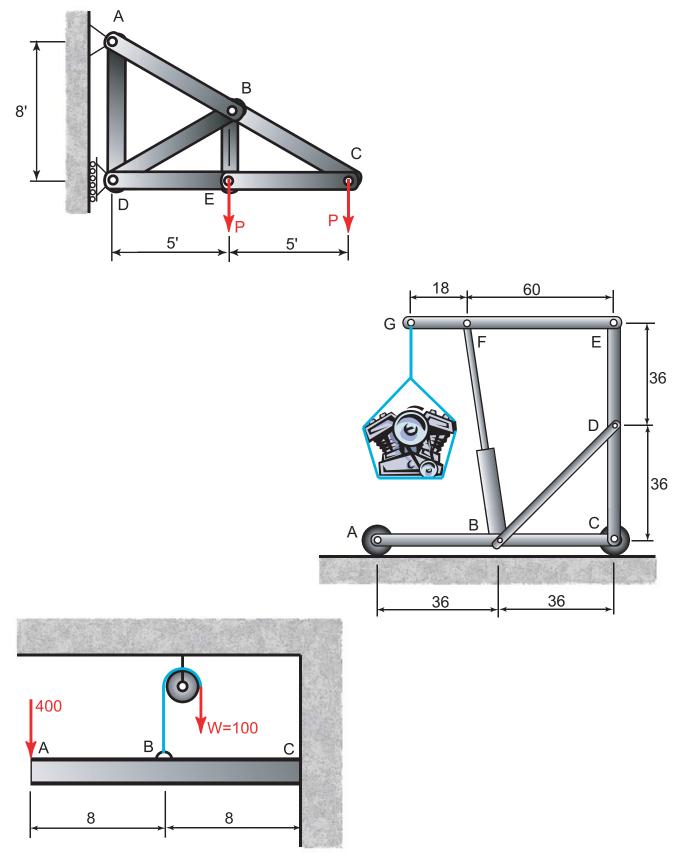


Sample Free-Body Diagrams

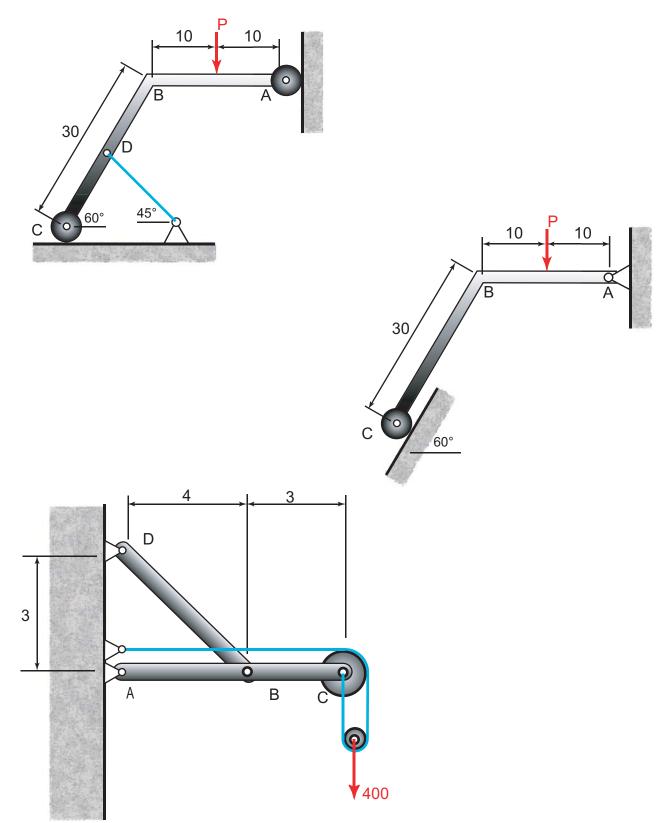
General Approach:

Map:

Sample Free-Body Diagrams

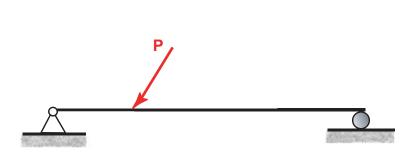


Sample Free-Body Diagrams



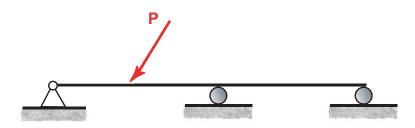
Constraints and Statical Determinacy

Sum of the forces and sum of the moments are always valid, but may be insufficient to solve the problem.

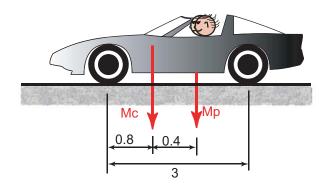


Statically Indeterminate

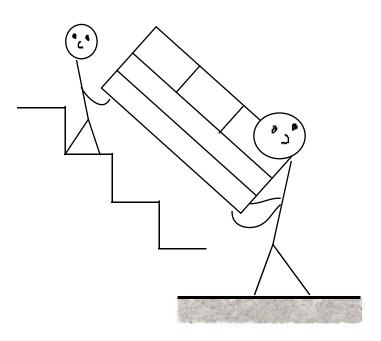
Statically Determinate



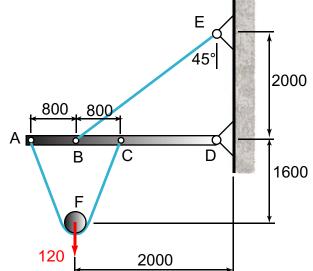
The car weighs 1400 kg (Mc) and the two passengers weigh 100 kg each (Mp). Determine the reactions at each of the two (a) rear wheels A, (b) front wheels B. Units: N, m.



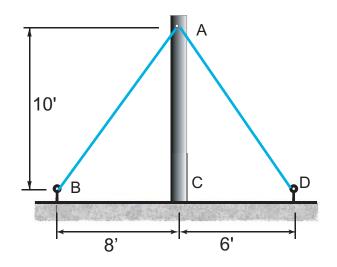
Determine the reactions that each person needs to support. The 6 ft. couch weighs 100 lb and is tilted 45°. Assume that the upper person is only able to support a reaction perpendicular to the couch (no friction) whereas the lower person can support parallel and perpendicular to the couch. Units: Lb, ft.



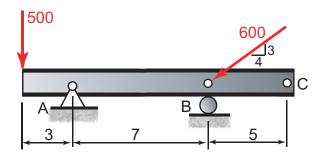
Determine the reactions at D and the tension in BE. The wire connected at A and C is continuous. Units: N, mm.



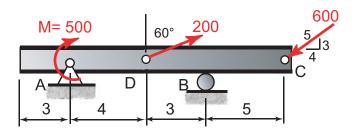
The cable stays AB and AD help support pole AC. Knowing that the tension is 140 lb in AB and 40 lb in AD, determine the reactions at C. Units: Lb, ft.



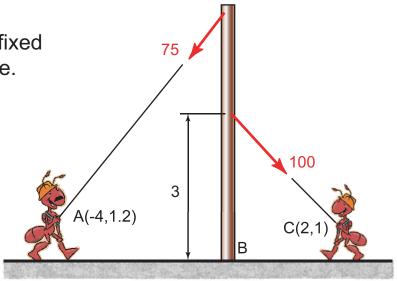
Determine the reactions at supports A and B. Units: Lb, ft.



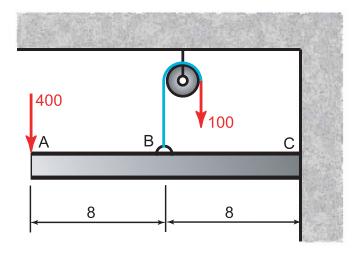
Determine the reactions at A and B. Units: Lb, ft.



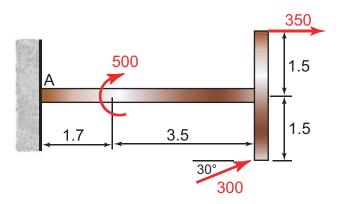
Determine the reactions at the fixed support (point B) of the 5 m pole. Units: N, m.



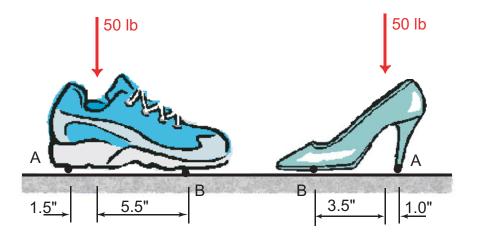
Find the reactions at the fixed support C. Units: Lb, ft.



Determine the reactions at fixed support A. Units: N, m.



Determine the reactions at A and B for each type of shoe. Units: Lb, in.



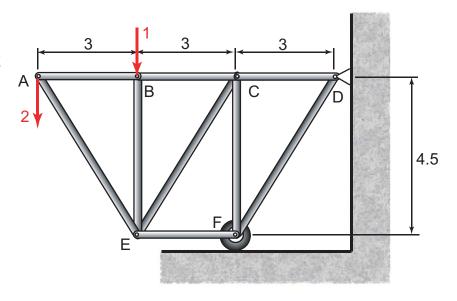
Example Determine the reactions at C and E. Units: Lb, ft.

7

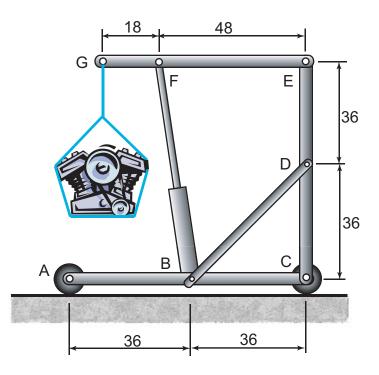
E

7

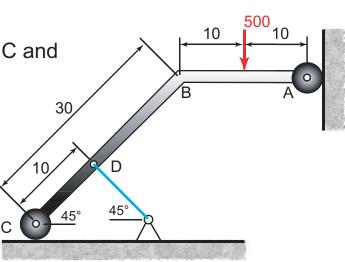
Determine the reactions at D and F. Units: kN, m.



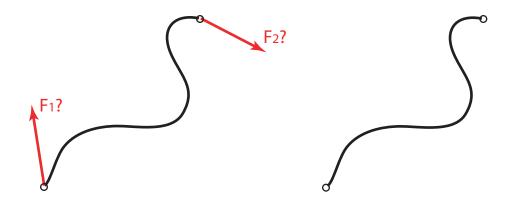
Find the reactions at A and C due to the 650 lb engine. Units: Lb, in.



Find the reactions at rollers A and C and the tension in the rope. Units: Lb, ft.



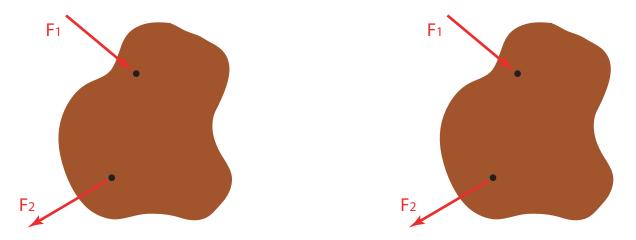
Equilibrium of a Two-Force Body



Conclusion:

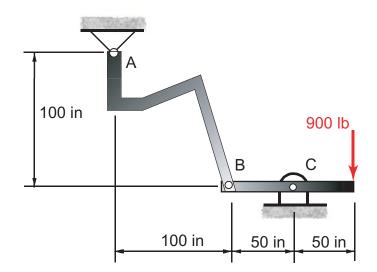
For any member that is pinned at both ends and no loads between the ends, the resultant forces must pass through each other.

Equilibrium of a Three-Force Body

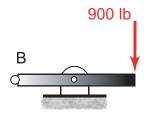


Conclusion: When the direction of two of the three forces are known, the third force must pass through the intersection of the other two.

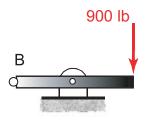
Find the reactions at A and C. Units: Lb, in.



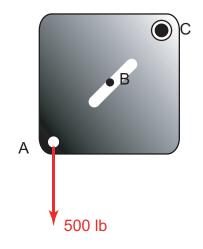
Solution 1



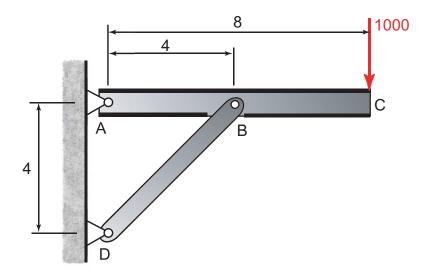
Solution 2



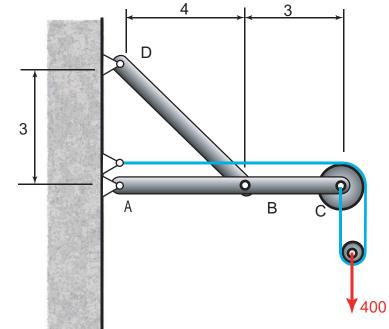
The square plate has two holes at A and C. At A a 500 lb load is applied. At C a nail is inserted and is attached to the wall so as to prevent movement in 2 directions. Another nail at the 45° slot B prevents movement perpendicular to the slot. Find the reactions at B and C knowing that B is in the center of the plate. Units: Lb, in.



Determine the reactions at A and D. Units: Lb, ft.



Determine the reactions at A, D, and the tension in the rope. The radius of the smaller pulley is 2.5" and the larger is 5". Units: Lb, ft.



Reactions at Supports and Connections for a Three-Dimensional Structure



Why do we normally ignore the moments for hinges and bearings?

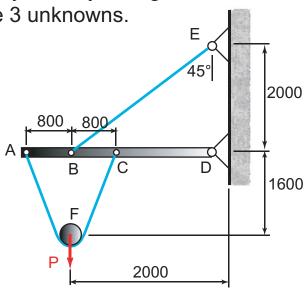


Equilibrium of a Rigid Body in 3D

$$\sum \vec{F} = 0$$
$$\sum \vec{M} = 0$$

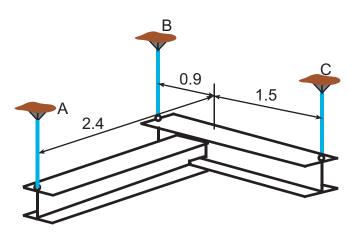
General Approach for Solving Three Dimensional Problems

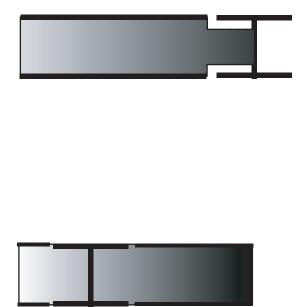
Recall for 2D problems we normally start by taking moments about a point that has 2 out of the 3 unknowns.



For 3D problems

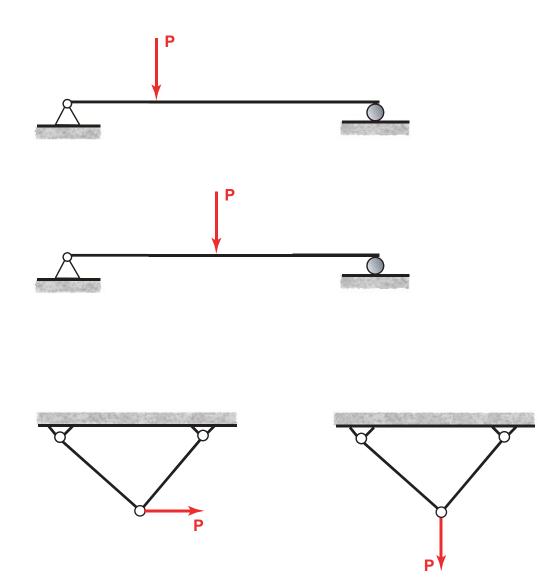
The two steel I-beams, each with a mass of 100 kg are welded together at right angles and lifted by the vertical cables so that the beams remain in a horizontal plane. Compute the tension in each of the cables A, B, C. Units: N, m.





Symmetry

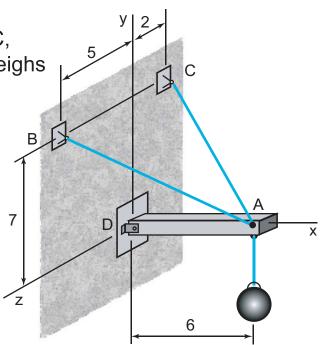
A structure whose geometry and loads are symmetric, will behave symmetrically.



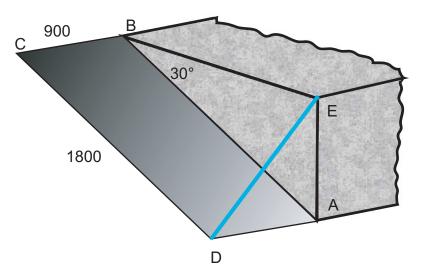
Calculate the tension in cables AB, AC, and the reactions at D. The sphere weighs 150 lb. Units: Lb, ft.

From a previous solution,

$$\begin{split} \vec{T}_{AB} &= T_{AB}(-0.571\vec{i} + 0.667\vec{j} + 0.476\vec{k}) \\ \vec{T}_{AC} &= T_{AC}(-0.636\vec{i} + 0.742\vec{j} - 0.212\vec{k}) \end{split}$$



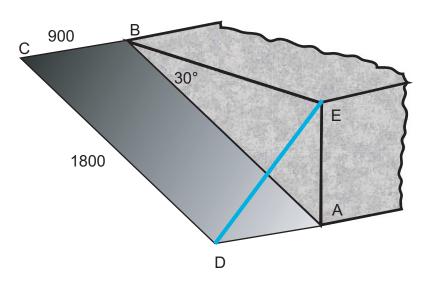
The cellar door weighs 50 kg. Hinge A can support thrust along the hinge axis AB, whereas hinge B supports force normal to the hinge axis only. Find the tension T in the wire ED. Units: N, mm.





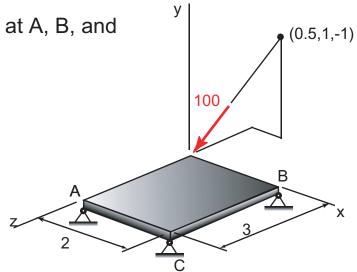


The cellar door weighs 50 kg. Hinge A can support thrust along the hinge axis AB, whereas hinge B supports force normal to the hinge axis only. Find the reactions at A and B.



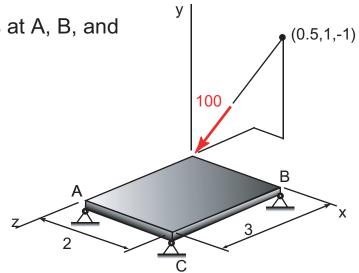
Determine the vertical reactions at A, B, and C. Units: N, m.

Solution #1:

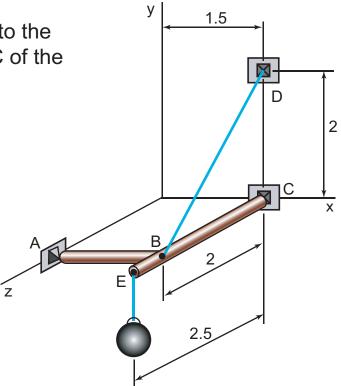


Determine the vertical reactions at A, B, and C. Units: N, m.

Solution #2:



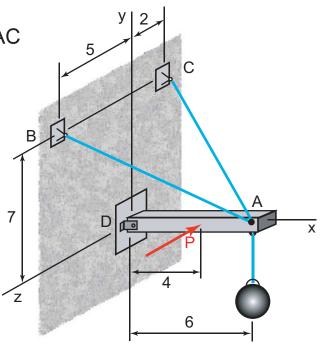
Determine the tension in BD due to the 100 kg sphere. Supports A and C of the right angle pipes are pinned. Units: N, m.



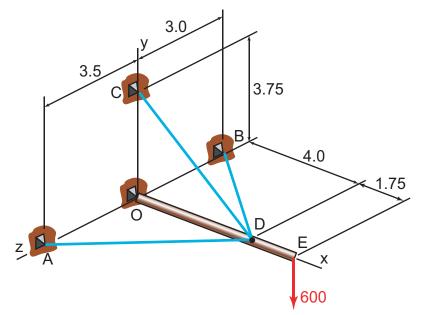
Find the force P so that the tension in AC is 0. The sphere weighs 150 lb. Units: Lb, ft.

From a previous solution,

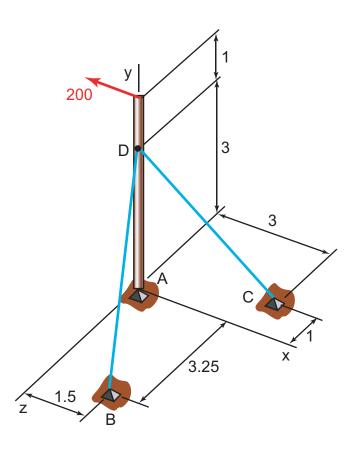
$$\begin{split} \vec{T}_{AB} &= T_{AB}(-0.571\vec{i} + 0.667\vec{j} + 0.476\vec{k}) \\ \vec{T}_{AC} &= T_{AC}(-0.636\vec{i} + 0.742\vec{j} - 0.212\vec{k}) \end{split}$$



Determine the tension in CD. Units: N, m.



Determine the force in each wire. Units: N, m.



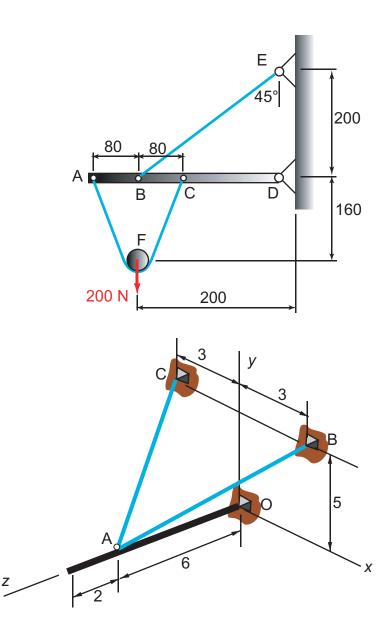


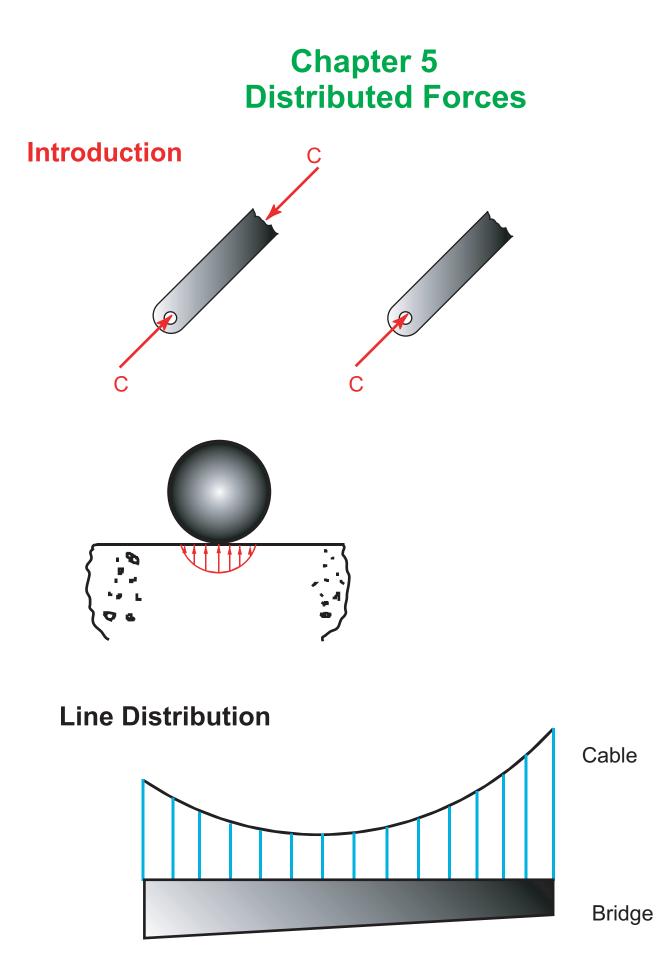
FBD

2D Equilibrium

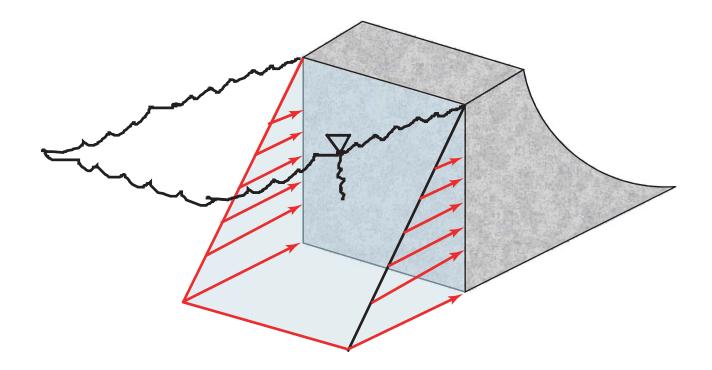
Mapping

3D Equilibrium

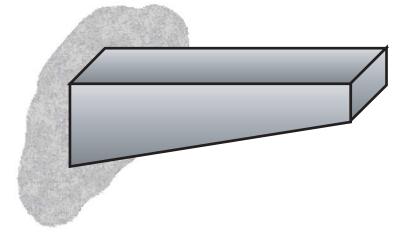




Area Distribution



Volume Distribution



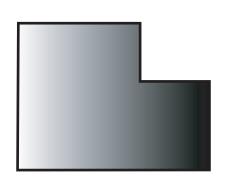
Center of Gravity of a Two-Dimensional Body

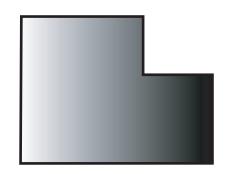


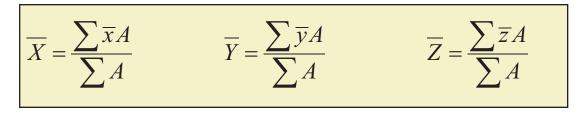
Composite Plates and Wires

Example

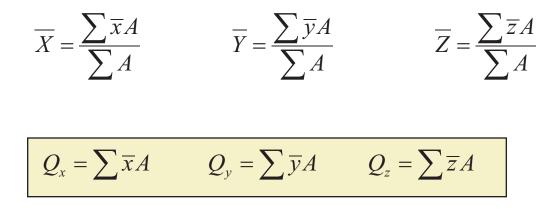
Find a general equation to locate the center of mass. Assume uniform thickness and homogeneous (same material).







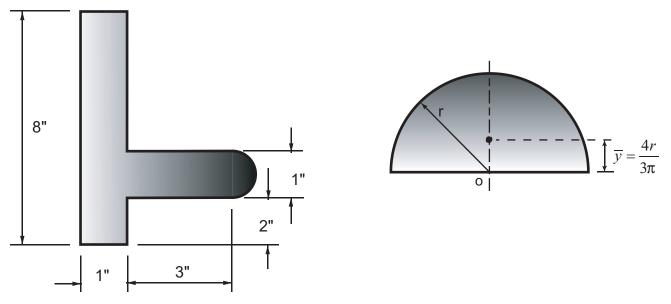
First Moment of Areas and Lines



Centroids of Areas

| Shape | | \overline{x} | $\overline{\mathcal{Y}}$ | Area |
|-----------------------|---|-------------------|--------------------------|---------------------|
| Triangle | \overline{y} | $\frac{b}{3}$ | $\frac{h}{3}$ | <u>bh</u> 2 |
| Semi- circle | | 0 | $\frac{4r}{3\pi}$ | $\frac{\pi r^2}{2}$ |
| Quarter- circle | | $\frac{4r}{3\pi}$ | $\frac{4r}{3\pi}$ | $\frac{\pi r^2}{4}$ |
| Semi- ellipse | | 0 | <u>4b</u> 3π | $\frac{\pi ab}{2}$ |
| Quarter- ellipse | $\begin{array}{c c} & & & \\ \hline & & \\$ | $\frac{4a}{3\pi}$ | $\frac{4b}{3\pi}$ | $\frac{\pi ab}{4}$ |
| Parabola | | 0 | $\frac{3h}{5}$ | $\frac{4ah}{3}$ |
| Semi- parabola | h J | $\frac{3a}{8}$ | $\frac{3h}{5}$ | $\frac{2ah}{3}$ |
| Parabolic spandrel | $y = kx^2$ \overline{x} \overline{x} \overline{x} | $\frac{3a}{4}$ | $\frac{3h}{10}$ | <u>ah</u> 3 |

Determine the centroid of the plane area. Units: In.

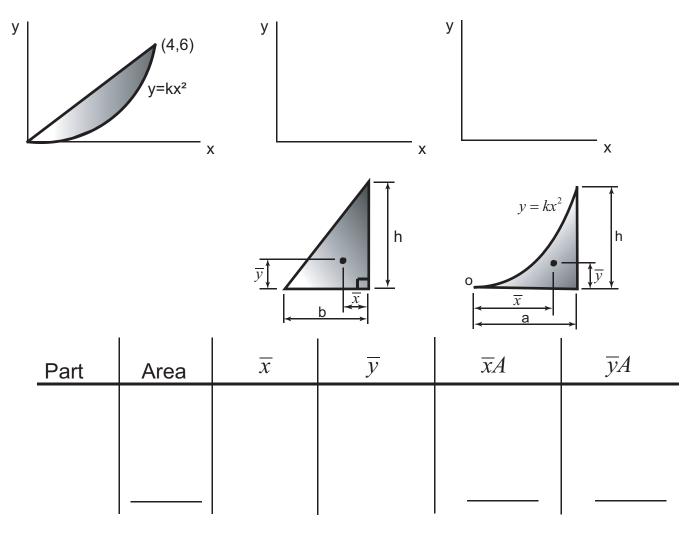


| Part | Area | \overline{x} | $\overline{\mathcal{Y}}$ | $\overline{x}A$ | <i>ӯ</i> А |
|------|------|----------------|--------------------------|-----------------|------------|
| | | | | | |
| | | | | | |
| | | | | | |

$$\overline{X} = \frac{\sum \overline{x}A}{\sum A}$$

$$\overline{Y} = \frac{\sum \overline{y}A}{\sum A}$$

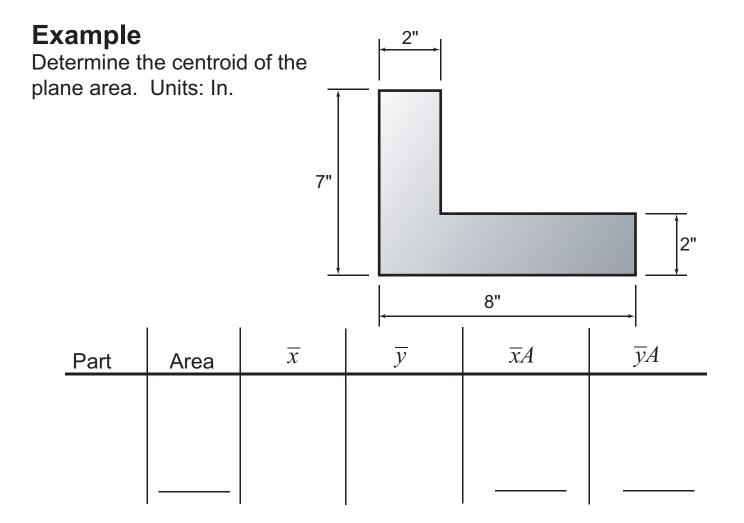
Determine the centroid of the plane area. Units: In.



$$\overline{X} = \frac{\sum \overline{x}A}{\sum A}$$

$$\overline{Y} = \frac{\sum \overline{y}A}{\sum A}$$

5-8



$$\overline{X} = \frac{\sum \overline{x}A}{\sum A}$$

$$\overline{Y} = \frac{\sum \overline{y}A}{\sum A}$$

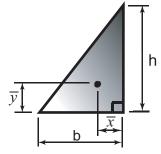
5-9

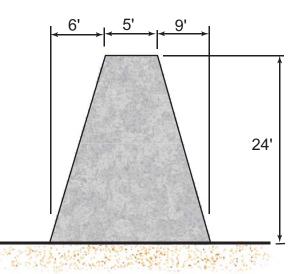
150 Example 75 Determine the centroid of ≻ the plane area. Units: mm. 15 150 15 R= 50 Part Area $\overline{\mathcal{Y}}$ $\overline{y}A$

$$\overline{Y} = \frac{\sum \overline{y}A}{\sum A}$$

Determine the X centroid of the dam. Units: Ft.

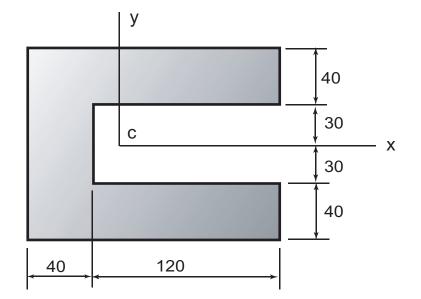
 $\sum A$





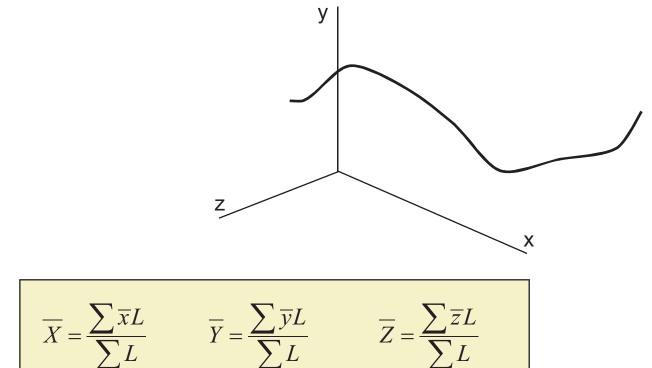
| Part | Area | \overline{x} | $\overline{x}A$ | | | |
|--|------|----------------|-----------------|--|--|--|
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| $\overline{X} = \frac{\sum \overline{x}A}{\sum A}$ | | | | | | |

Determine the centroid of the plane area. Units: mm.



| Part | Area | \overline{x} | $\overline{x}A$ |
|------------------------------------|-----------------|---|-----------------|
| | | | |
| | | | |
| | | | |
| | | | |
| | | l i i i i i i i i i i i i i i i i i i i | I |
| $\overline{X} = \frac{\sum}{\sum}$ | \overline{XA} | | |

Centroids of Lines

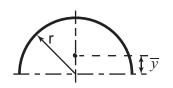


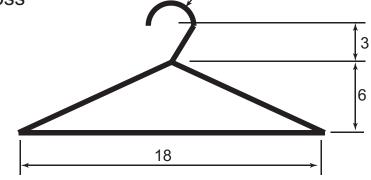
$$\overline{X} = \frac{\int_{0}^{L} xdL}{L} \qquad \overline{Y} = \frac{\int_{0}^{L} ydL}{L} \qquad \overline{Z} = \frac{\int_{0}^{L} zdL}{L}$$

Centroids of Lines

| Shape | | \overline{x} | $\overline{\mathcal{Y}}$ | L |
|--------------------|---|------------------------------|--------------------------|-------------------|
| Half- Circle | | 0 | $\frac{2r}{\pi}$ | πr |
| Quarter- Circle | $ \begin{array}{c} \hline \\ \hline \\$ | $\frac{2r}{\pi}$ | $\frac{2r}{\pi}$ | $\frac{\pi r}{2}$ |
| Arc | R α $-\alpha$ $-\alpha$ $-\alpha$ $-\alpha$ | $\frac{r\sin\alpha}{\alpha}$ | 0 | 2α <i>r</i> |

A thin steel wire of uniform cross section is bent into the shape shown. Locate the center of gravity. Units: In.





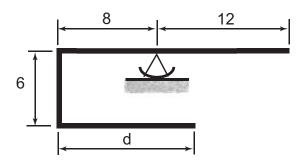
-R1.5

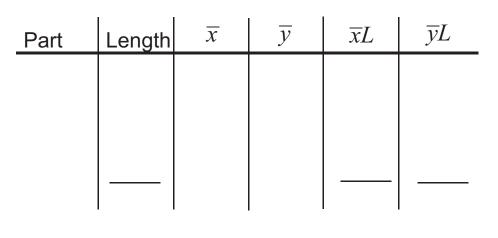
| Part | Length | \overline{x} | $\overline{\mathcal{Y}}$ | $\overline{x}L$ | $\overline{y}L$ |
|------|--------|----------------|--------------------------|-----------------|-----------------|
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |

$$\overline{X} = \frac{\sum \overline{x}L}{\sum L}$$

$$\overline{Y} = \frac{\sum \overline{y}L}{\sum L}$$

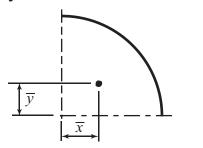
A thin steel wire of uniform cross section is bent into the shape shown. Determine the distance d to keep it aligned as shown. Units: In.

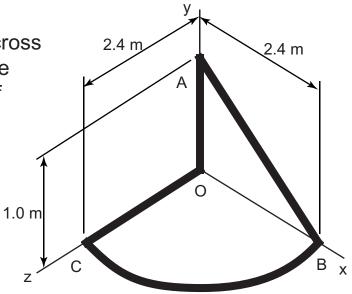




$$\overline{X} = \frac{\sum \overline{x}L}{\sum L}$$

A thin steel wire of uniform cross section is bent into the shape shown. Locate the center of gravity.





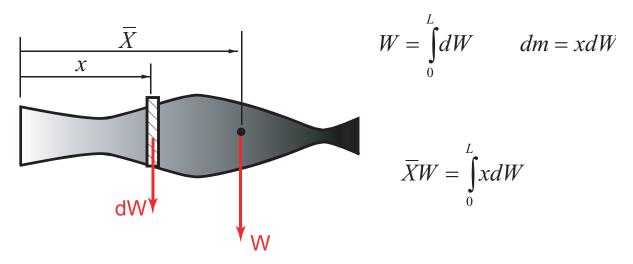
| Part | Length | \overline{x} | $\overline{\mathcal{Y}}$ | \overline{Z} | $\overline{x}L$ | $\overline{y}L$ | $\overline{z}L$ |
|------|--------|----------------|--------------------------|----------------|-----------------|-----------------|-----------------|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |

$$\overline{X} = \frac{\sum \overline{x}L}{\sum L}$$

$$\overline{Y} = \frac{\sum \overline{y}L}{\sum L}$$
$$\overline{Z} = \frac{\sum \overline{z}L}{\sum \overline{z}L}$$

$$=\frac{\sum 2L}{\sum L}$$

Determination of Centroids by Integration



Since the moments in each system must be equal,

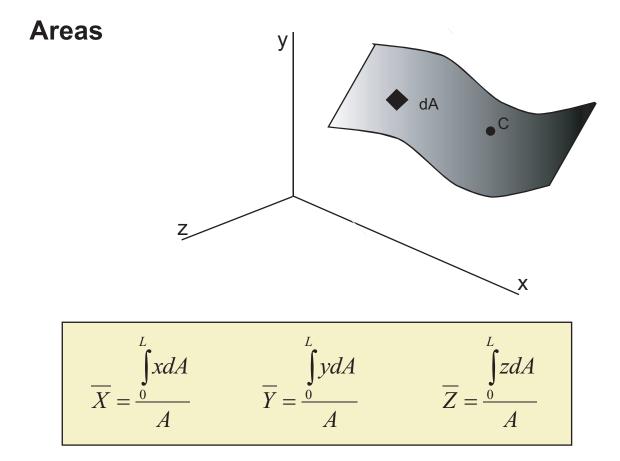
$$\overline{X} = \frac{\int_{0}^{L} x dW}{W} \qquad \qquad \overline{Y} = \frac{\int_{0}^{L} y dW}{W} \qquad \qquad \overline{Z} = \frac{\int_{0}^{L} z dW}{W}$$

or with W= Mg and dW= gdM,

$$\overline{X} = \frac{\int_{0}^{L} x dM}{M} \qquad \qquad \overline{Y} = \frac{\int_{0}^{L} y dM}{M} \qquad \qquad \overline{Z} = \frac{\int_{0}^{L} z dM}{M}$$

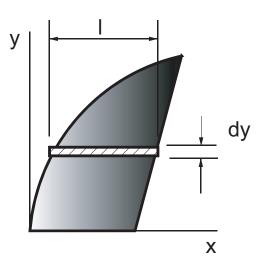
or with M= ρ V and dM= ρ dV,

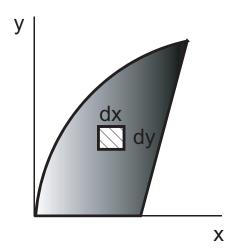
$$\overline{X} = \frac{\int_{0}^{L} x \rho \, dV}{\rho V} \qquad \overline{Y} = \frac{\int_{0}^{L} y \rho \, dV}{\rho V} \qquad \overline{Z} = \frac{\int_{0}^{L} z \rho \, dV}{\rho V}$$



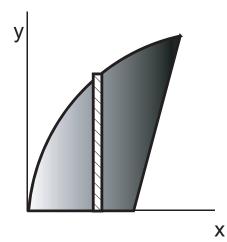
Choice of Element Integration

Order of Element

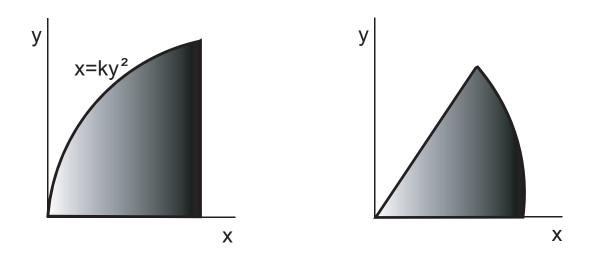




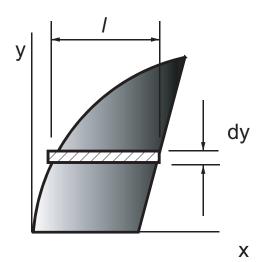
Continuity



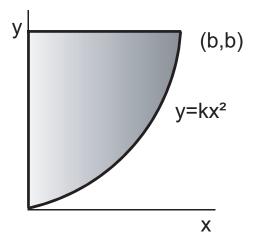
Choice of Coordinates



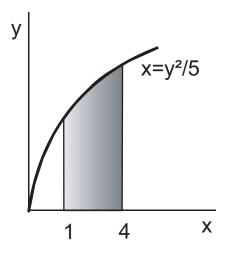
Centroidal Coordinates of the Element



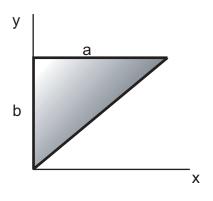
Using integration, determine the coordinates of the centroid of the shaded area.



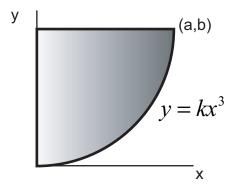
Using integration, determine the coordinates of the centroid of the shaded area.



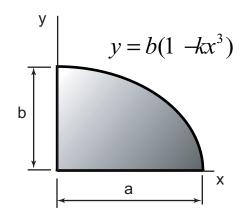
Determine the centroid of the area. Use integration.



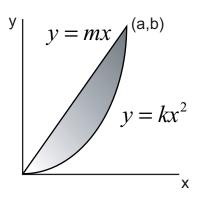
Determine the centroid of the area. Use integration.



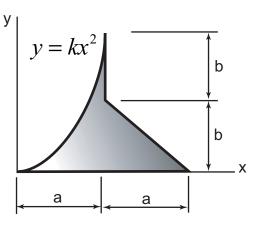
Determine the x centroid of the area. Use integration.



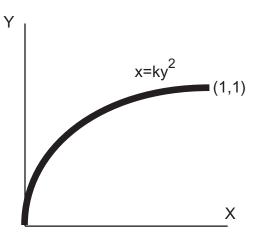
Determine the centroid of the area. Use integration.



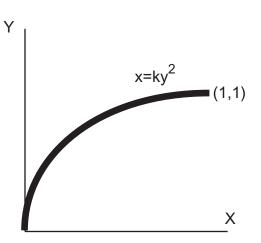
Determine the x centroid of the area. Use integration.



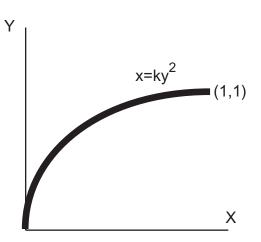
Determine the length of the homogeneous rod. Use integration.



Determine the x centroid of the homogeneous rod. Use integration.



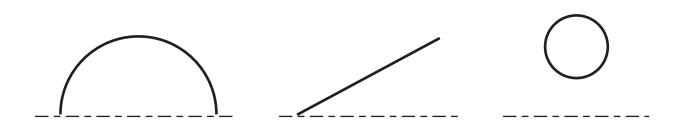
Determine the y centroid of the homogeneous rod. Use integration.



Theorems of Pappus-Guldinus: Theorem I

The area of a surface of revolution is equal to the length of the generating curve times the distance traveled by the centroid of the curve while the surface is being generated.

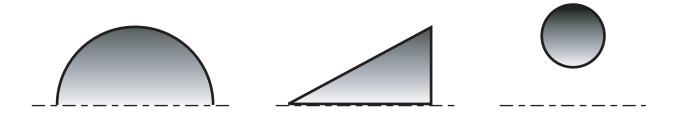
$$A = 2\pi \,\overline{y}L$$



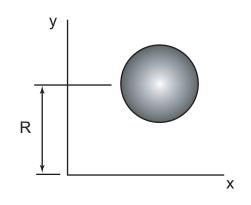
Theorems of Pappus-Guldinus-Theorem II

The volume of a body of revolution is equal to the generating area times the distance traveled by the centroid of the area while the body is being generated.

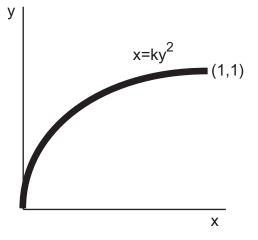
$$V = 2\pi \overline{y}A$$



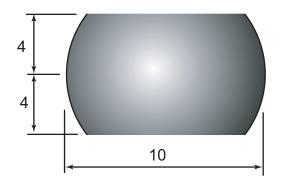
Determine the surface area of a circle with radius r rotated about the x-axis forming a torus.



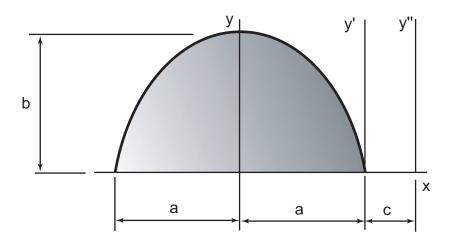
Determine the surface area of the parabolic shape if it is rotated 180° about the x-axis. Units: in.



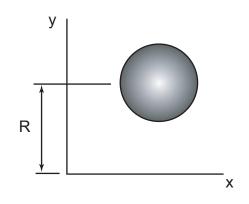
Determine the surface area and volume of a ball that has been cut off on the top and bottom as shown. Units: In.



Determine the volume of the semi-elliptical shape rotated about the y, y' and y" axis.



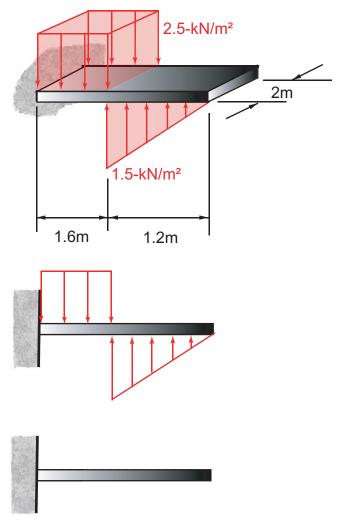
Determine volume of a circle with radius r rotated about the x-axis forming a torus.



Distributed Loads on Beams

Example

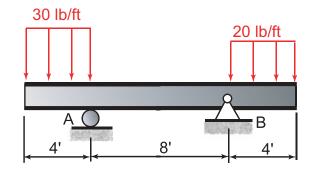
Determine the support reactions of the cantilever beam. Units: kN, m.

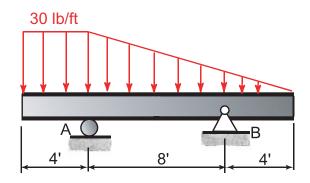


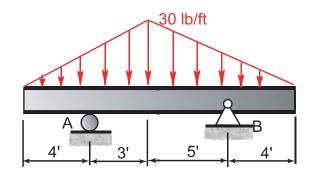
Conclusion:

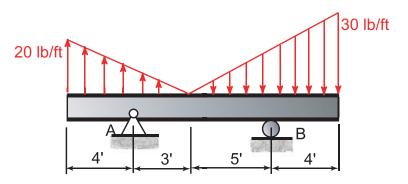
-When given a distributed load with the units of force per length the resultant is equal to the area under the curve.

-When given a distributed load with the units of force per area the resultant is equal to the volume under the curve.

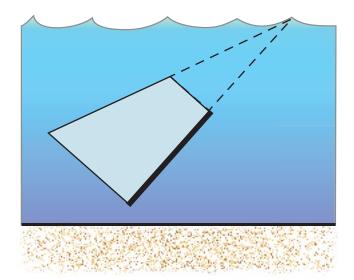


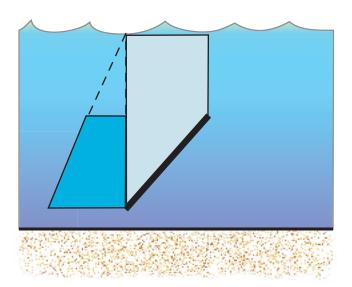




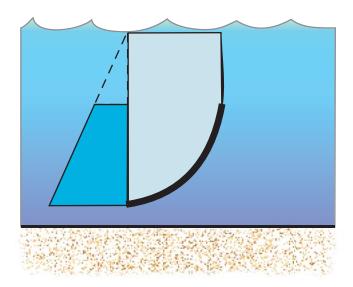


Forces on Submerged Surfaces- Flat Surfaces

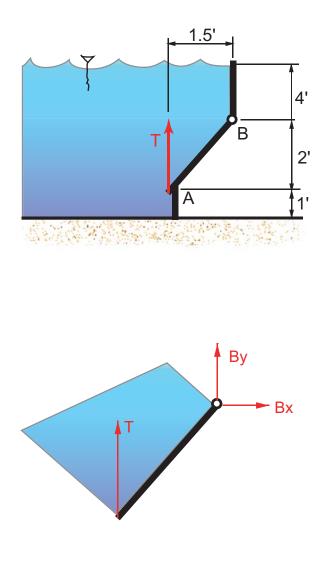




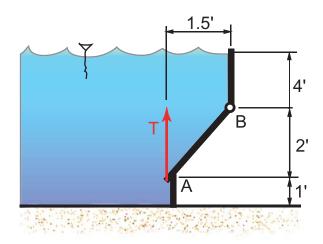
Forces on Submerged Surfaces- Curved Surfaces

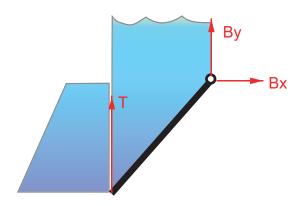


Determine the minimum tension required to open the gate. The gate AB is 2.25 ft wide. Units: Lb, ft.

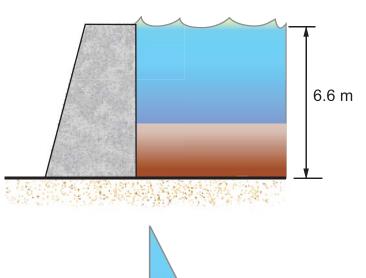


Determine the minimum tension required to open the gate. The gate AB is 2.25 ft wide. Units: Lb, ft.

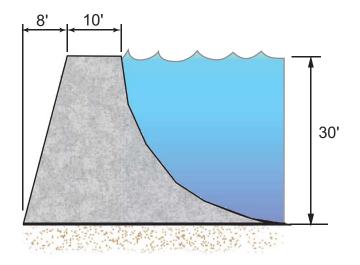


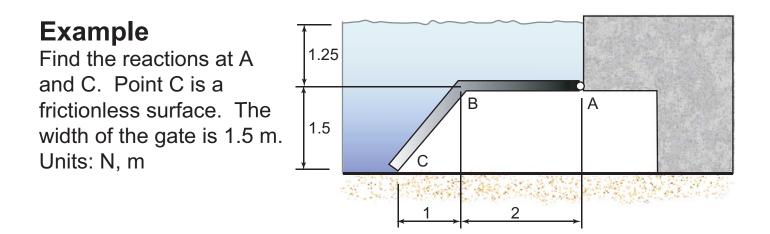


The dam is designed to withstand the additional force caused by silt. Assuming that silt is equivalent to a liquid of density of 1800 kg/m³ and considering a 1 m wide section of dam, determine the force acting on the dam face for a slit accumulation of depth 2 m. Units: N, m.

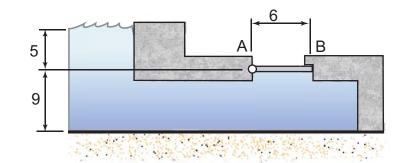


Determine the resultant force due to the water on the face of the dam. Also find the forces under the concrete dam. Units: Lb, ft.

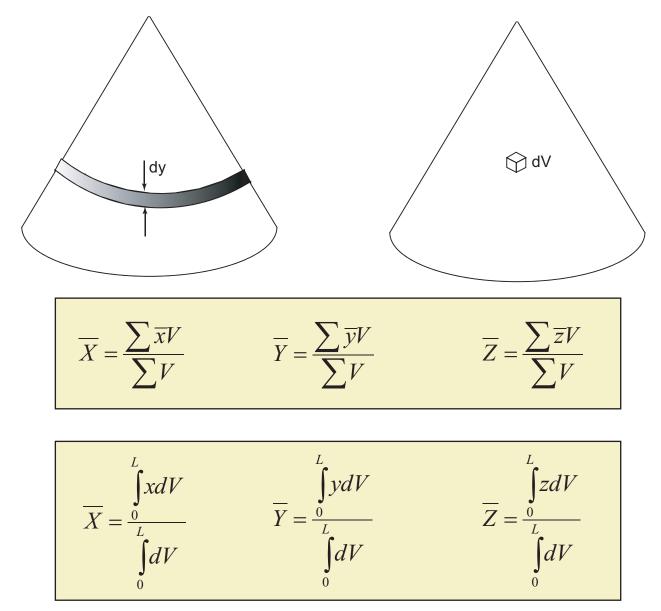




Determine the reactions at A and B. The gate is 8' wide. Units: Ft



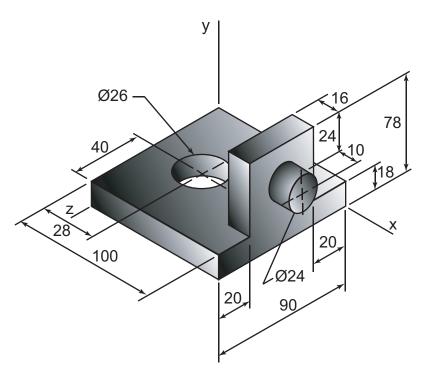
Center of Gravity of a Three-Dimensional Body Centroid of a Volume



Centroids of Volumes

| Shape | | \overline{X} | Volume |
|--------------------------------|---|----------------|------------------------|
| Hemisphere | | $\frac{3a}{8}$ | $\frac{2}{3}\pi a^3$ |
| Semiellipsoid of revolution | | $\frac{3h}{8}$ | $\frac{2}{3}\pi a^2 h$ |
| Paraboloid of revolution | a b c c b c b c c b c | $\frac{h}{3}$ | $\frac{1}{2}\pi a^2 h$ |
| Cone | h | $\frac{h}{4}$ | $\frac{1}{3}\pi a^2 h$ |
| Pyramid | b h | <u>h</u> 4 | $\frac{1}{3}abh$ |

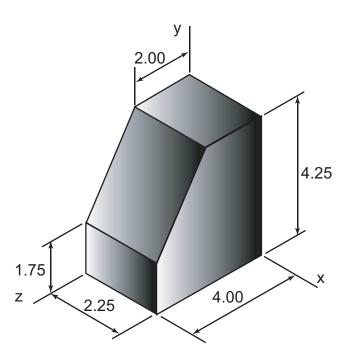
For the machine element shown, locate the centroid. Units: mm.



| Part | Volume | Xel | Yel | Zel | XelV | YelV | ZelV |
|------|--------|-----|-----|-----|------|------|------|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |

$$\overline{X} = \frac{\sum \overline{x}V}{\sum V}$$
$$\overline{Y} = \frac{\sum \overline{y}V}{\sum V}$$
$$\overline{Z} = \frac{\sum \overline{z}V}{\sum V}$$

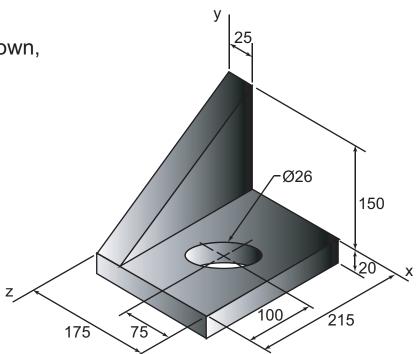
For the machine element shown, locate the centroid. Units: in.



| Part | Volume | Xel | Yel | Zel | XelV | YelV | ZelV |
|------|--------|-----|-----|-----|------|------|------|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |

$$\overline{X} = \frac{\sum \overline{x}V}{\sum V}$$
$$\overline{Y} = \frac{\sum \overline{y}V}{\sum V}$$
$$\overline{Z} = \frac{\sum \overline{z}V}{\sum V}$$

For the machine element shown, locate the centroid. Units: mm.



| Part | Volume | Xel | Yel | Zel | XelV | YelV | ZelV |
|------|--------|-----|-----|-----|------|------|------|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |

$$\overline{X} = \frac{\sum \overline{x}V}{\sum V}$$
$$\overline{Y} = \frac{\sum \overline{y}V}{\sum V}$$
$$\overline{Z} = \frac{\sum \overline{z}V}{\sum V}$$

Summary

Centroids Vs. Center of Masses

Centroids of Lines

$$\overline{X} = \frac{\sum \overline{x}L}{\sum L} \qquad \overline{Y} = \frac{\sum \overline{y}L}{\sum L} \qquad \overline{Z} = \frac{\sum \overline{z}L}{\sum L}$$

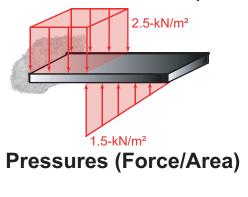
Centroids of Areas

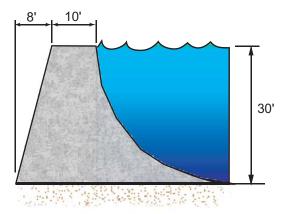
$$\overline{X} = \frac{\sum \overline{x}A}{\sum A} \qquad \qquad \overline{Y} = \frac{\sum \overline{y}A}{\sum A} \qquad \qquad \overline{Z} = \frac{\sum \overline{z}A}{\sum A}$$

Centroids of Volumes

$$\overline{X} = \frac{\sum \overline{x}V}{\sum V} \qquad \qquad \overline{Y} = \frac{\sum \overline{y}V}{\sum V} \qquad \qquad \overline{Z} = \frac{\sum \overline{z}V}{\sum V}$$

Distributed Loads (Force/Length)



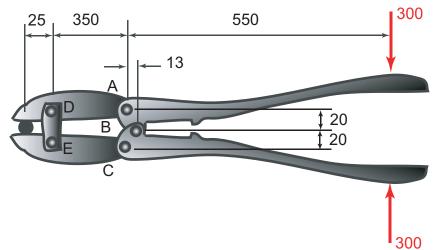


Chapter 6 Analysis of Structures

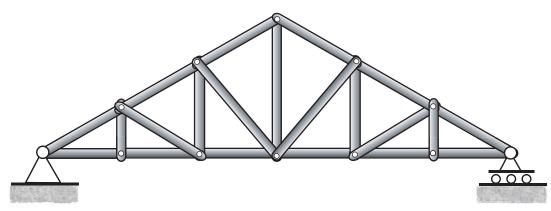
Introduction Trusses



Frames



Plane Trusses



- -Loads act only at the joints
- -Pinned connections
- -Two force members (tension/compression)
- -Basic element is the triangle

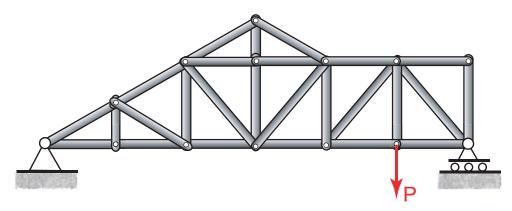




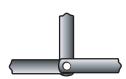
Bridge Truss in Santa Margarita



Method of Joints Joints Under Special Loading Conditions- Tricks



Trick #1



Trick #2

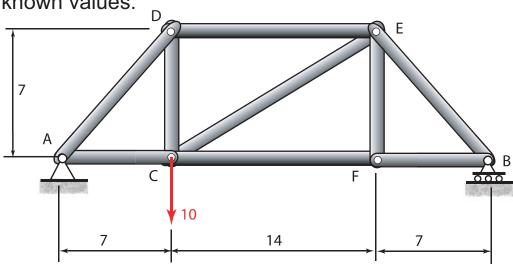


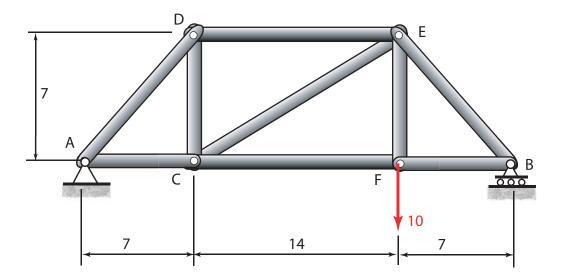


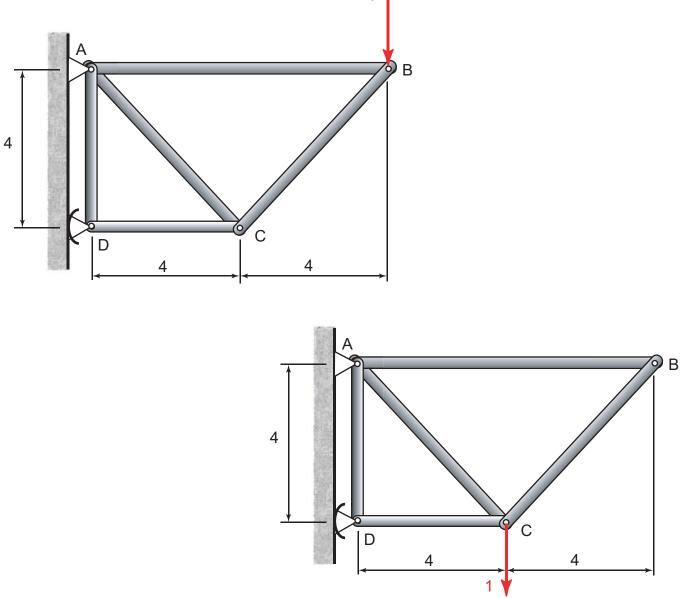


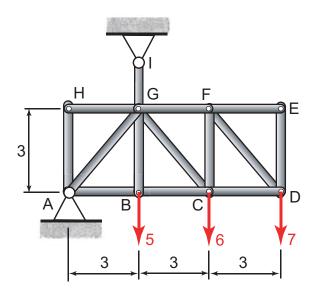


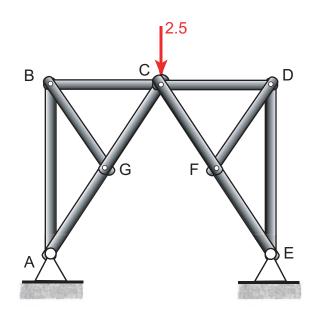
NOTE: No additional loads applied to the joints.



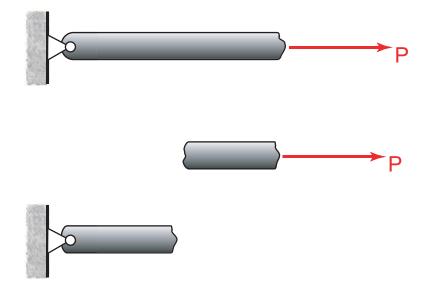








Review of FBDs

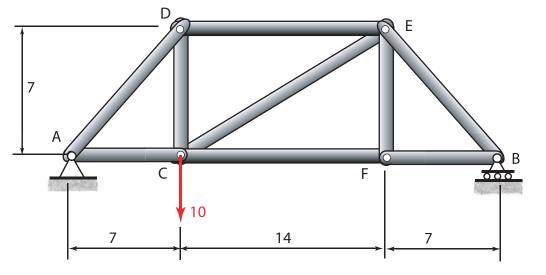


NEWTON'S THIRD LAW: The forces of action and reaction between interacting bodies are equal in magnitude, opposite in direction, and collinear.

Conclusion:

If a bar is in tension, then no matter what FBD you draw it is still in tension. If a bar is in compression, then no matter what FBD you draw it is still in compression.

Relationships Between FBDs

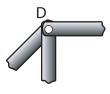


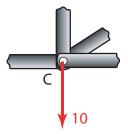
FBD- Joint A

FBD- Joint D

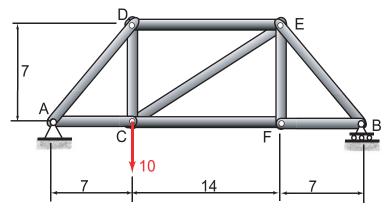
FBD- Joint C







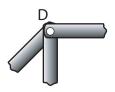
Determine the force in each member of the truss. Note the presence of any zero-force members. Units: kN, m.



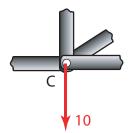
FBD- Joint A



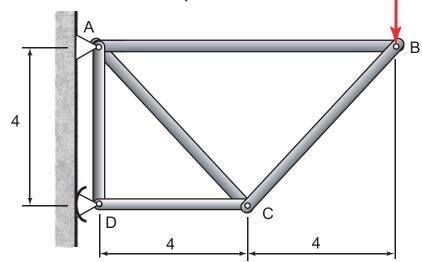
FBD- Joint D



FBD- Joint C

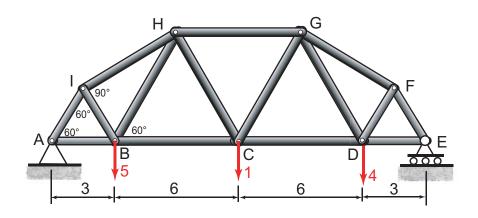


Determine the force in each member of the truss. Note the presence of any zero-force members. Units: Kips, ft.

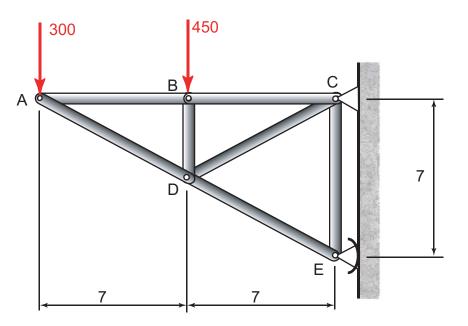


1

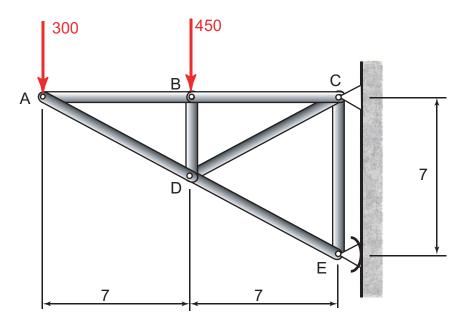
Example Determine the forces in members BI and BH. Units: kN, m.



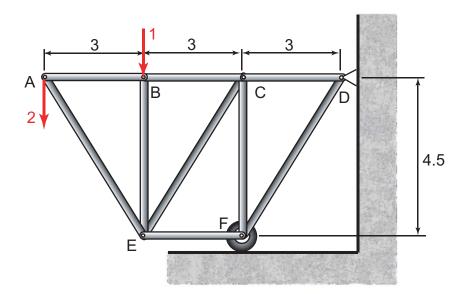
Determine the forces in AB and AD. Units: kN, m.



Determine the forces in CD and DE. Units: kN, m.



Determine the forces in AB and AE. Units: kN, m.



Example Determine the forces in CD and DF. Units: kN, m.

E

4.5

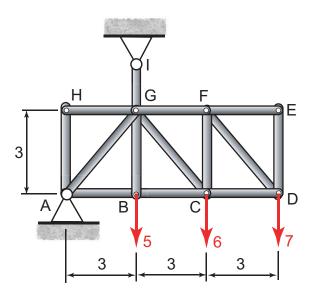
Example A Determine the forces in BC and 0 EC. Units: Lb, ft. В 8 0 С 00000 O 0 0 Е D 500 700 5 5

Example А Determine the forces in AB and 0 AD. Units: Lb, ft. В 8 6 С 000000 0 0 0 Е D 500 700 5 5

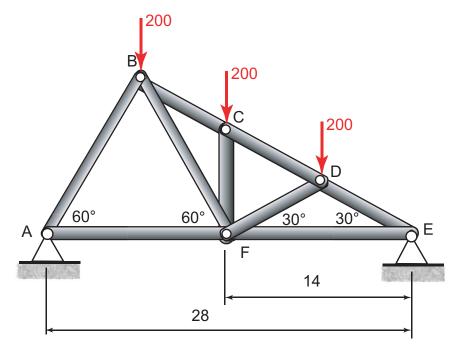
Method of Sections

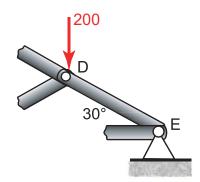
Example

Determine the force in member CG. Units: kN, m.

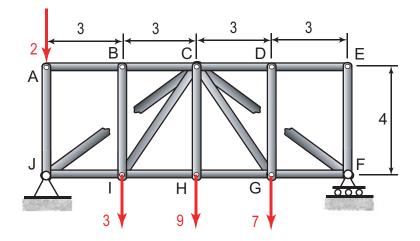


Determine the forces in members CD, CF, and EF. Ignore any horizontal reactions at the supports. Units: Lb, ft.

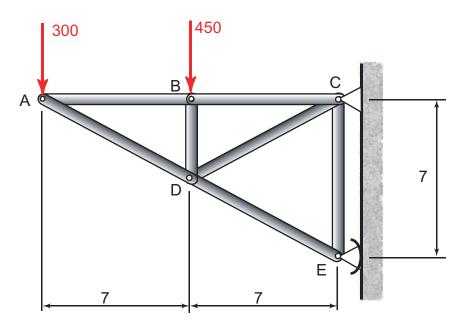




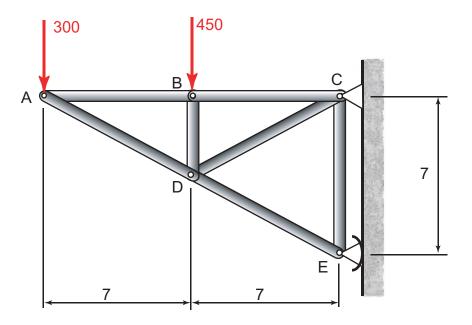
Compute the forces in members BC, CJ, CI, and HI. The members CJ and CF pass behind BI and DG. Units: Kips, ft. 1 Kip= 1000 lb.



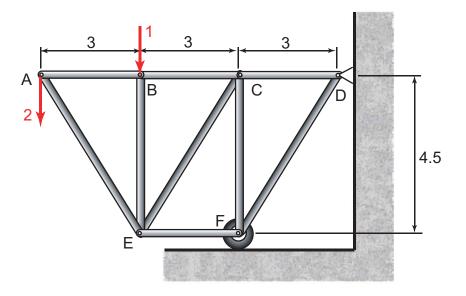
Determine the forces in BC, CD, and DE. Units: kN, m.



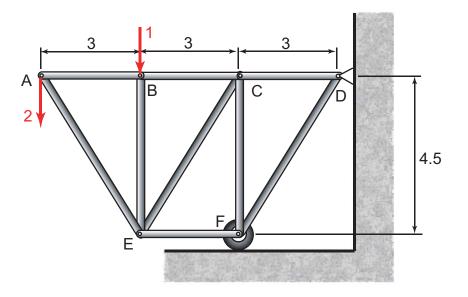
Determine the forces in BC, BD, and AD. Units: kN, m.



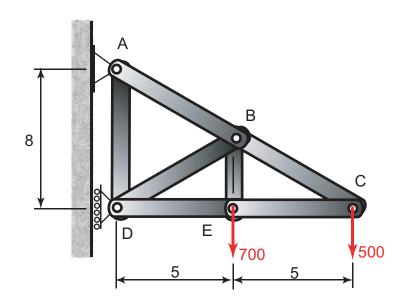
Determine the forces in BC, CE, and EF. Units: kN, m.



Determine the forces in CD and DF. Units: kN, m.



Determine the forces in AB, BD, and DE. Units: Lb, ft.



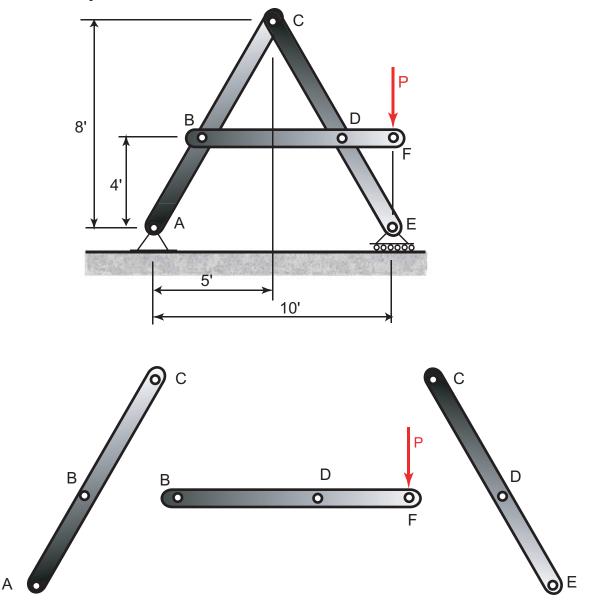
Example A Determine the forces in AB, 0 BD, and EC. Units: Lb, ft. В 8 O 000000 σ 0 0 Е D 500 700 5

С

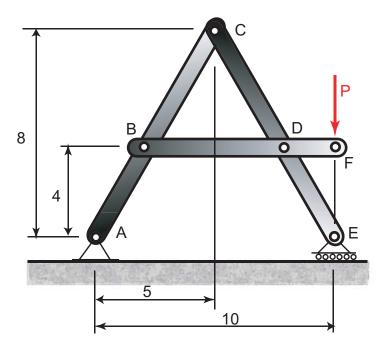
5

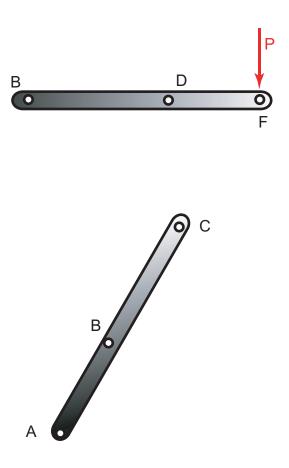
FRAMES and **MACHINES**

A structure is called a FRAME or MACHINE if at least one of its individual members is a multi-force member. If the structure is intended to move then we call it a MACHINE, if its not intended to move as in a building then its called a frame. No matter what you call them they are both analyzed the same.

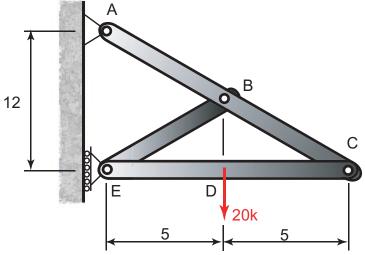


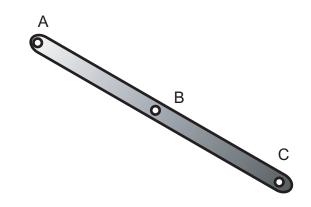
Compute the force supported by the pin at B. P= 5000 lb. Units: Lb, ft.



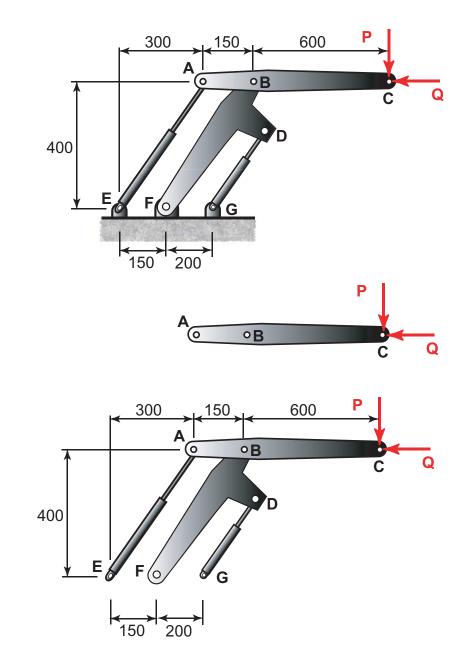


For the frame and loading shown, determine the components of all forces acting on member ABC. Units: Kips, ft.

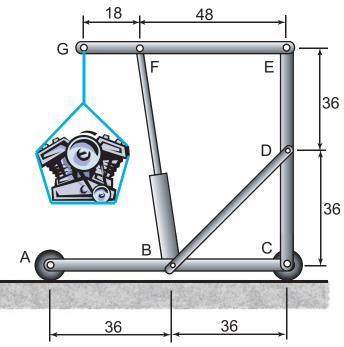


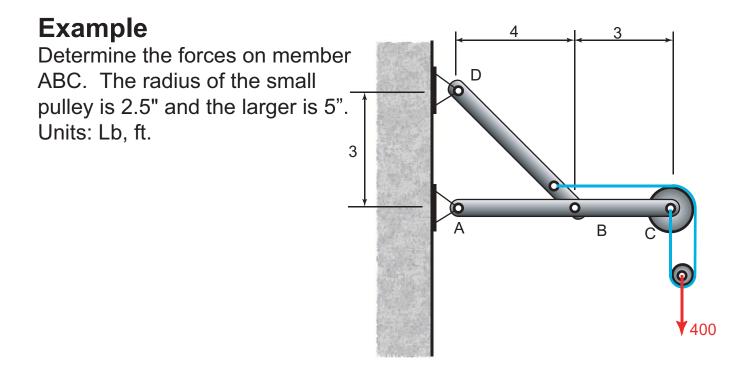


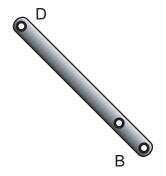
Knowing that in the position shown the cylinders are parallel, determine the force exerted by each cylinder when P= 190 N and Q= 95 N. Dimensions: N, mm.



Determine the forces on member EFG due to the 650 lb engine. Units: Lb, in.

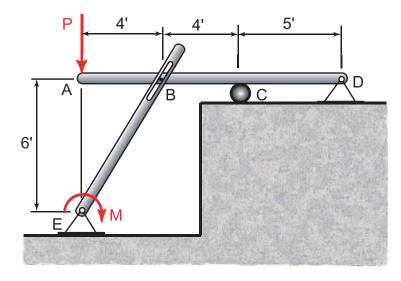






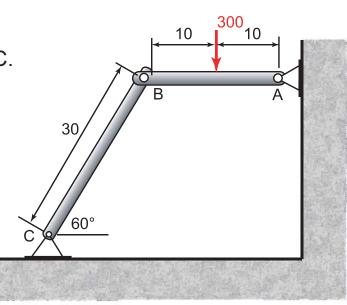


Determine the forces on member ABCD due to P= 500 lb and M= 700 ft-lb. Units: Lb, ft.

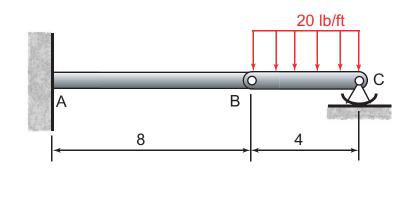




Determine the reactions at A and C. Units: Lb, in.

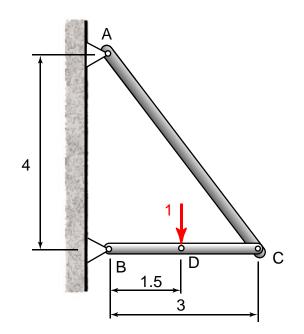


Determine the reactions at A and C. Units: Lb, ft.

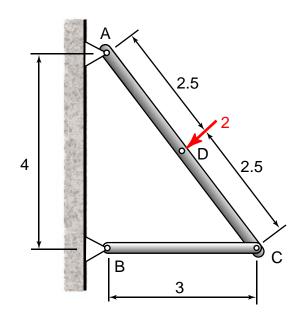




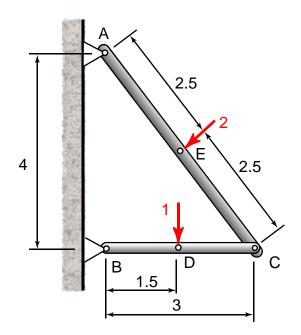
Determine the support reactions Units: Kips, ft.

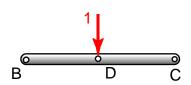


Example Determine the support reactions Units: Kips, ft.

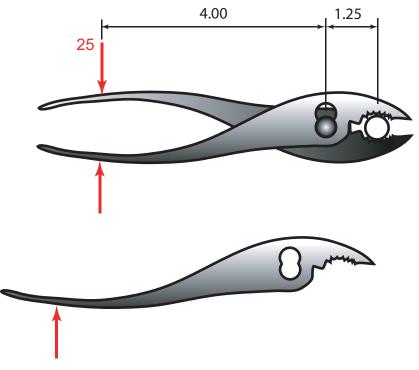


Determine the support reactions Units: Kips, ft.





Determine the clamping force exerted on the pipe. Units: Lb, in.



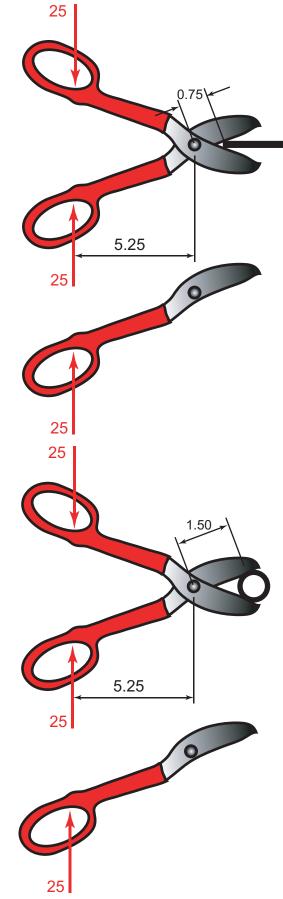


Example 300 350 550 25 Determine the cutting _ 13 force exerted on the rod. А Units: N, mm. **O**D 6 \$ 20 В 20 dE \mathbf{O} С 300 А



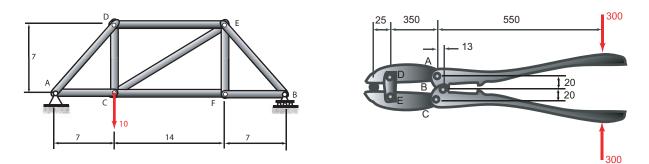


Determine the cutting force exerted on the a) thin sheet metal and b) the pipe. Ignore any friction between the blades and the object. Units: Lb, in.

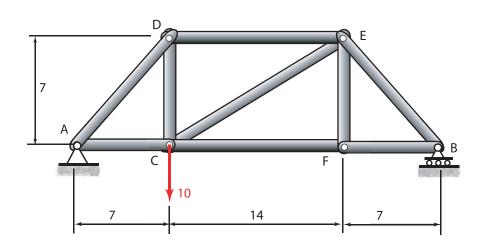


Summary

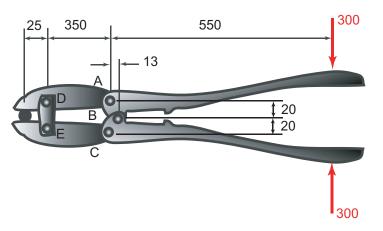
Two Force Members



Method of Joints and Method of Sections

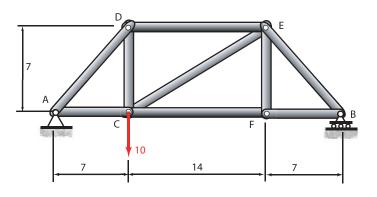


Frames and Machines (Multi-Force Members)

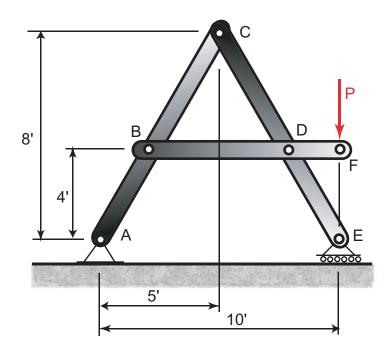


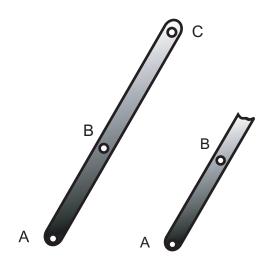
Chapter 7 Forces in Beams

Introduction Internal Forces in Members

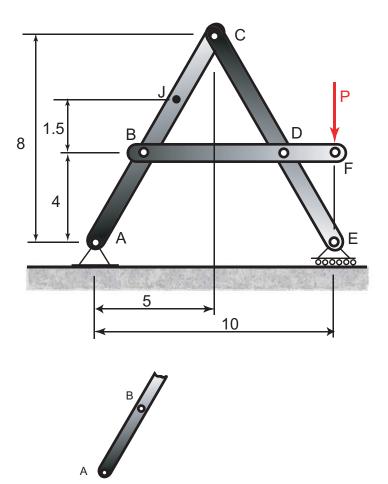




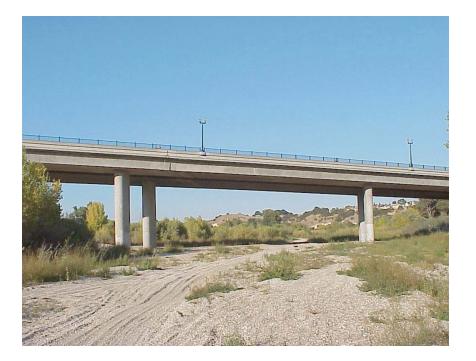




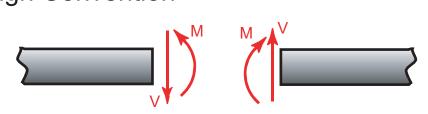
Determine the internal forces at point J. P= 5000 lb. Units: Lb, ft.



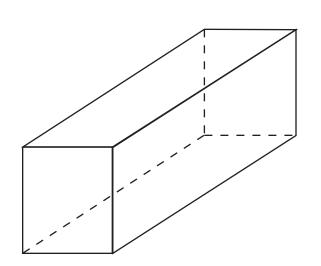
Shear and Bending Moment Diagrams

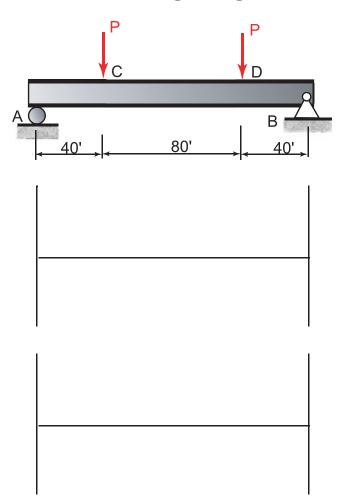


Sign Convention

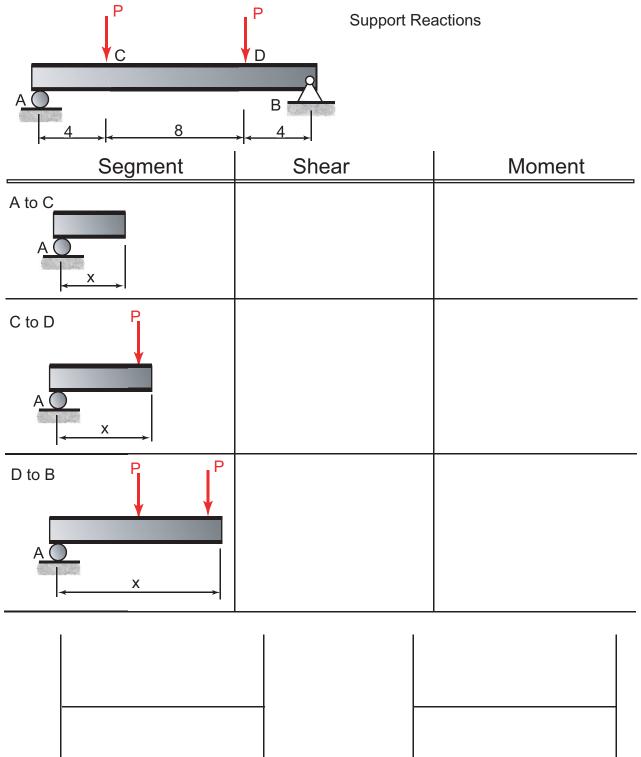


Why do we Need to Draw Shear and Bending Diagrams?

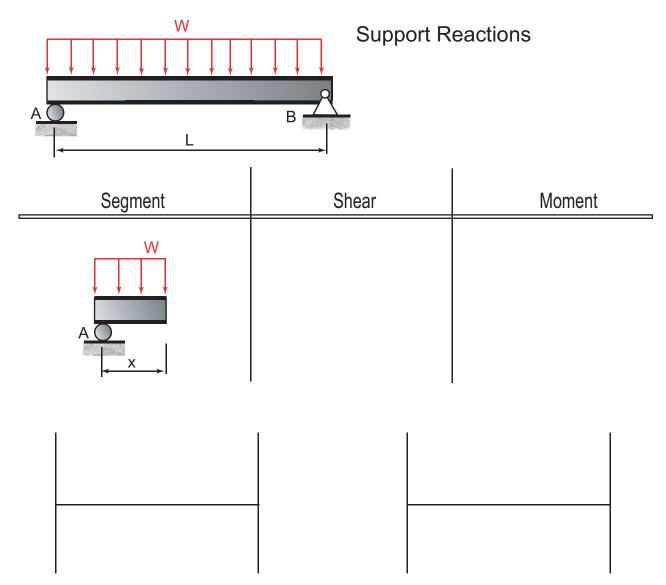




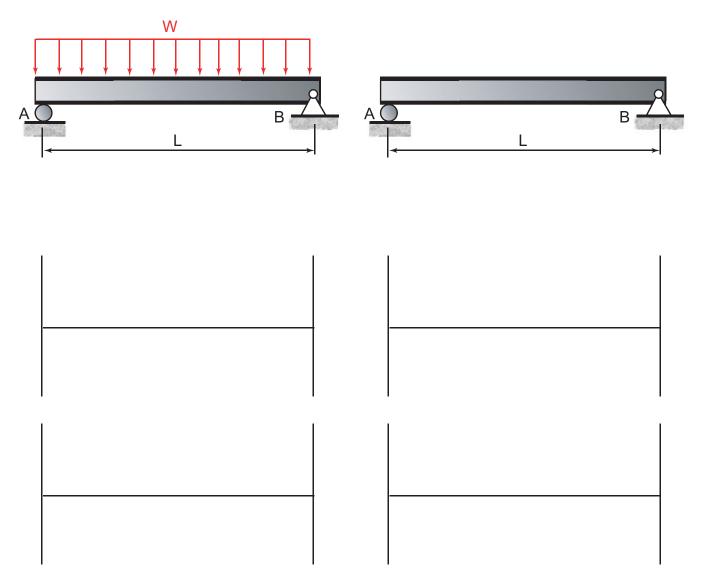
Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: Lb, ft.



Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes.

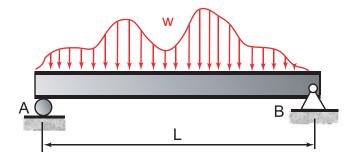


Caution:



When drawing FBDs, always use the original loading and not the equivalent.

Relations Among Load, Shear, and Bending Moment





$$\Delta V = -w\Delta x$$

$$\frac{dV}{dx} = -w$$

The change in shear is equal to the area under the load curve.

The slope of the shear diagram is equal to the value of the w load.

$$\frac{dM}{dx} = V$$

$$\Delta M = V \Delta x$$

The slope of the moment diagram is equal to the value of the shear.

The change in moment is equal to the area under the shear curve.

Observations about the Shape of Shear/ Moment Diagrams

Shear Diagrams:

-Are a plot of forces (note the units).

-Discontinuities occur at concentrated forces.

Moment Diagrams:

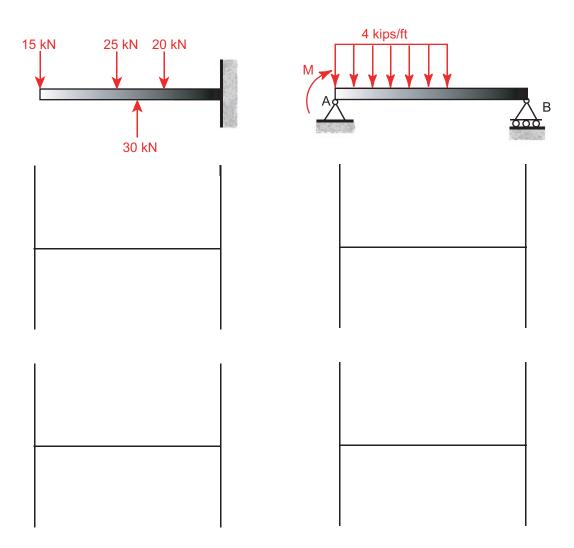
-Are a plot of moments (note the units).

-Discontinuities occur at concentrated moments.

Miscellaneous:

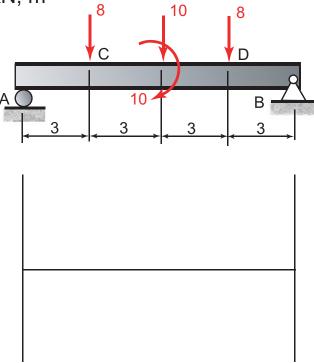
-Check your work by noting that you always start and end at zero.

-Always use the original loading and not the equivalent.



Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: kN, m

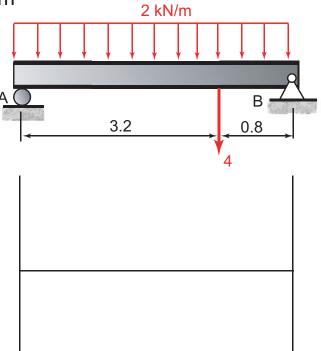
Support Reactions





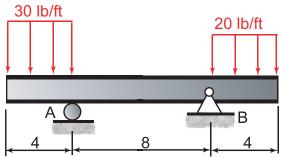
Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: kN, m

Support Reactions





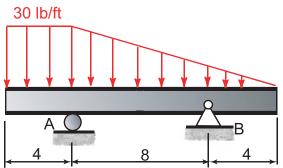
Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: Lb, ft.







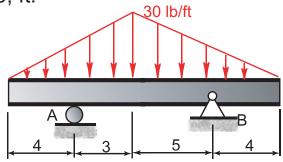
Sketch the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: Lb, ft.





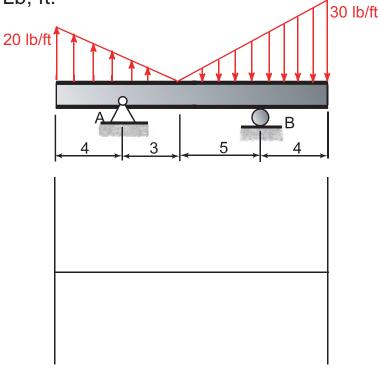


Sketch the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: Lb, ft.





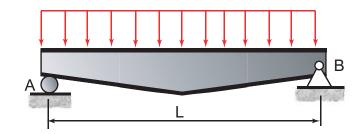
Sketch the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. Units: Lb, ft.

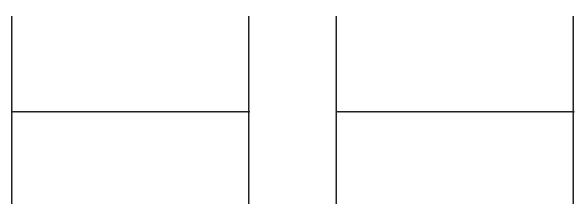




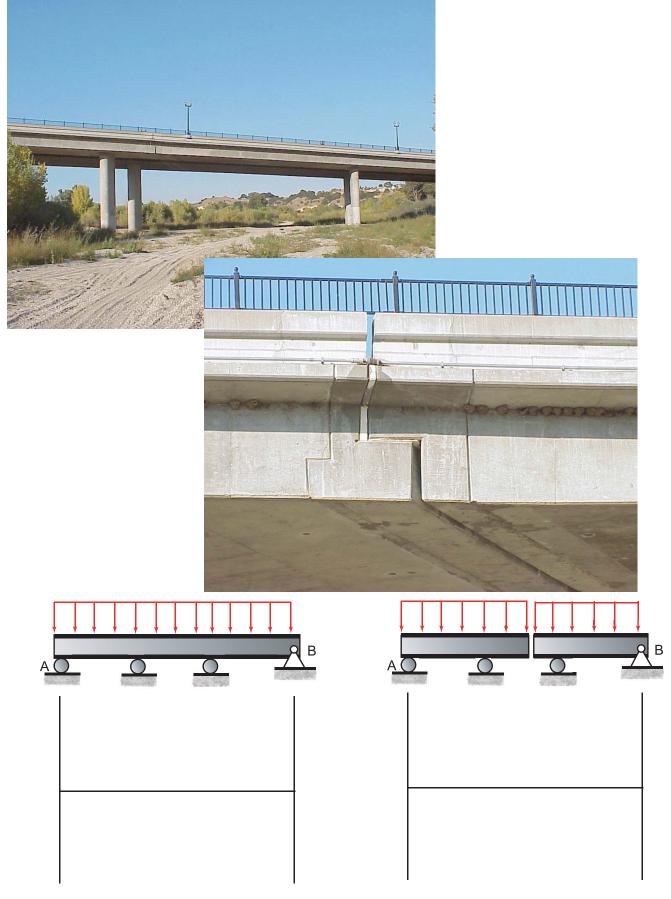
Here is an example of how the shape of the girder reflects the shear and bending diagrams.







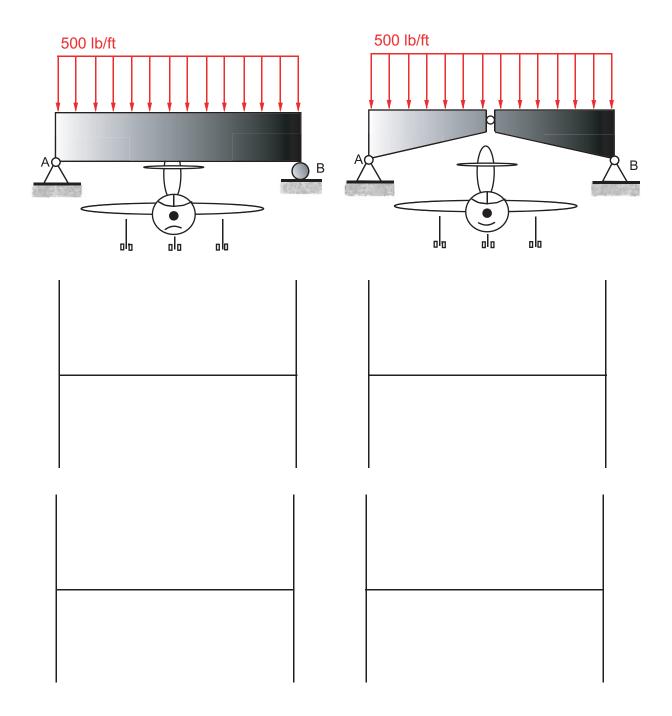
So why did they put that gap in the bridge?



Pins

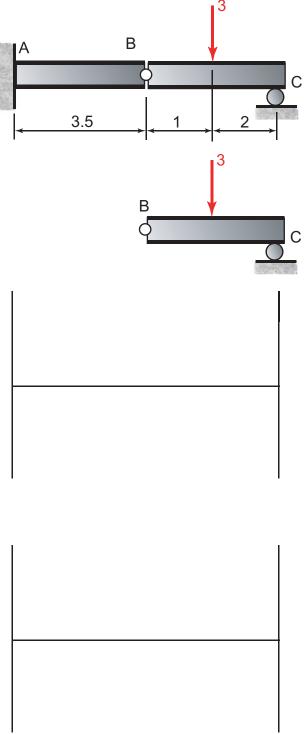


Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. The addition of the internal pin at the center of the beam allows additional head room because rather than the moment being a maximum in the center it becomes zero. This design is used at Wings Air West in SLO. Total span= 75 ft.

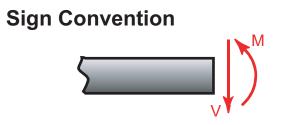


Draw the shear and bending-moment diagrams for the beam and loading shown. Label all points of change, maximums and minimums, and the axes. This example demonstrates that with the addition of an internal pin we get an additional equation, otherwise we would have too many unknowns.

Support Reactions



Summary



Shear Diagrams

Moment Diagrams

Observations about the Shape of Shear/ Moment Diagrams Shear Diagrams:

-Are a plot of forces (note the units).

-Discontinuities occur at concentrated forces.

Moment Diagrams:

-Are a plot of moments (note the units).

-Discontinuities occur at concentrated moments.

Miscellaneous:

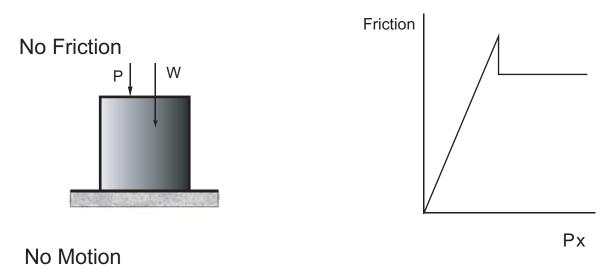
-Check your work by noting that you always start and end at zero. -Always use the original loading and not the equivalent.

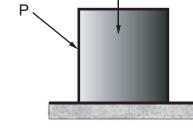
Chapter 8 Friction

Introduction

| Friction | | $F = {}_{s}N$ Coefficient of Static Friction for Dry Surfaces | |
|----------|----|--|---|
| | | Metal on metal Metal on wood Metal on stone Metal on leather Wood on wood Wood on leather Stone on stone | 0.15-0.60 0.20-0.60 0.30-0.70 0.30-0.60 0.25-0.50 0.25-0.50 0.40-0.70 |
| | Px | Earth on earth | 0.20-1.00 |

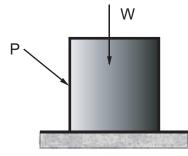
States of Friction



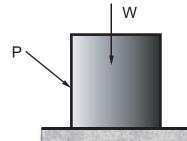


W

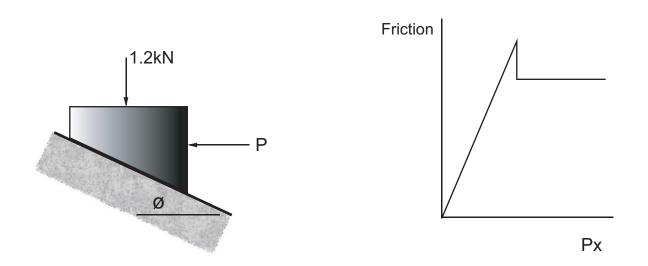
Motion Impending

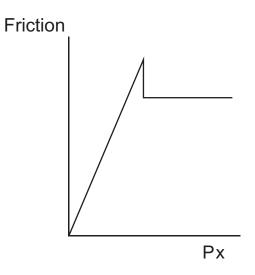


Motion

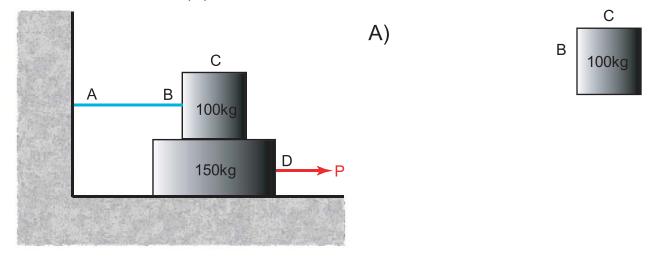


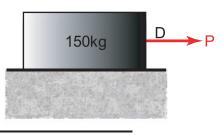
The static and dynamic coefficients of friction between the block and the incline are 0.35 and 0.25 respectively. Determine whether the block is in equilibrium and find the magnitude and direction of the friction force when $\emptyset = 25^{\circ}$ and P= 750N. Units: N.



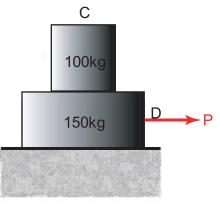


The static and dynamic coefficients of friction between all surfaces are 0.30 and 0.25 respectively. Determine the smallest force P required to start block D moving if (a) block C is restrained by cable AB as shown, (b) cable AB is removed. Units: N.

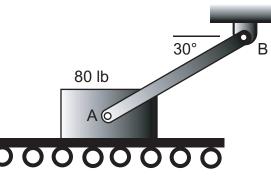


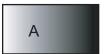






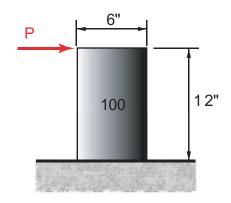
The 80 lb block is attached to link AB and rests on a moving belt. Knowing that the static and dynamic coefficients are 0.25 and 0.20, determine the magnitude of the horizontal force P which should be applied to the belt to maintain its motion (a) to the right, (b) to the left. Units: Lb.

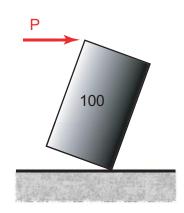




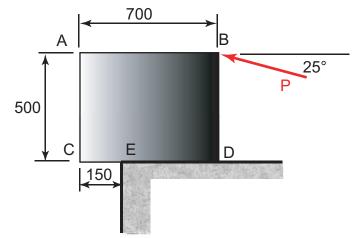
A

Determine whether the 100 lb block will tip before it has a chance to slide. The static coefficient is 0.30.

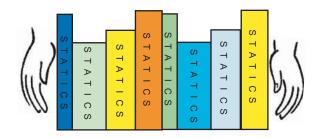




Knowing that the 100 kg crate starts to tip as it slides, determine (a) the magnitude of the force P, (b) the coefficient of kinetic friction. Units: N, mm.

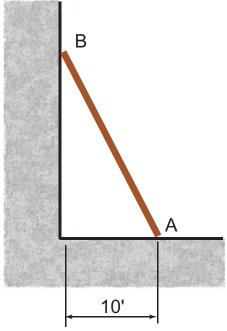


Calculate the force that each hand must apply to support (8) 1 lb books. The coefficient of static friction between the hands and the books is 0.50 and 0.35 between each book. Units: lb.

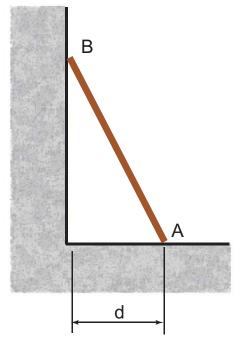


| STATIC | STATIC | STATICS | STATICS | STATIC | STATICS |
|--------|--------|---------|---------|--------|---------|
| C S | C S | S | S | I C S | C S |

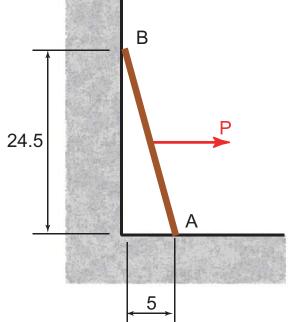
Determine the reactions at A and B. A is rough and B is smooth. The ladder has a length of 25 ft and weighs 25 lb. The coefficient of static friction is 0.3. Units: Lb, ft.



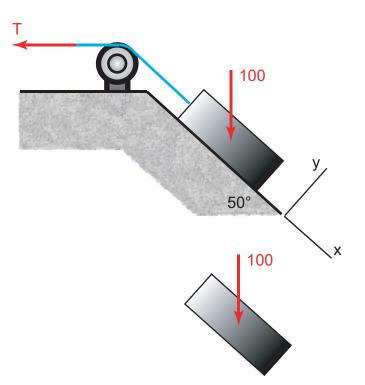
Determine the distance d at which the ladder will start to slide. A is rough and B is smooth. The ladder has a length of 25 ft and weighs 25 lb. The coefficient of static friction is 0.3. Units: Lb, ft.

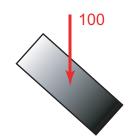


Determine the force P required to start the ladder to slide or tip. A is rough and B is smooth. P is applied to the middle of the ladder. The ladder has a length of 25 ft and weighs 25 lb. The coefficient of static friction is 0.3. Units: Lb, ft.

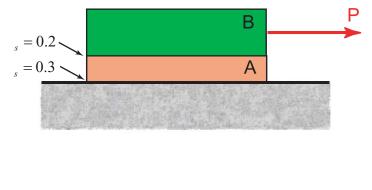


Find the range of T for which the block is in equilibrium. The coefficient of friction is 0.3. Units: N.





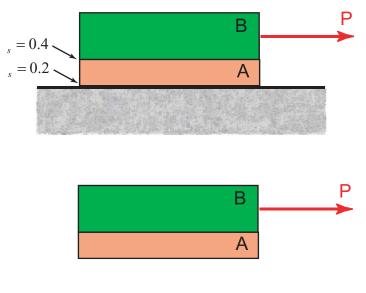
Determine the smallest force P required to move the blocks. Block A and B weigh 20 and 40 lb respectively. Units: Lb.





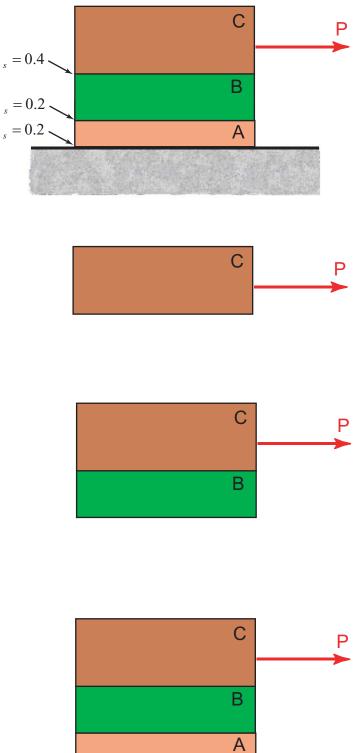


Determine the smallest force P required to move the blocks. Block A and B weigh 20 and 40 lb respectively. Units: Lb.

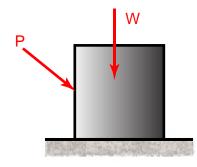




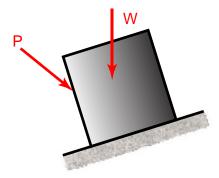
Determine the smallest force P required to move the blocks. Block A, B, C weigh 20, 40, and 60 Lb respectively. Units: Lb.



Angles of Friction



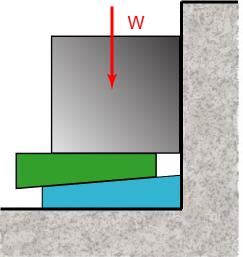
$$\tan\phi_s = \mu_s$$

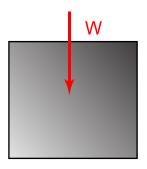


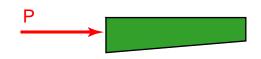
Wedges

Example

Find the force P required to move the block up. W= 500 lb, Static coefficient= 0.30, a 15° wedge. Units: Lb.

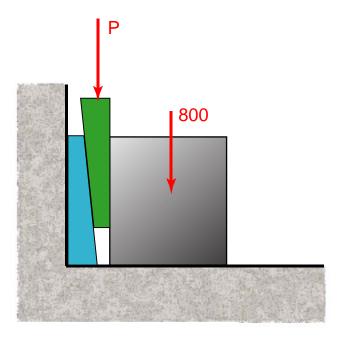


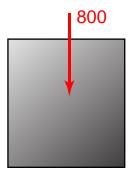


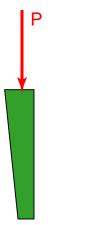


Example Find the force P required to move the block up. W= 500 lb, Static coefficient= 0.30, a 15° wedge. Units: Lb.

Find the minimum force P required to move the 800 N block. Static coefficient= 0.30, 15° wedges. Units: N.

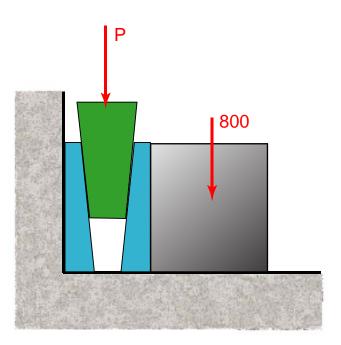


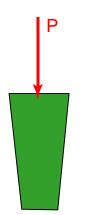




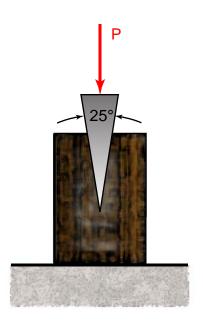
Find the minimum force P required to move the 800 N block. Static coefficient= 0.30, 15° wedges. Units: N.

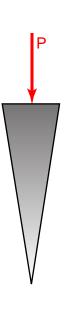
800



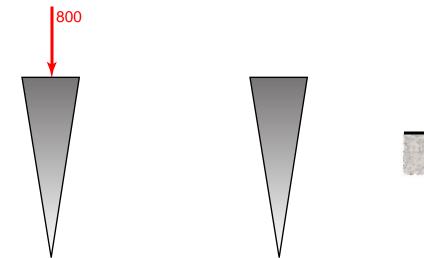


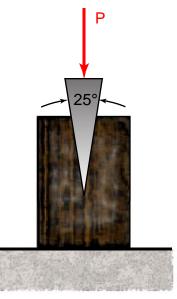
Knowing that it takes 800 N to insert the 25° wedge, find the forces exerted on the log. Kinetic coefficient= 0.26. Units: N.



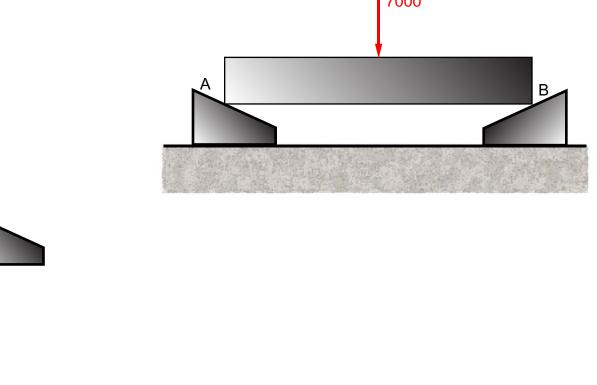


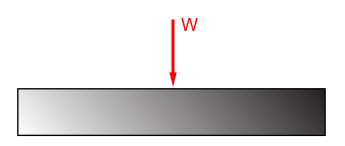
Knowing that it takes 800 N to insert the 25° wedge, will the wedge remain in place after P is removed? Static coefficient= 0.30. Units: N.



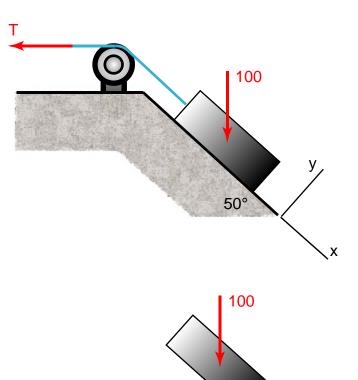


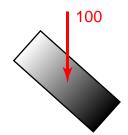
Wedge B is rough and the right end of the beam may be considered as fixed. Determine the horizontal force P which should be applied to the 15° wedge A to raise the left end of the beam. The beam is 7 m long. Static coefficient= 0.20. Units: N, m.



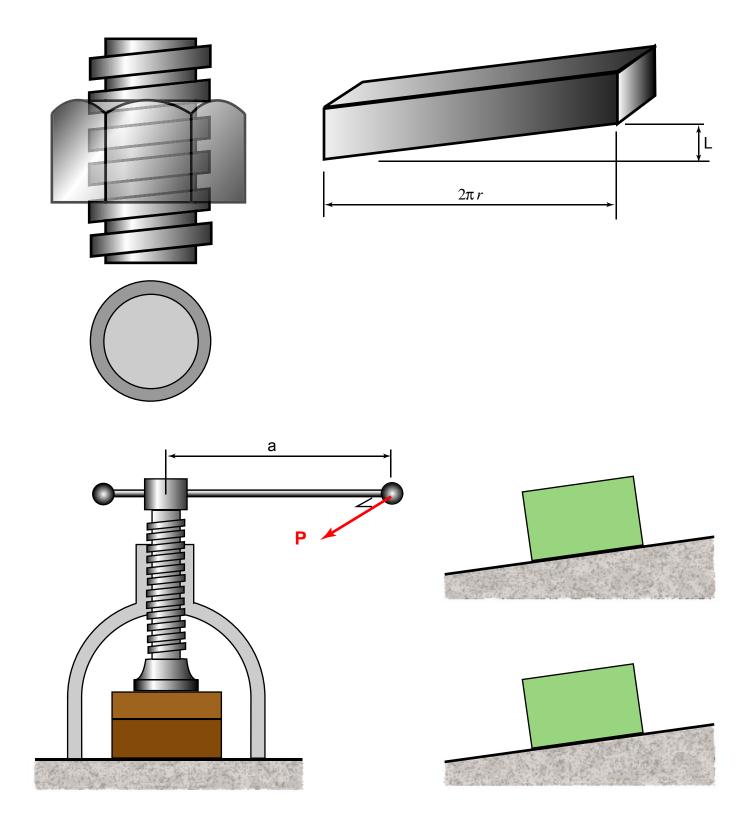


Find the range of T for which the block is in equilibrium. The static coefficient of friction is 0.3. Units: N.

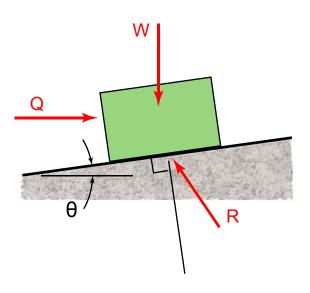




Square-Threaded Screws

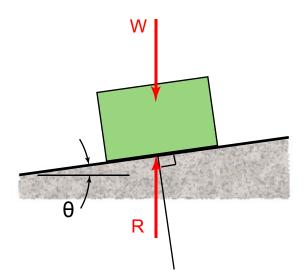


Tightening the Screw

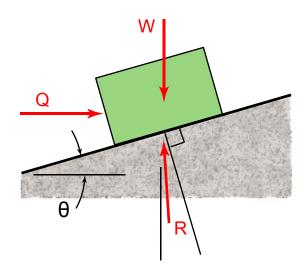


$$M = Wr \tan(\theta + \phi_s)$$

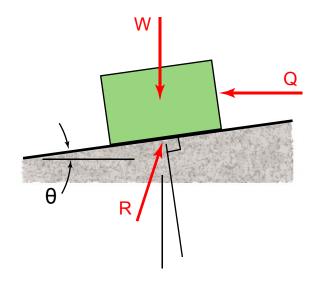
Self-Locking Screw



Loosening the Screw

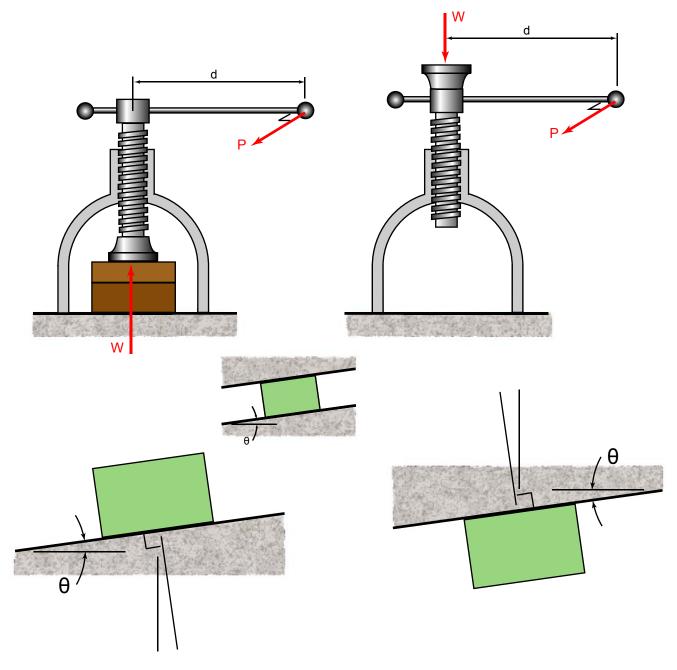


$$M = Wr \tan(\theta - \phi_s)$$



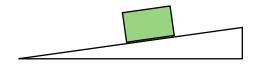
$$M = Wr \tan(\phi_s - \theta)$$

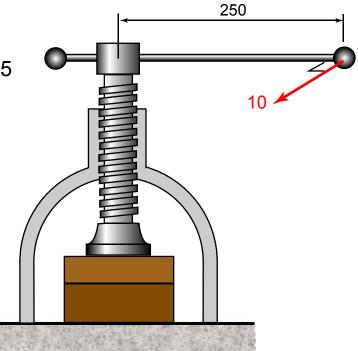
Analyze the amount of torque required to move the screws downward. The two systems are identical except for the placement of the load W.

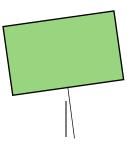


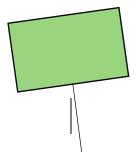
Common Sense: If you are turning it to where you know that it will be harder to turn, then use the equation on the left. If looser, then use the equation on the right.

The clamp has a single square thread of mean diameter equal to 15 mm with a pitch of 3 mm. If a force of 10 N is applied perpendicular to the handle, determine (a) the force exerted on the pieces of wood, (b) the force required to loosen the clamp. The static coefficient of friction is 0.3. Units: N, mm.

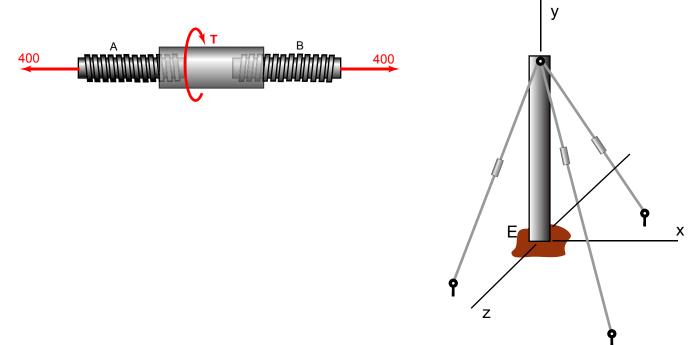




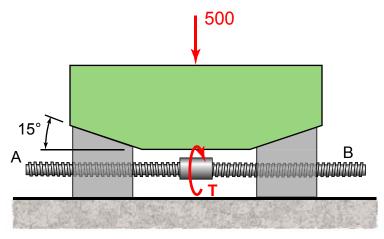


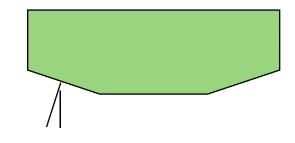


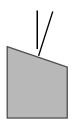
Rod A has a right-handed thread and rod B has a left-handed thread. Both rods are single-threaded with a mean radius of 0.3 in. and a pitch of 0.1 in. Determine the torque T that must be applied to the sleeve in order for the (a) rods to tighten, (b) rods to loosen. The static coefficient of friction is 0.30. Units: lb.



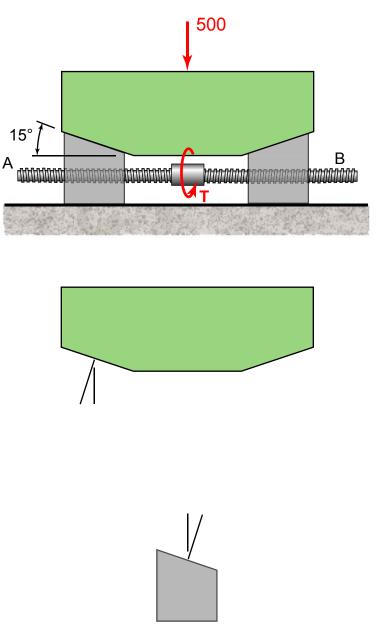
The two sliding 15° wedges support the 25 lb block above them and the 500 lb load. Rod A has a right-handed thread and rod B has a left-handed thread. Both rods are single-threaded with a mean radius of 0.3 in. and a pitch of 0.1 in. Determine the torque T that must be applied to the sleeve in order for the blocks to come together. The static coefficient of friction between all surfaces is 0.3. Units: lb.



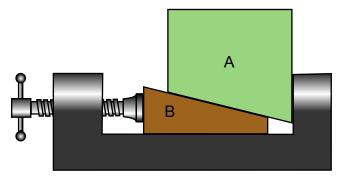


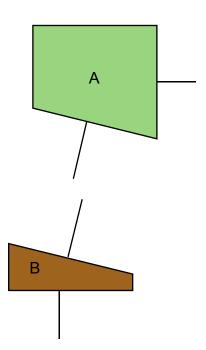


The two sliding 15° wedges support the 25 lb block above them and the 500 lb load. Rod A has a right-handed thread and rod B has a left-handed thread. Both rods are single-threaded with a mean radius of 0.3 in. and a pitch of 0.1 in. Determine the torque T that must be applied to the sleeve in order for the blocks to move apart. The static coefficient of friction between all surfaces is 0.3. Units: lb.

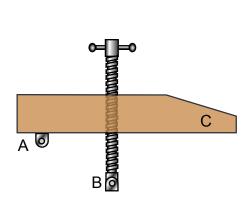


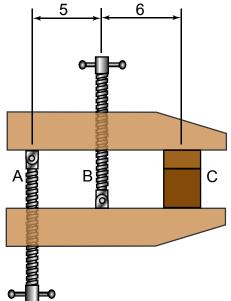
The clamp has a single square thread of mean diameter equal to 0.3 in. with a pitch of 0.1 in. The screw has a static coefficient of friction of 0.3, whereas it is 0.5 between the two blocks and the clamp. Ignore the weight of the 12° wedge B. Determine the torque required at the clamp's handle to lift the 200 lb block A.





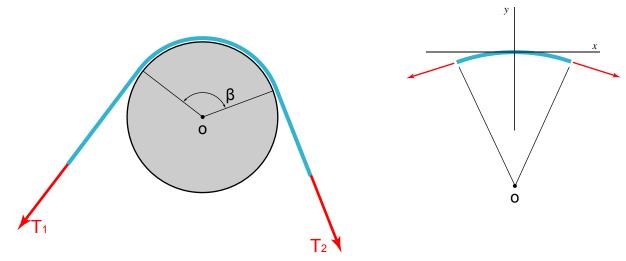
The wood clamp has a single square thread of mean diameter equal to 0.3 in. with a pitch of 0.1 in. The screws have a static coefficient of friction of 0.3. The clamp exerts a force of 200 lbs on the blocks at C. Determine the torque required to loosen the clamp if a) the torque is applied to screw A, b) the torque is applied to screw B. Units: Inches.





This page is intentionally left blank for future problems.

Belt Friction

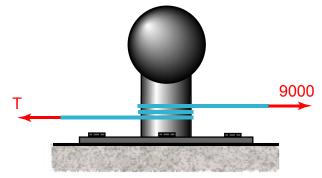


$$\sum F_x = 0: \qquad (T + \Delta T)\cos\frac{\Delta\theta}{2} - T\cos\frac{\Delta\theta}{2} - \mu_s\Delta N = 0$$

$$\sum F_y = 0: \qquad \Delta N - (T + \Delta T)\sin\frac{\Delta\theta}{2} - T\sin\frac{\Delta\theta}{2} = 0$$

$$\ln \frac{T_2}{T_1} = \mu_s \beta \qquad \qquad \frac{T_2}{T_1} = e^{\mu_s \beta}$$

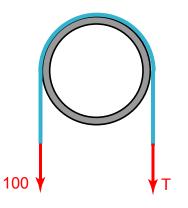
A ship tied up to the dock develops 9000 N in the rope that is wrapped two times around the bollard. Determine the minimum force required to keep the boat in place. The static coefficient is 0.3. Units: N.

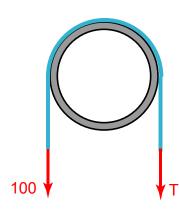


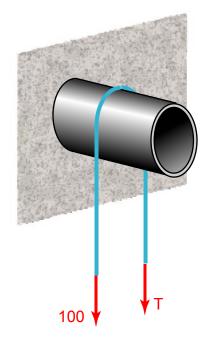
8-42

Example A rope is thro

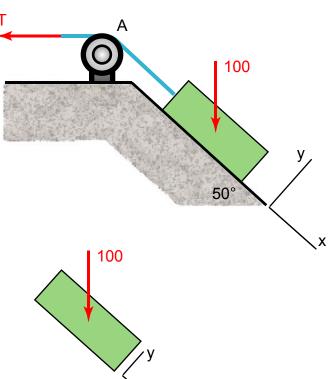
A rope is thrown around a 250 mm diameter pipe to raise a 100 N weight. What is the minimum tension T that must be applied to a) raise the weight, b) maintain this position? c) What effect will replacing the 250 mm pipe with a 350 mm pipe have? The static coefficient is 0.3. Units: N.

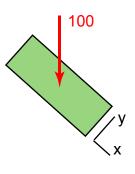




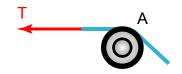


The pulley at A has rusted and is no longer able to rotate freely. Determine the (a) minimum force required to keep the block from sliding down the incline, (b) minimum force required to pull the block up the incline. The static coefficient is 0.3 between all surfaces. Units: N.

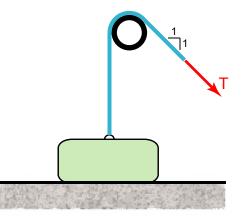


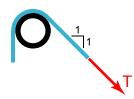


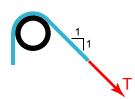




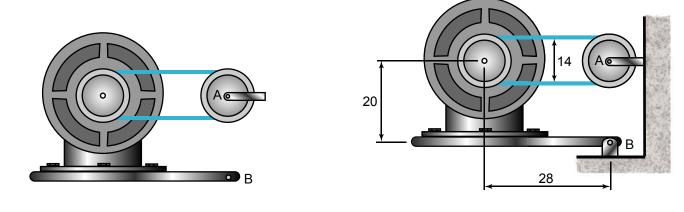
A rope is thrown around a pipe to raise a 100 N weight. a) What is the minimum tension T that must be applied to lift the weight? b) What is the minimum tension T that must be applied to then lower the weight? The static coefficient is 0.3. Units: N.

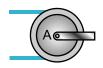






The 200 lb motor's weight is used to maintain tension in the flat belts. Determine the largest torque that can be transmitted to pulley A when the motor is rotating clockwise. The static coefficient is 0.3. Units: Lb, inches.





Determine the minimum weight of A to maintain equilibrium if a) pulley D is locked, b) pulley C is locked, c) pulleys C and D are locked. The static coefficient is 0.3. Units: Lb.

 $\frac{T_2}{T_1} = e^{\mu_s \beta}$

$$\frac{T_2}{T_1} = e^{\mu_s \beta}$$

a) D is locked:

b) C is locked:

$$\frac{T_2}{T_1} = e^{\mu_s \beta}$$

a) C and D are locked:

$$\frac{T_2}{T_1} = e^{\mu_s \beta}$$

D

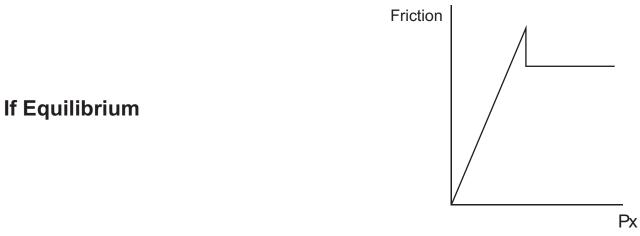
В

100

D

D

Summary

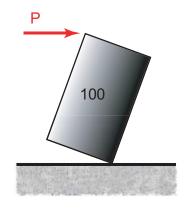


If Sliding

If Motion, but no Acceleration

If Tipping

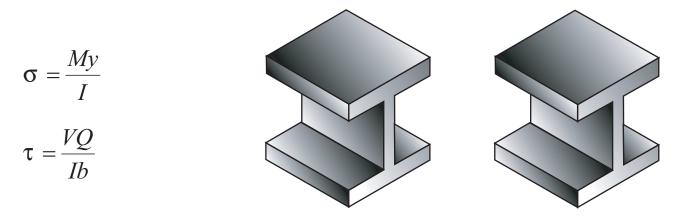
Wedges





Chapter 9 Moments of Inertia of Areas

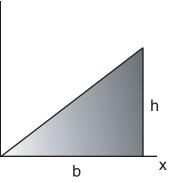
Introduction Second Moment, or Moment of Inertia, of an Area



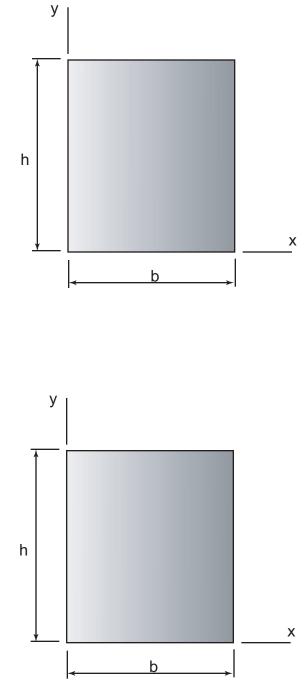
Determination of the Moment of Inertia of an Area by Integration

$$I_x = \int y^2 dA \qquad \qquad I_y = \int x^2 dA$$

Determine the moment of inertia about the x-axis of the area below. Use integration. y_{\parallel}



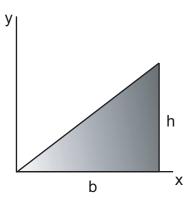
Determine the moment of inertia about the axes of the area below. Use integration.



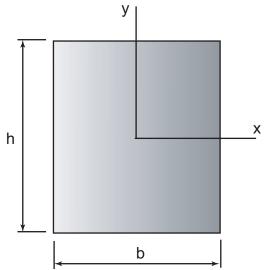
Alternative Solution

Determine the moment of inertia of the area below. Use integration.

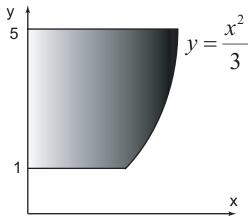


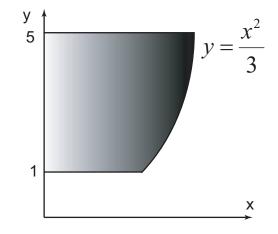


Determine the moment of inertia about the centroidal axes of the area below. Use integration.

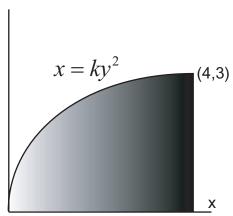


Determine the moment of inertia about the y-axis of the area below. Use integration. $y \uparrow$



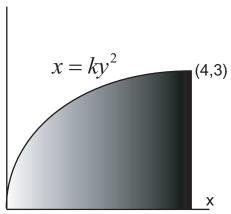


Determine the moment of inertia about the x-axis of the area below. Use integration. y_{\parallel}



Determine the moment of inertia about the x-axis of the area below. Use integration. y_{\parallel}

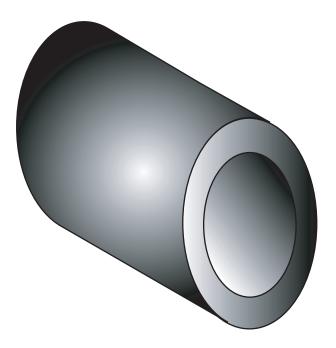
Alternative Solution



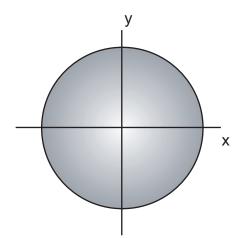
Polar Moment of Inertia

$$\tau = \frac{Tr}{J_o}$$

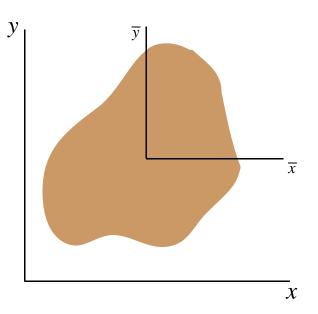
$$J_o = I_p = \int \rho^2 dA = \int (x^2 + y^2) dA$$



Determine the polar moment of inertia of the area below. Use integration.



Parallel-Axis Theorem



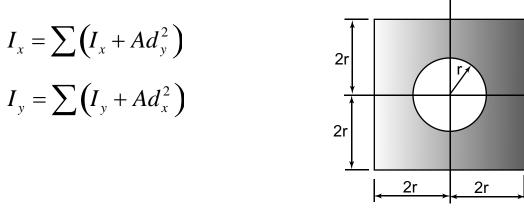
$$I_{x} = \sum \left(\overline{I}_{x} + Ad_{y}^{2}\right)$$
$$I_{y} = \sum \left(\overline{I}_{y} + Ad_{x}^{2}\right)$$

Moments of Inertia of Composite Areas

| Shape | | |
|----------------|---|---|
| Rectangle | $\begin{array}{c c} y & y' \\ \hline \\ h \\ \hline \\ \hline \\ \hline \\ h \\ \hline \\ \hline \\ \hline \\ \hline$ | $\overline{I}_{x'} = \frac{1}{12}bh^3 \qquad \overline{I}_{y'} = \frac{1}{12}hb^3$ $I_x = \frac{1}{3}bh^3 \qquad I_y = \frac{1}{3}hb^3$ $J_c = \frac{1}{12}bh(b^2 + h^2)$ |
| Triangle | y' x' h h | $\overline{I}_{x'} = \frac{1}{36}bh^3$ $I_x = \frac{1}{12}bh^3$ |
| Circle | y r x | $\overline{I}_{x} = \overline{I}_{y} = \frac{1}{4}\pi r^{4}$ $J_{o} = \frac{1}{2}\pi r^{4}$ |
| Semicircle | | $I_x = I_y = \frac{1}{8}\pi r^4$ $J_o = \frac{1}{4}\pi r^4$ |
| Quarter circle | | $I_x = I_y = \frac{1}{16}\pi r^4$ $J_o = \frac{1}{8}\pi r^4$ |

Moment of Inertia of Composite Areas

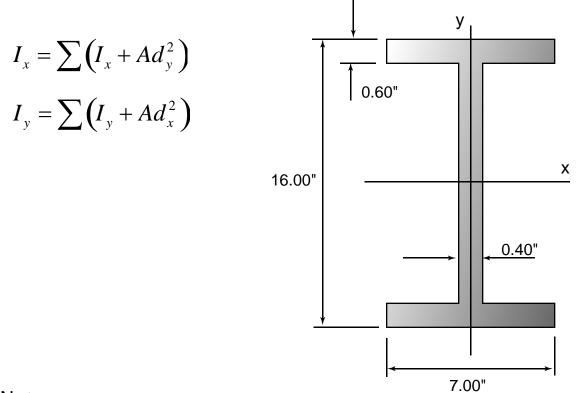
Determine the moment of inertia about the centrodial axes of the area below.



| Part | I | Area | d | Ad^2 |
|------|---|------|---|--------|
| | | | | |
| | | | | |
| | | | | |
| | | | | |

Х

Determine the moment of inertia about the centrodial axes of the area below. Units: in.

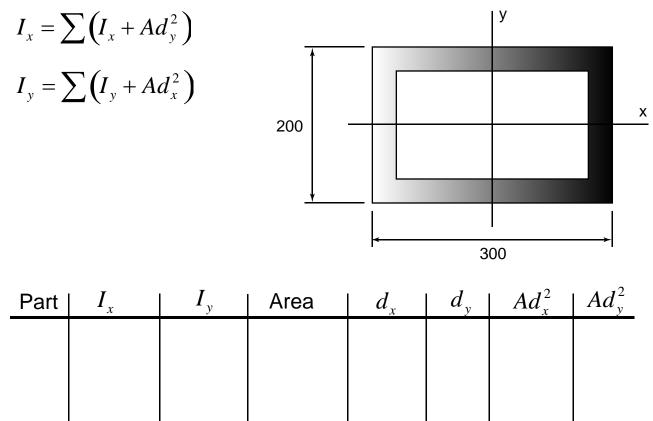


Note:

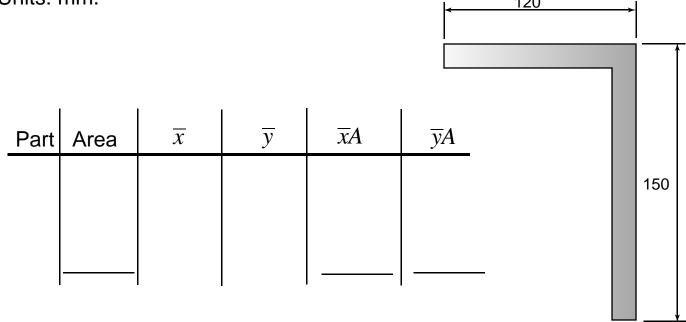
d is the distance between the property of the part to the new axis. b is always parallel to the axis you want to find I about.

| Part | | d | Area | Ad^2 |
|------|--|---|------|--------|
| | | | | |
| | | | | |
| | | | | |
| | | | | |
| | | | | |

Determine the moment of inertia about the centrodial axes of the area below. Uniform thickness t= 20 mm. Units: mm.



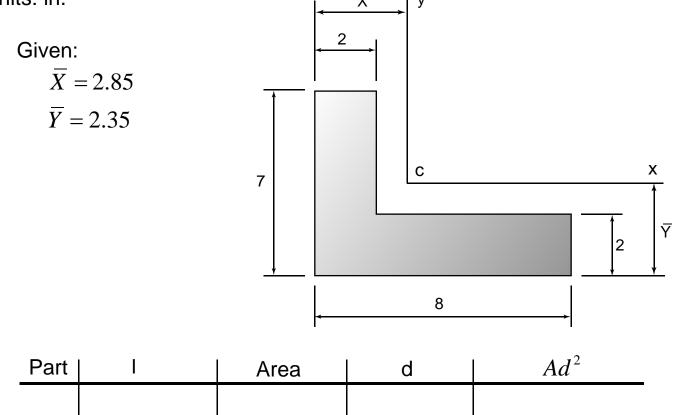
Determine the moment of inertia about the centrodial axes of the area below. The section has a uniform width of 20 mm. Units: mm.



| Part | I_x | I_y | Area | d_x | d_y | Ad_x^2 | Ad_y^2 |
|------|-------|-------|------|-------|-------|----------|----------|
| | | | | | | | |
| | | | | | | | |
| | | | | | | | |
| | | | l | | | | |

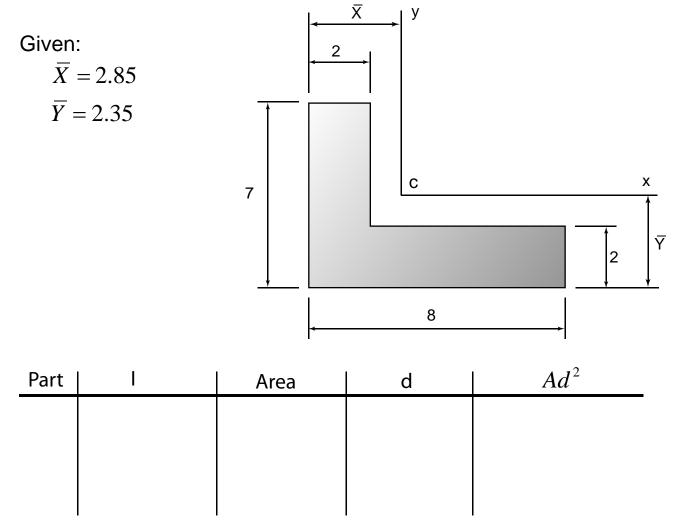
 $I_{x} = \sum \left(I_{x} + Ad_{y}^{2} \right)$ $I_{y} = \sum \left(I_{y} + Ad_{x}^{2} \right)$

Determine the moment of inertia about the x axis of the area below. Units: in. $\overline{x} + y$



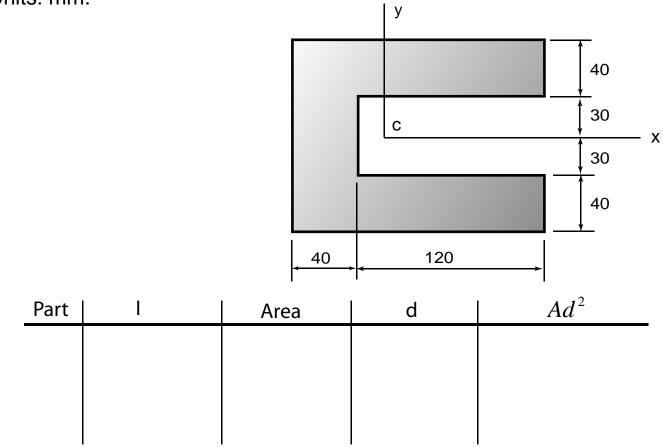
| $I_x = \sum \left(I_x + Ad_y^2 \right)$ | |
|--|--|

Determine the moment of inertia about the y axis of the area below. Units: in.



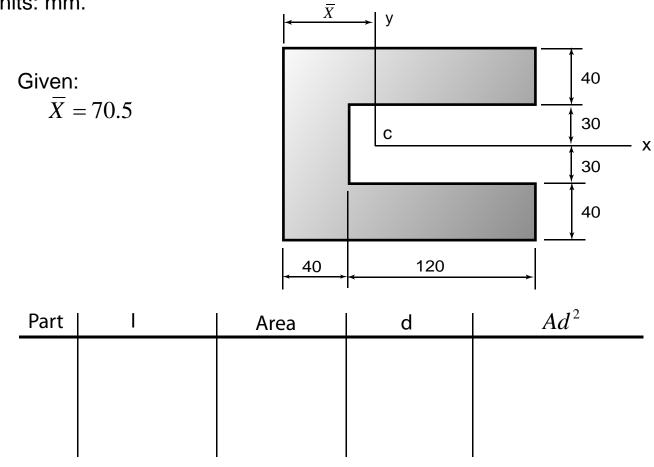
$$I_{y} = \sum \left(I_{y} + Ad_{x}^{2} \right)$$

Determine the moment of inertia about the x axis of the area below. Units: mm.



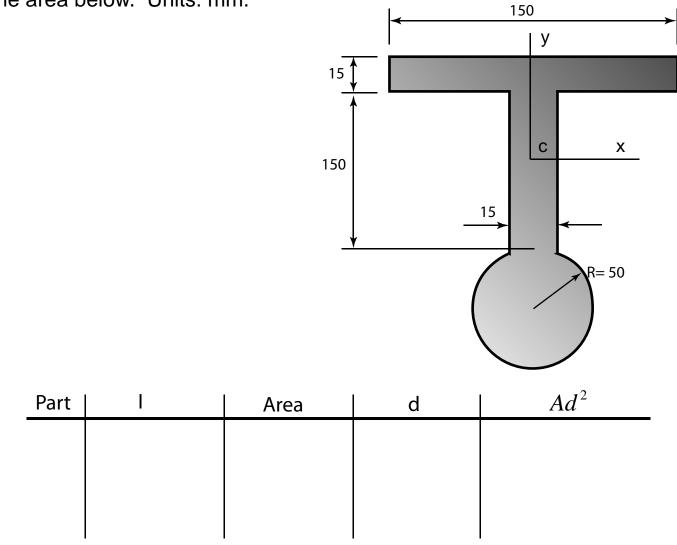
$$I_x = \sum \left(I_x + Ad_y^2 \right)$$

Determine the moment of inertia about the y-axis of the area below. Units: mm. \overline{x}



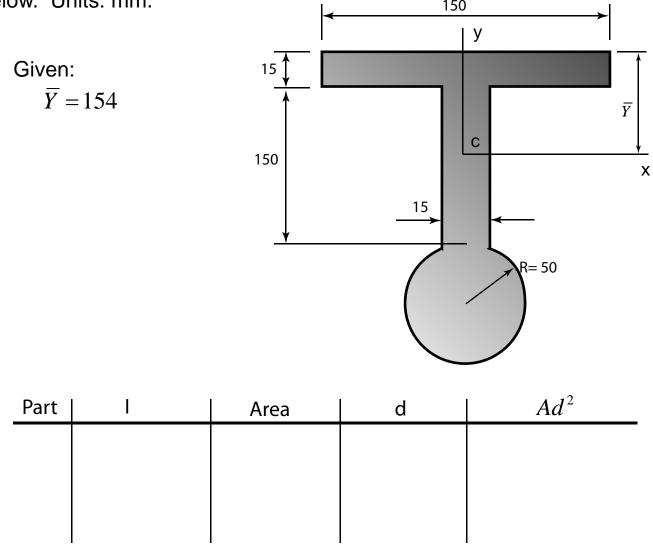
$$I_{y} = \sum \left(I_{y} + Ad_{x}^{2} \right)$$

Determine the moment of inertia about the centroidal y axis of the area below. Units: mm.



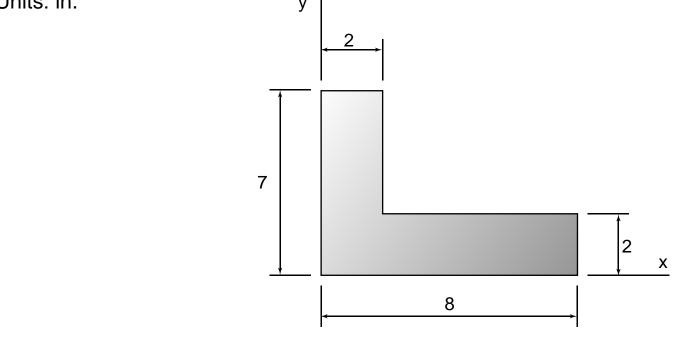
$$I_{y} = \sum \left(I_{y} + Ad_{x}^{2} \right)$$

Determine the moment of inertia about the centroidal x axis of the area below. Units: mm.



$$I_x = \sum \left(I_x + Ad_y^2 \right)$$

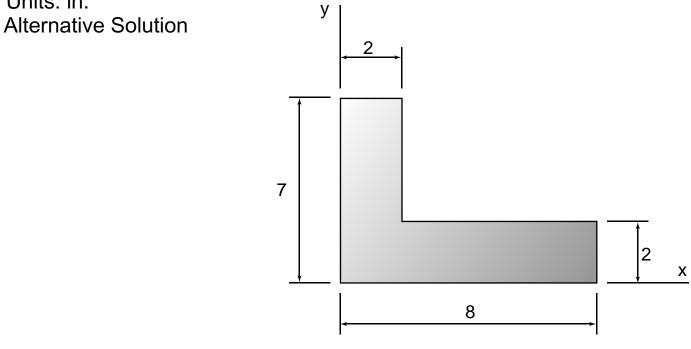
Determine the moment of inertia about the x axis of the area below. Units: in. y



| Part | Area | d | Ad^2 |
|------|------|---|--------|
| | | | |
| | | | |
| | | | |
| | | | |

$$I_x = \sum \left(I_x + Ad_y^2 \right)$$

Determine the moment of inertia about the x axis of the area below. Units: in. v_{1}

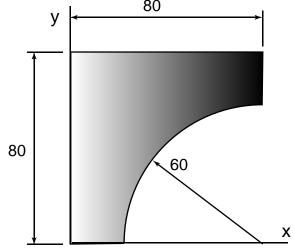


| Part | | Area | d | Ad^2 |
|------|--|------|---|--------|
| | | | | |
| | | | | |
| | | | | |
| | | | | |

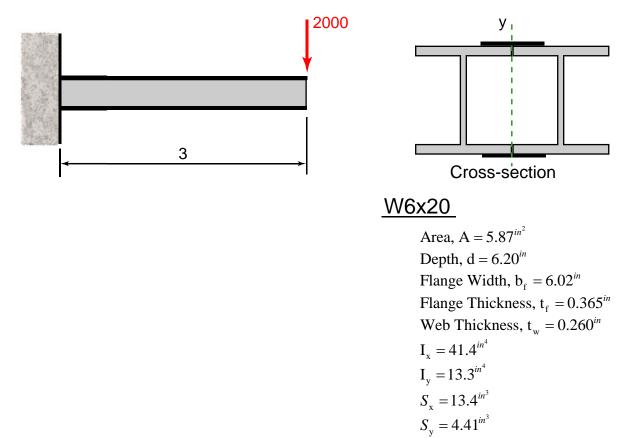
$$I_x = \sum \left(I_x + Ad_y^2 \right)$$

Determine the moment of inertia about the x axis of the area below. Units: mm.

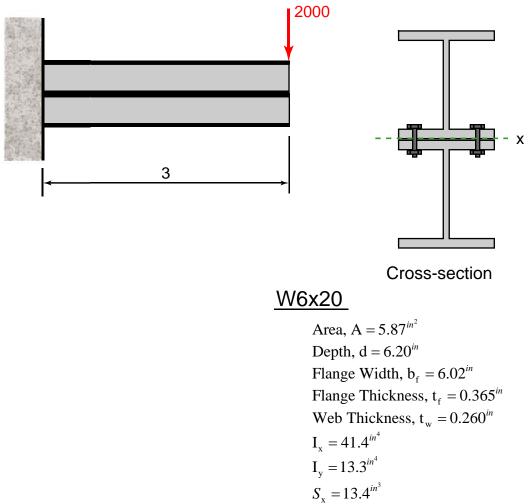
$$I_x = \sum \left(I_x + Ad_y^2 \right)$$



The two beams are connected by a thin rigid plate on the top and bottom side of the flanges. Determine the moment of inertia about the y axis for the W6x20 beam. Units: lb, ft

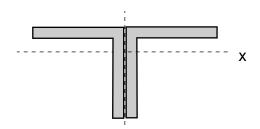


The two beams are connected by bolts through the flanges. Determine the moment of inertia about the x axis for the W6x20 beam. Units: lb, ft



$$S_{y} = 4.41^{in}$$

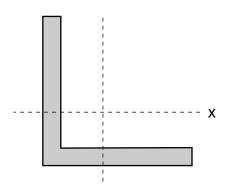
Two L76x76x12.7 angle sections are welded back-to-back. Determine the moment of inertia about the centroidal x axis.

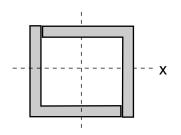


L76x76x12.7

Area, A = 1770^{mm^2} d = b = 76^{mm} $\overline{x} = \overline{y} = 23.6^{mm}$ Thickness, t = 12.7^{mm} $I_x = I_y = 0.915 \times 10^{6mm^4}$ $r_z = 14.8^{mm}$

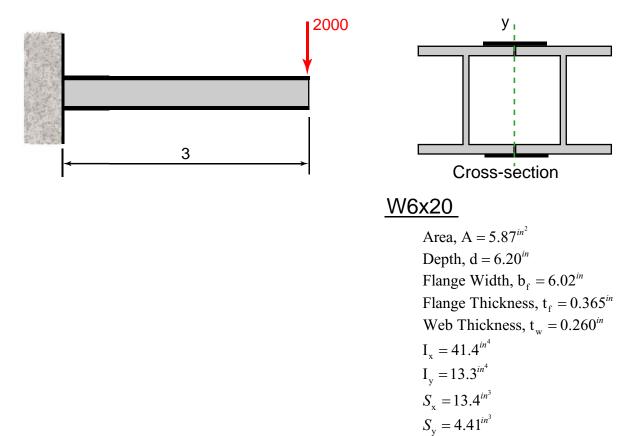
Two L76x76x12.7 angle sections are welded together as shown. Determine the moment of inertia about the centroidal x axis.



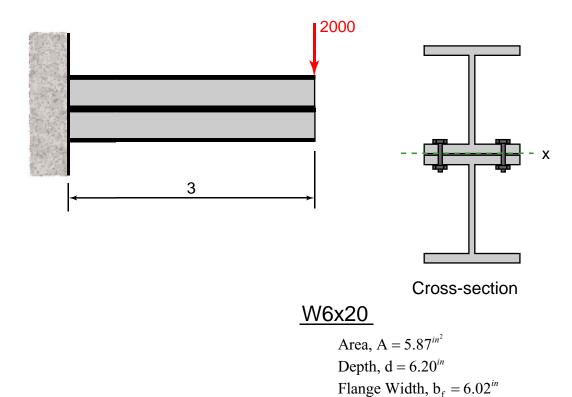


<u>L76x76x12.7</u> Area, A = 1770^{*nun*²} d = b = 76^{*mm*} $\overline{x} = \overline{y} = 23.6^{$ *mm* $}$ Thickness, t = 12.7^{*mm*} $I_x = I_y = 0.915x10^{6$ *mm* 4 $r_z = 14.8^{$ *mm* $}$

The two beams are connected by a thin rigid plate on the top and bottom side of the flanges. Determine the radius of gyration about the y axis for the W6x20 beam. Units: ft



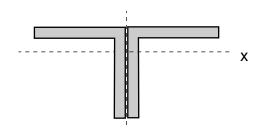
The two beams are connected by bolts through the flanges. Determine the radius of gyration about the x axis for the W6x20 beam. Units: lb, ft



Flange Thickness, $t_f = 0.365^{in}$ Web Thickness, $t_w = 0.260^{in}$

 $I_{x} = 41.4^{in^{4}}$ $I_{y} = 13.3^{in^{4}}$ $S_{x} = 13.4^{in^{3}}$ $S_{y} = 4.41^{in^{3}}$

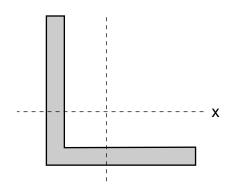
Two L76x76x12.7 angle sections are welded back-to-back. Determine the radius of gyration about the centroidal x axis.

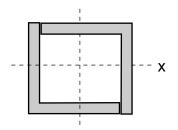


L76x76x12.7

Area, A = 1770^{mm^2} d = b = 76^{mm} $\overline{x} = \overline{y} = 23.6^{mm}$ Thickness, t = 12.7^{mm} $I_x = I_y = 0.915x10^{6mm^4}$ $r_z = 14.8^{mm}$

Two L76x76x12.7 angle sections are welded together as shown. Determine the radius of gyration about the centroidal x axis.





<u>L76x76x12.7</u> Area, A = 1770^{mm²} $d = b = 76^{mm}$ $\overline{x} = \overline{y} = 23.6^{mm}$ Thickness, t = 12.7^{mm} $I_x = I_y = 0.915x10^{6mm^4}$ $r_z = 14.8^{mm}$

Determine the radius of gyration about the x axis of the area below. Units: mm.

